



**Synchronous DRAM Module 128Mbyte (16Mx64bit), SMM ,16Mx8,
4Banks, 4K Ref. 3.3V** **Part No. HSD16M64F8K**

GENERAL DESCRIPTION

The HSD16M64F8K is a 16M x 64 bit Synchronous Dynamic RAM high-density memory module. The module consists of eight CMOS 16M x 8 bit with 4banks Synchronous DRAMs in TSOP-II 400mil packages and 2K EEPROM in 8-pin TSSOP package on a 120-pin glass-epoxy. Three 0.1uF decoupling capacitors are mounted on the printed circuit board in parallel for each SDRAM. The HSD16M64F8K is a SMM(Stackable Memory Module type) .Synchronous design allows precise cycle control with the use of system clock. I/O transactions are possible on every clock cycle. Range of operating frequencies, programmable latencies allows the same device to be useful for a variety of high bandwidth, high performance memory system applications All module components may be powered from a single 3.3V DC power supply and all inputs and outputs are LVTTTL-compatible.

FEATURES

- Part Identification
 - HSD16M64F8K : 100MHz (CL=2 & CL=3)
- Burst mode operation
- Auto & self refresh capability (4096 Cycles/64ms)
- LVTTTL compatible inputs and outputs
- Single 3.3V \pm 0.3V power supply
- MRS cycle with address key programs
 - Latency (Access from column address)
 - Burst length (1, 2, 4, 8 & Full page)
 - Data scramble (Sequential & Interleave)
- All inputs are sampled at the positive going edge of the system clock
- The used device is 4M x 8bit x 4Banks SDRAM

PIN ASSIGNMENT

| P1 | | | | | | P2 | | | | | |
|-----|--------|-----|--------|-----|--------|-----|--------|-----|--------|-----|--------|
| PIN | Symbol | PIN | Symbol | PIN | Symbol | PIN | Symbol | PIN | Symbol | PIN | Symbol |
| 1 | Vcc | 29 | NC | 57 | /RAS | 1 | Vss | 29 | A3 | 57 | A6 |
| 2 | DQ32 | 30 | Vcc | 58 | /CS0 | 2 | DQ16 | 30 | Vss | 58 | A5 |
| 3 | DQ33 | 31 | Vss | 59 | NC | 3 | DQ17 | 31 | Vcc | 59 | A4 |
| 4 | DQ34 | 32 | DQ0 | 60 | Vss | 4 | DQ18 | 32 | DQ48 | 60 | Vcc |
| 5 | DQ35 | 33 | DQ1 | | | 5 | DQ19 | 33 | DQ49 | | |
| 6 | DQ36 | 34 | DQ2 | | | 6 | DQ20 | 34 | DQ50 | | |
| 7 | DQ37 | 35 | DQ3 | | | 7 | DQ21 | 35 | DQ51 | | |
| 8 | DQ38 | 36 | DQ4 | | | 8 | DQ22 | 36 | DQ52 | | |
| 9 | DQ39 | 37 | DQ5 | | | 9 | DQ23 | 37 | DQ53 | | |
| 10 | Vcc | 38 | DQ6 | | | 10 | Vss | 38 | DQ54 | | |
| 11 | DQ40 | 39 | DQ7 | | | 11 | DQ24 | 39 | DQ55 | | |
| 12 | DQ41 | 40 | Vss | | | 12 | DQ25 | 40 | Vcc | | |
| 13 | DQ42 | 41 | DQ8 | | | 13 | DQ26 | 41 | DQ56 | | |
| 14 | DQ43 | 42 | DQ9 | | | 14 | DQ27 | 42 | DQ57 | | |
| 15 | DQ44 | 43 | DQ10 | | | 15 | DQ28 | 43 | DQ58 | | |
| 16 | DQ45 | 44 | DQ11 | | | 16 | DQ29 | 44 | DQ59 | | |
| 17 | DQ46 | 45 | DQ12 | | | 17 | DQ30 | 45 | DQ60 | | |
| 18 | DQ47 | 46 | DQ13 | | | 18 | DQ31 | 46 | DQ61 | | |
| 19 | Vcc | 47 | DQ14 | | | 19 | Vss | 47 | DQ62 | | |
| 20 | DQM4 | 48 | DQ15 | | | 20 | DQM2 | 48 | DQ63 | | |
| 21 | DQM5 | 49 | Vss | | | 21 | DQM3 | 49 | Vcc | | |
| 22 | REGE | 50 | DQM0 | | | 22 | NC | 50 | DQM6 | | |
| 23 | CKE0 | 51 | DQM1 | | | 23 | BA0 | 51 | DQM7 | | |
| 24 | NC | 52 | /WE | | | 24 | BA1 | 52 | A12 | | |
| 25 | Vcc | 53 | CLK0 | | | 25 | A10 | 53 | A11 | | |
| 26 | SDA | 54 | CLK1 | | | 26 | A0 | 54 | A9 | | |
| 27 | SCL | 55 | Vss | | | 27 | A1 | 55 | A8 | | |
| 28 | /CS2 | 56 | /CAS | | | 28 | A2 | 56 | A7 | | |

* Pin Names

A0~A11: Address input (Multiplexed)

DQ0~DQ63: Data input/output

CKE0: Clock enable input

/RAS: Row address strobe

/CAS: Column address strobe

DQM0~7: DQM

REGE: Register enable

SDA: Serial data I/O

NC: No connection

BA0~BA1: Select bank

CLK0: Clock input

/CS0, /CS2: Chip select input

/WE: Write enable

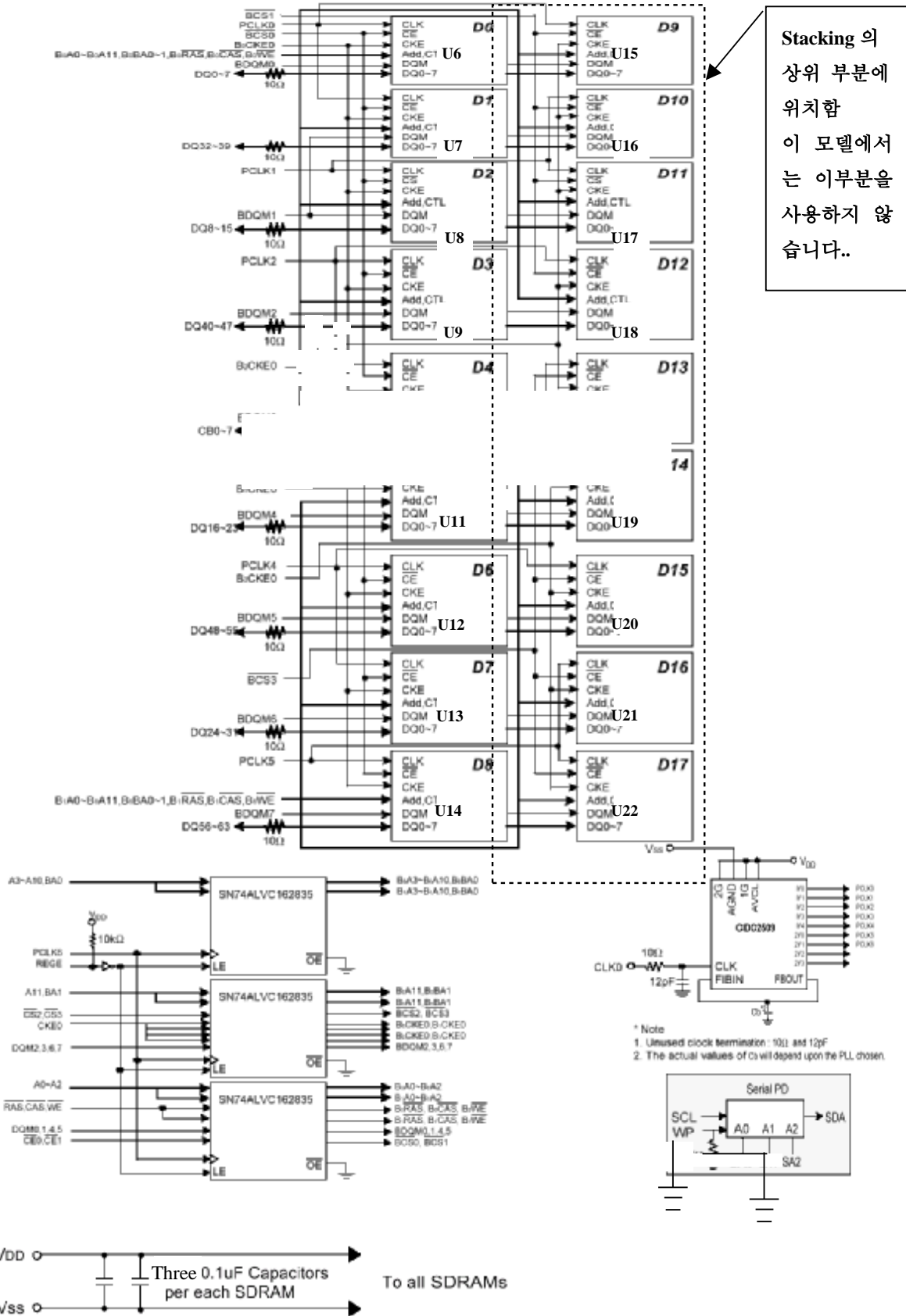
Vss: Ground

Vcc: Power supply(3.3V)

SCL: Serial clock

DU: Don't use

FUNCTIONAL BLOCK DIAGRAM



PIN FUNCTION DESCRIPTION

| Pin | Name | Input Function |
|-----------|------------------------|---|
| CLK | System clock | Active on the positive going edge to sample all inputs. |
| /CE | Chip enable | Disables or enables device operation by masking or enabling all inputs except CLK, CKE and DQM |
| CKE | Clock enable | Masks system clock to freeze operation from the next clock cycle. CKE should be enabled at least one cycle prior to new command. Disable input buffers for power down in standby. CKE should be enabled 1CLK+tss prior to valid command. |
| A0 ~ A11 | Address | Row/column addresses are multiplexed on the same pins. Row address : RA0 ~ RA11, Column address : CA0 ~ CA9 |
| BA0 ~ BA1 | Bank select address | Selects bank to be activated during row address latch time. Selects bank for read/write during column address latch time. |
| /RAS | Row address strobe | Latches row addresses on the positive going edge of the CLK with /RAS low. Enables row access & precharge. |
| /CAS | Column address strobe | Latches column addresses on the positive going edge of the CLK with /CAS low. Enables column access. |
| /WE | Write enable | Enables write operation and row precharge. Latches data in starting from /CAS, /WE active. |
| DQM0 ~ 7 | Data input/output mask | Makes data output Hi-Z, tsHZ after the clock and masks the output. Blocks data input when DQM active. (Byte masking) |
| REGE | Register enable | The device operates in the transparent mode when REGE is low. When REGE is high, the device operates in the registered mode. In registered mode, the Address and control inputs are latched if CLK is held at a high or low logic level. The inputs are strobed in the latch/flip-flop on the rising edge of CLK. REGE is tied to V _{DD} through 10K ohm register on PCB. So if REGE of module is floating, this module will be operated as registered mode. |
| DQ0 ~ 63 | Data input/output | Data inputs/outputs are multiplexed on the same pins. |
| Vcc/Vss | Power supply/ground | Power and ground for the input buffers and the core logic. |

ABSOLUTE MAXIMUM RATINGS

| PARAMETER | SYMBOL | RATING |
|---------------------------------------|--------------|----------------|
| Voltage on Any Pin Relative to Vss | $V_{IN,OUT}$ | -1V to 4.6V |
| Voltage on Vcc Supply Relative to Vss | Vcc | -1V to 4.6V |
| Power Dissipation | P_D | 8W |
| Storage Temperature | T_{STG} | -55°C to 150°C |
| Short Circuit Output Current | I_{OS} | 50mA |

Notes:

Permanent device damage may occur if " Absolute Maximum Ratings" are exceeded. Functional operation should be restricted to the conditions as detailed in the operational sections of this data sheet. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC OPERATING CONDITIONS

(Recommended operating conditions (Voltage referenced to Vss = 0V, $T_A = 0$ to 70°C)

| PARAMETER | SYMBOL | MIN | TYP. | MAX | UNIT | NOTE |
|-----------------------|----------|------|------|--------------|------|-----------------|
| Supply Voltage | Vcc | 3.0 | 3.3 | 3.6 | V | |
| Input High Voltage | V_{IH} | 2.0 | 3.0 | $V_{cc}+0.3$ | V | 1 |
| Input Low Voltage | V_{IL} | -0.3 | 0 | 0.8 | V | 2 |
| Output High Voltage | V_{OH} | 2.4 | - | - | V | $I_{OH} = -2mA$ |
| Output Low Voltage | V_{OL} | - | - | 0.4 | V | $I_{OL} = 2mA$ |
| Input leakage current | I_{LI} | -10 | - | 10 | uA | 3 |

Notes :

- V_{IH} (max) = 5.6V AC. The overshoot voltage duration is $\leq 3ns$.
- V_{IL} (min) = -2.0V AC. The undershoot voltage duration is $\leq 3ns$.
- Any input $0V \leq V_{IN} \leq V_{DDQ}$.
Input leakage currents include Hi-Z output leakage for all bi-directional buffers with Tri-State outputs.

CAPACITANCE

(Vcc = 3.3V, $T_A = 23^\circ C$, $f = 1MHz$, $V_{REF} = 1.4V \pm 200 mV$)

| DESCRIPTION | SYMBOL | MIN | MAX | UNITS |
|--|-----------|-----|-----|-------|
| Input capacitance(A0~A11) | C_{IN1} | 2.5 | 5.0 | pF |
| Input capacitance(/RAS, /CAS,/WE) | C_{IN2} | 2.5 | 5.0 | pF |
| Input capacitance(CKE0) | C_{IN3} | 2.5 | 5.0 | pF |
| Input capacitance(CLK0) | C_{IN4} | 2.5 | 4.0 | pF |
| Input capacitance(/CE0,CE3) | C_{IN5} | 2.5 | 5.0 | pF |
| Input capacitance(DQM0~DQM7) | C_{IN3} | 2.5 | 5.0 | pF |
| Input capacitance(BA0~BA1) | C_{IN3} | 2.5 | 5.0 | pF |
| Data input/output capacitance (DQ0 ~ DQ63) | C_{OUT} | 4.0 | 6.5 | pF |

DC CHARACTERISTICS

(Recommended operating condition unless otherwise noted, $T_A = 0$ to 70°C)

| PARAMETER | SYMBOL | TEST CONDITION | VERSION | | | | | UNIT | NOT E |
|---|-------------|--|----------|----------|----------|----------|----------|------|----------|
| | | | -13 | -12 | -1H | -1L | -10 | | |
| Operating current (One bank active) | I_{CC1} | Burst length = 1 $t_{RC} \geq t_{RC}(\text{min})$ $I_O = 0\text{mA}$ | 960 | 960 | 880 | 880 | 880 | mA | 1 |
| Precharge standby current in power-down mode | I_{CC2P} | $\text{CKE} \leq V_{IL}(\text{max})$ $t_{CC}=10\text{ns}$ | 8 | | | | | mA | 3 |
| | I_{CC2PS} | $\text{CKE} \& \text{CLK} \leq V_{IL}(\text{max})$ $t_{CC}=\infty$ | 8 | | | | | mA | 3 |
| Precharge standby current in non power- down mode | I_{CC2N} | $\text{CKE} \geq V_{IH}(\text{min})$ $/\text{CE} \geq V_{IH}(\text{min}), t_{CC}=10\text{ns}$ Input signals are changed one time during 20ns | 160 | | | | | mA | 3 |
| | I_{CC2NS} | $\text{CKE} \geq V_{IH}(\text{min})$ $\text{CLK} \leq V_{IL}(\text{max}), t_{CC}=\infty$ Input signals are stable | 56 | | | | | | |
| Active standby current in power-down mode | I_{CC3P} | $\text{CKE} \leq V_{IL}(\text{max}), t_{CC}=10\text{ns}$ | 40 | | | | | mA | 3 |
| | I_{CC3PS} | $\text{CKE} \& \text{CLK} \leq V_{IL}(\text{max})$ $t_{CC}=\infty$ | 40 | | | | | | |
| Active standby current in non power-down mode (One bank active) | I_{CC3N} | $\text{CKE} \geq V_{IH}(\text{min}),$ $/\text{CE} \geq V_{IH}(\text{min}), t_{CC}=10\text{ns}$ Input signals are changed one time during 20ns | 240 | | | | | mA | 3 |
| | I_{CC3NS} | $\text{CKE} \geq V_{IH}(\text{min})$ $\text{CLK} \leq V_{IL}(\text{max}), t_{CC}=\infty$ Input signals are stable | 160 | | | | | | |
| Operating current (Burst mode) | I_{CC4} | $I_O = 0\text{mA}$ Page burst 4Banks Activated $t_{CCD} = 2\text{CLKs}$ | 1.2 | 1.1 6 | 1 | 1 | 1 | A | 1 |
| Refresh current | I_{CC5} | $t_{RC} \geq t_{RC}(\text{min})$ | 1.7 6 | 1.7 6 | 1.6 8 | 1.6 8 | 1.6 8 | A | 2 |
| Self refresh current | I_{CC6} | $\text{CKE} \leq 0.2\text{V}$ | 12 | | | | | mA | 3 |

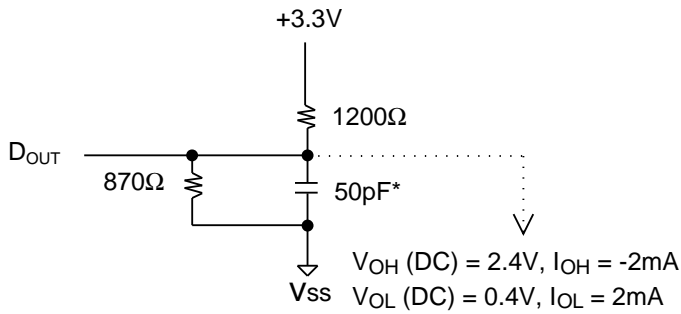
Notes:

1. Measured with outputs open.
2. Refresh period is 64ms.
3. Measured with 1PLL & 3 Drive Ics.
4. Unless otherwise noticed, input swing level is CMOS($V_{IH}/V_{IL}=V_{DDQ}/V_{SSQ}$).

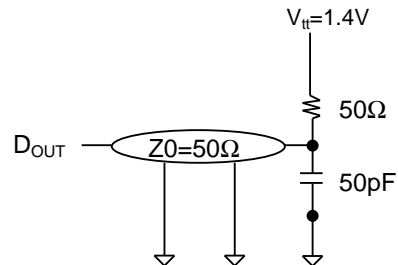
AC OPERATING TEST CONDITIONS

(V_{CC} = 3.3V ± 0.3V, T_A = 0 to 70°C)

| PARAMETER | Value | UNIT |
|---|-------------|------|
| AC Input levels (V _{ih} /V _{il}) | 2.4/0.4 | V |
| Input timing measurement reference level | 1.4 | V |
| Input rise and fall time | tr/tf = 1/1 | ns |
| Output timing measurement reference level | 1.4 | V |
| Output load condition | See Fig. 2 | |



(Fig. 1) DC output load circuit



(Fig. 2) AC output load circuit

OPERATING AC PARAMETER

(AC operating conditions unless otherwise noted)

| PARAMETER | SYMBOL | VERSION | | | | | UNIT | NOTE |
|--|------------------------|---------------|-----|-----|-----|-----|------|------|
| | | -13 | -12 | -1H | -1L | -10 | | |
| Row active to row active delay | t _{RRD} (min) | 15 | 16 | 20 | 20 | 20 | ns | 1 |
| /RAS to /CAS delay | t _{RCD} (min) | 20 | 20 | 20 | 20 | 24 | ns | 1 |
| Row precharge time | t _{RP} (min) | 20 | 20 | 20 | 20 | 24 | ns | 1 |
| Row active time | t _{RAS} (min) | 45 | 48 | 50 | 50 | 50 | ns | 1 |
| | t _{RAS} (max) | 100 | | | | | ns | |
| Row cycle time | t _{RC} (min) | 65 | 68 | 70 | 70 | 80 | ns | 1 |
| Last data in to row precharge | t _{RDL} (min) | 2 | | | | | CLK | 2,5 |
| Last data in to Active delay | t _{DAL} (min) | 2 CLK + 20 ns | | | | | - | 5 |
| Last data in to new col. address delay | t _{CDL} (min) | 1 | | | | | CLK | 2 |
| Last data in to burst stop | t _{BDL} (min) | 1 | | | | | CLK | 2 |
| Col. address to col. address delay | t _{CCD} (min) | 1 | | | | | CLK | 3 |
| Number of valid output data | CAS latency=3 | 2 | | | | | ea | 4 |
| | CAS latency=2 | 1 | | | | | | |

Notes :

1. The minimum number of clock cycles is determined by dividing the minimum time required with clock cycle time and then rounding off to the next higher integer.
2. Minimum delay is required to complete write.
3. All parts allow every cycle column address change.
4. In case of row precharge interrupt, auto precharge and read burst stop.
5. For -1H/1L, tRDL=1CLK and tDAL=1CLK+20ns is also supported .
(recommend : tRDL=2CLK and tDAL=2CLK + 20ns.)

AC CHARACTERISTICS

(AC operating conditions unless otherwise noted)

| PARAMETER | | SYMBOL | -13 | | -12 | | -1H | | -1L | | -10 | | UNIT | NOTE |
|---------------------------|---------------|------------------|-----|------|-----|-----|-----|-----|-----|-----|-----|-----|------|------|
| | | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | | |
| CLK cycle time | CAS latency=3 | t _{CC} | 7.5 | 1000 | 8 | 100 | 10 | 100 | 10 | 100 | 10 | 100 | ns | 1 |
| | CAS latency=2 | | - | | - | | 0 | | 10 | | 0 | | | |
| CLK to valid output delay | CAS latency=3 | t _{SAC} | | 5.4 | | 6 | | 6 | | 6 | | 7 | ns | 1,2 |
| | CAS latency=2 | | | - | | - | | 6 | | 7 | | 7 | | |
| Output data hold time | CAS latency=3 | t _{OH} | 2.7 | | 3 | | 3 | | 3 | | 3 | | ns | 2 |
| | CAS latency=2 | | | | | | 3 | | 3 | | 3 | | | |
| CLK high pulse width | | t _{CH} | 2.5 | | 3 | | 3 | | 3 | | 3.5 | | ns | 3 |
| CLK low pulse width | | t _{CL} | 2.5 | | 3 | | 3 | | 3 | | 3.5 | | ns | 3 |
| Input setup time | | t _{SS} | 1.5 | | 2 | | 2 | | 2 | | 2.5 | | ns | 3 |
| Input hold time | | t _{SH} | 0.8 | | 1 | | 1 | | 1 | | 1.5 | | ns | 3 |
| CLK to output in Low-Z | | t _{SLZ} | 1 | | 1 | | 1 | | 1 | | 1 | | ns | 2 |
| CLK to output in Hi-Z | CAS latency=3 | t _{SHZ} | | 5.4 | | 6 | | 6 | | 6 | | 7 | ns | |
| | CAS latency=2 | | | - | | - | | 6 | | 7 | | 7 | ns | |

Notes :

1. Parameters depend on programmed CAS latency.
2. If clock rising time is longer than 1ns, (tr/2-0.5)ns should be added to the parameter.
3. Assumed input rise and fall time (tr & tf) = 1ns.
If tr & tf is longer than 1ns, transient time compensation should be considered
i.e., [(tr + tf)/2-1]ns should be added to the parameter.

SIMPLIFIED TRUTH TABLE

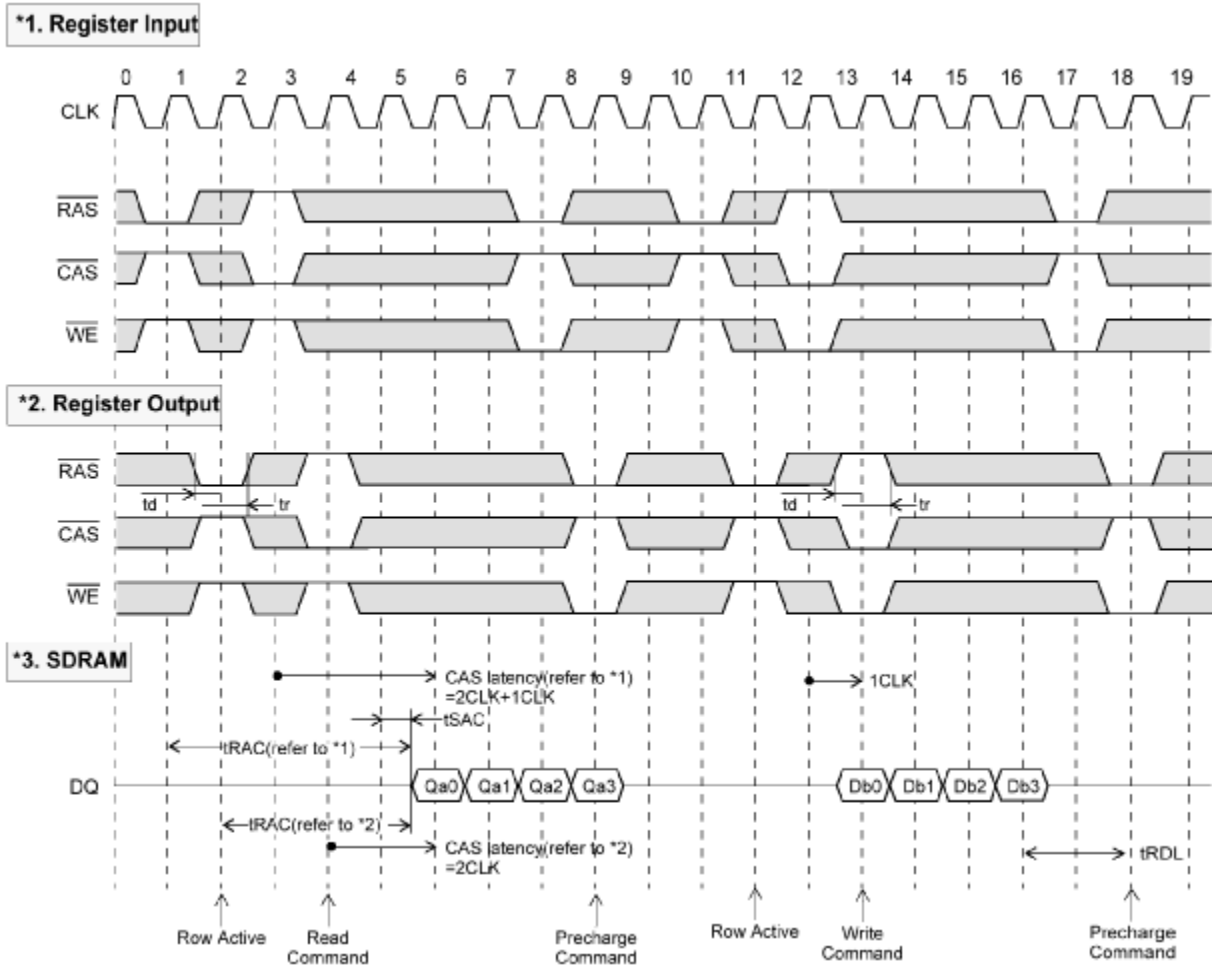
| COMMAND | | CKE n-1 | CKE n | /CE | /RAS | /CAS | /WE | DQM | BA 0,1 | A10/AP | A11 A9~A0 | NOTE |
|------------------------------------|------------------------|---------|-------|------|------|------|-----|-----|---------|-------------|--------------------------|------|
| Register | Mode register set | H | X | L | L | L | L | X | OP code | | | 1,2 |
| Refresh | Auto refresh | H | H | L | L | L | H | X | X | | | 3 |
| | Entry | | L | | | | | | | | | 3 |
| | Self refresh | L | H | L | H | H | H | X | X | | | 3 |
| | | | | Exit | H | X | X | | | | | X |
| Bank active & row addr. | | H | X | L | L | H | H | X | V | Row address | | |
| Read & column address | Auto precharge disable | H | X | L | H | L | H | X | V | L | Column Address (A0 ~ A9) | 4 |
| | Auto precharge enable | | | | | | | | | H | | 4,5 |
| Write & column address | Auto precharge disable | H | X | L | H | L | H | X | V | L | Column Address (A0 ~ A9) | 4 |
| | Auto precharge enable | | | | | | L | | | 4,5 | | |
| Burst Stop | | H | X | L | H | H | L | X | X | | | 6 |
| Precharge | Bank selection | H | X | L | L | H | L | X | V | L | X | |
| | All banks | | | | | | | | X | H | | |
| Clock suspend or active power down | Entry | H | L | H | X | X | X | X | X | | | |
| | | | | L | V | V | V | | | | | |
| Exit | L | H | H | X | X | X | X | X | X | | | |
| | | | | X | X | X | X | | | | | |
| Precharge power down mode | Entry | H | L | H | X | X | X | X | X | | | |
| | | | | L | H | H | H | | | | | |
| | Exit | L | H | H | X | X | X | X | | | | |
| | | | | L | V | V | V | | | | | |
| DQM | | H | X | | | | | V | X | | 7 | |
| No operation command | | H | X | H | X | X | X | X | X | | | |
| | | | | L | H | H | H | | | | | |

(V=Valid, X=Don't care, H=Logic high, L=Logic low)

Notes :

- OP Code : Operand code
A0 ~ A11 & BA0 ~ BA1 : Program keys. (@ MRS)
- MRS can be issued only at all banks precharge state.
A new command can be issued after 2 CLK cycles of MRS.
- Auto refresh functions are as same as CBR refresh of DRAM.
The automatical precharge without row precharge command is meant by "Auto".
Auto/self refresh can be issued only at all banks precharge state.
- BA0 ~ BA1 : Bank select addresses.
If both BA0 and BA1 are "Low" at read, write, row active and precharge, bank A is selected.
If both BA0 is "Low" and BA1 is "High" at read, write, row active and precharge, bank B is selected.
If both BA0 is "High" and BA1 is "Low" at read, write, row active and precharge, bank C is selected.
If both BA0 and BA1 are "High" at read, write, row active and precharge, bank D is selected.
If A10/AP is "High" at row precharge, BA0 and BA1 is ignored and all banks are selected.
- During burst read or write with auto precharge, new read/write command can not be issued.
Another bank read/write command can be issued after the end of burst.
New row active of the associated bank can be issued at t_{RP} after the end of burst.
- Burst stop command is valid at every burst length.
- DQM sampled at positive going edge of a CLK and masks the data-in at the very CLK (Write DQM latency is 0), but makes Hi-Z state the data-out of 2 CLK cycles after. (Read DQM latency is 2)

TIMING DIAGRAMS



td, tr = Delay of register (74LVC162835)

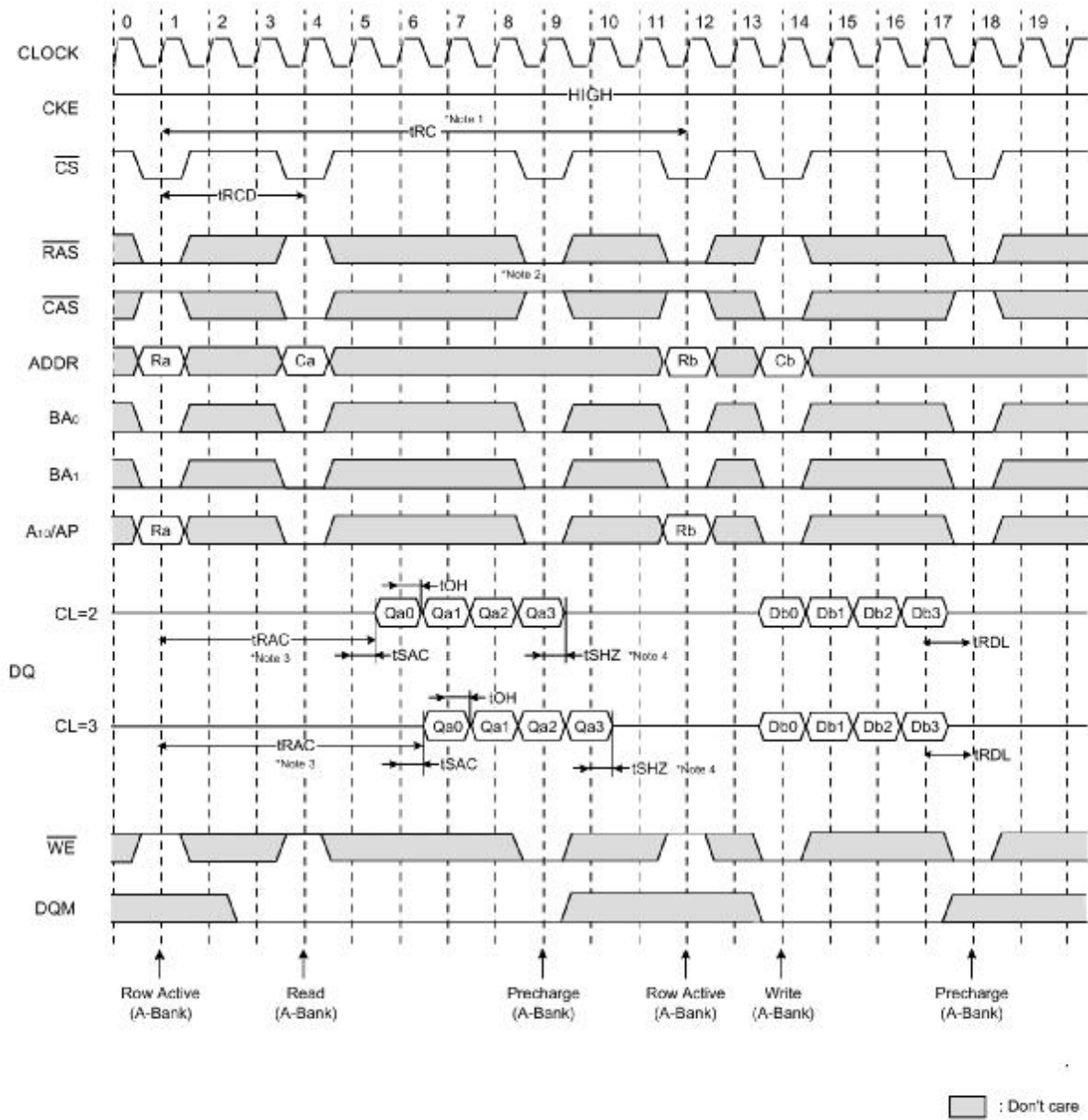
Notes : 1. In case of module timing, command cycles 1CLK with respect to external input timing at the address and input signal because of the buffering in register (74LVC162835). Therefore, Input/Output signals of read/write function should be issued 1CLK earlier as compared to Unbuffered MODULE.

2. D_{IN} is to be issued 1 clock after write command in external timing because D_{IN} is issued directly to module.

Power Up Sequence

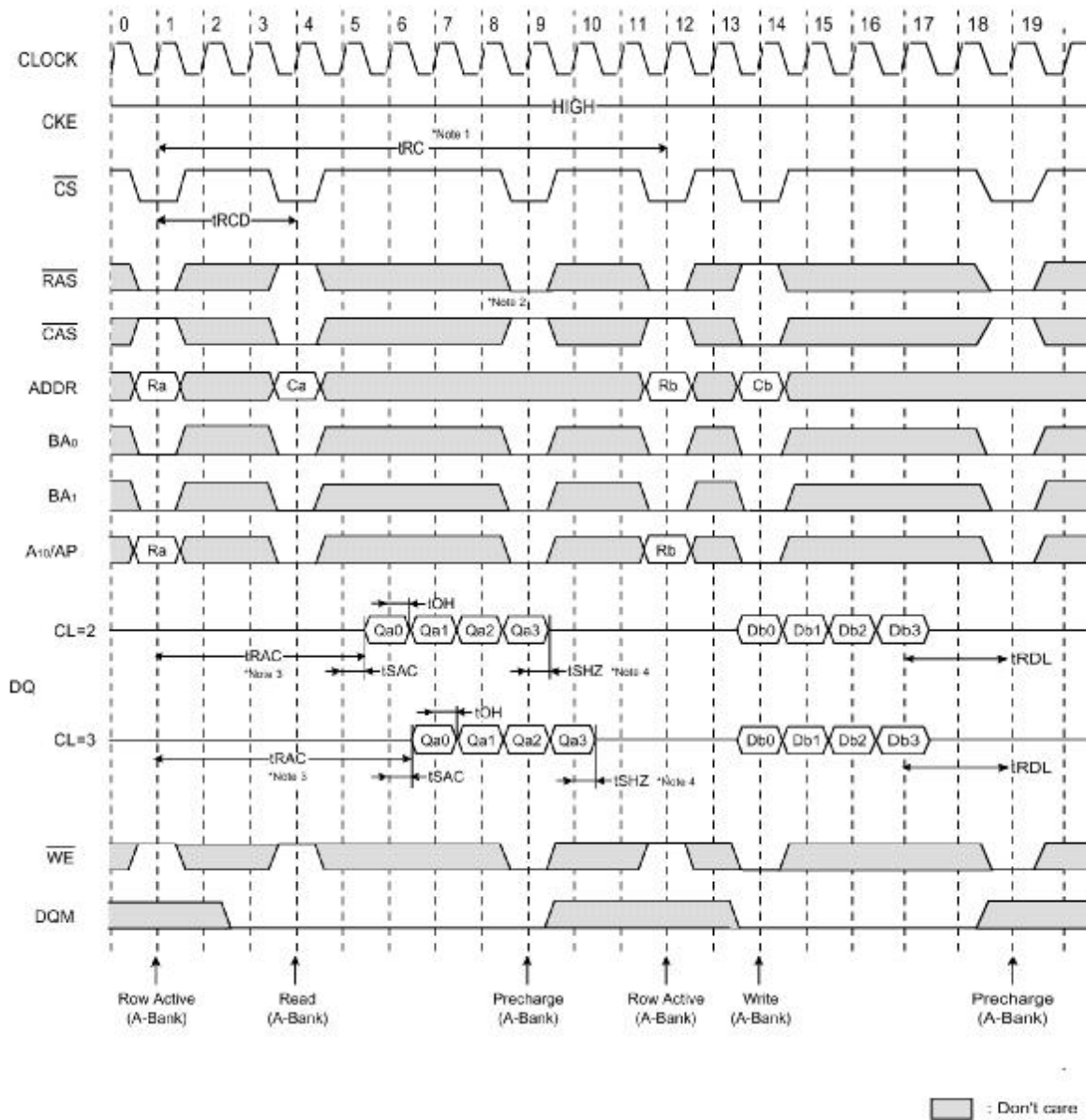


Read & Write Cycle at Same Bank @Burst Length=4, tRDL=1CLK



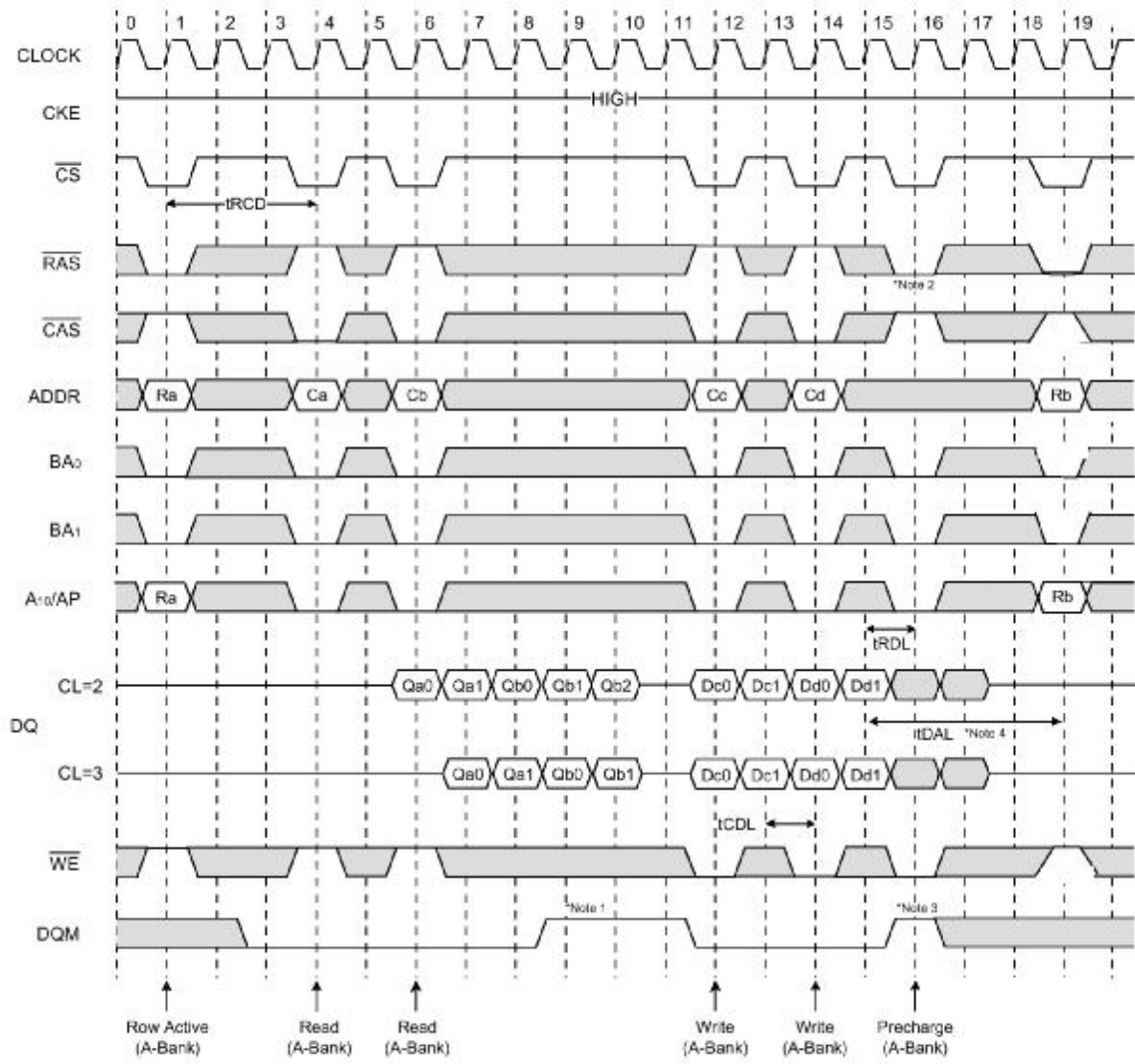
- *Note :**
1. Minimum row cycle times is required to complete internal DRAM operation.
 2. Row precharge can interrupt burst on any cycle. [CAS Latency - 1] number of valid output data is available after Row precharge. Last valid output will be Hi-Z(t_{SHZ}) after the clock.
 3. Access time from Row active command. $t_{acc} = (t_{RCD} + CAS\ latency - 1) + t_{SAC}$
 4. Output will be Hi-Z after the end of burst. (1, 2, 4, 8 & Full page bit burst)

Read & Write Cycle at Same Bank @Burst Length=4, tRDL=2CLK



- *Note :**
1. Minimum row cycle times is required to complete internal DRAM operation.
 2. Row precharge can interrupt burst on any cycle. [CAS Latency - 1] number of valid output data is available after Row precharge. Last valid output will be Hi-Z (hsiz) after the clock.
 3. Access time from Row active command. $t_{RC} = (t_{RCO} + \text{CAS latency} - 1) + t_{SAC}$
 4. Output will be Hi-Z after the end of burst. (1, 2, 4, 8 & Full page bit burst)

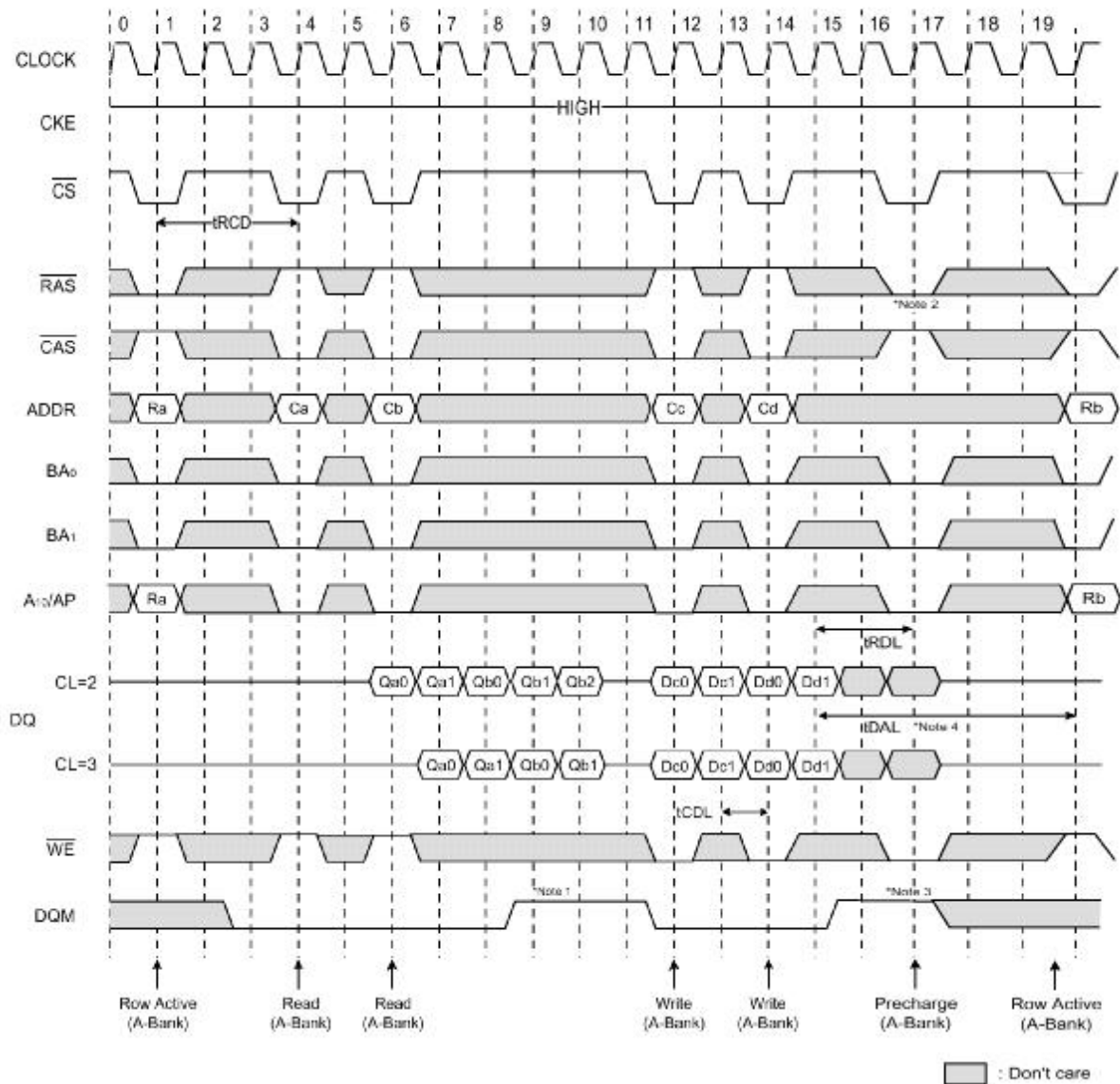
Page Read & Write Cycle at Same Bank @Burst Length=4, tRDL=1CLK



□ : Don't care

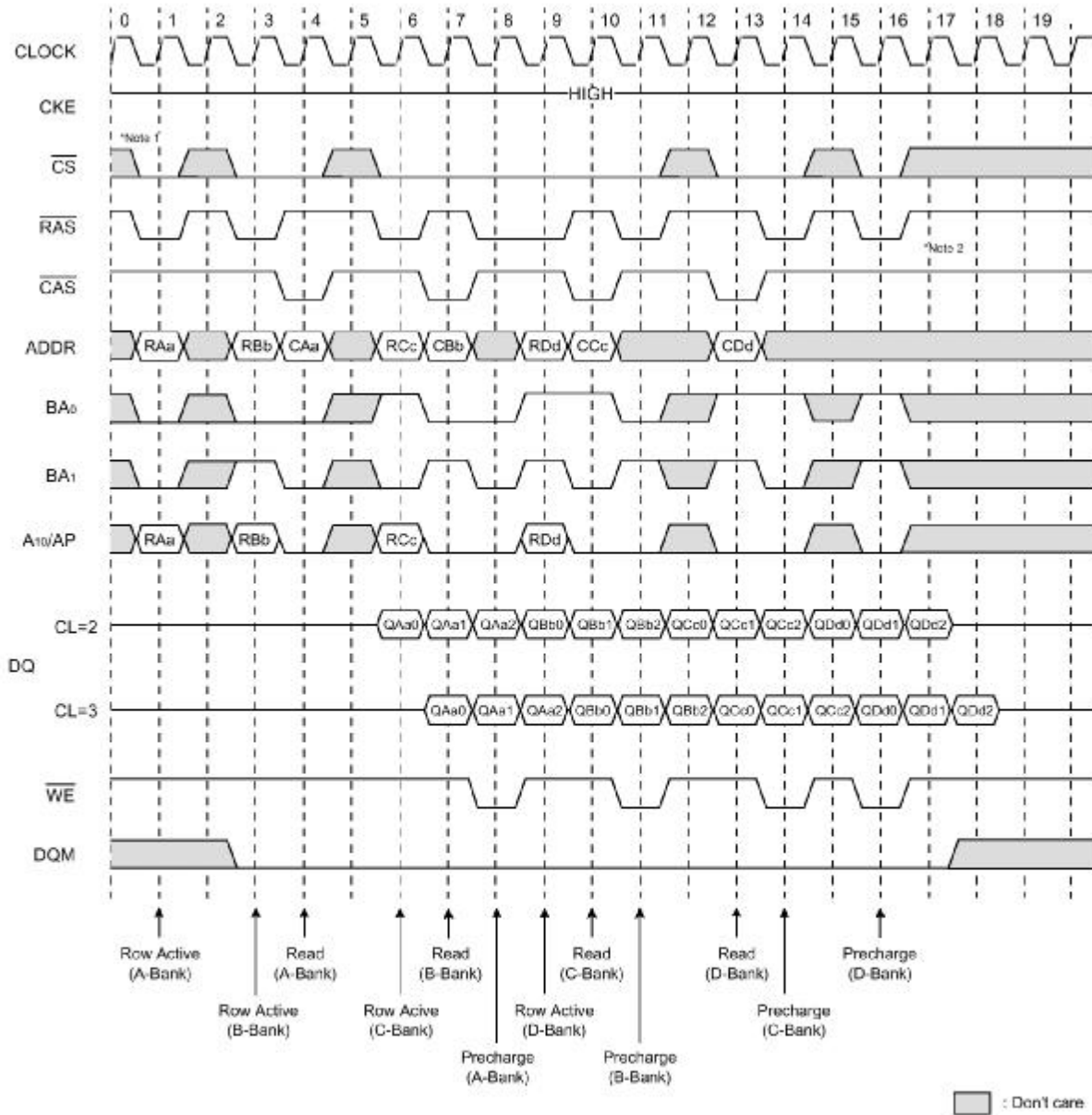
- *Note :**
1. To write data before burst read ends, DQM should be asserted three cycle prior to write command to avoid bus contention.
 2. Row precharge will interrupt writing. Last data input, t_{CDL} before Row precharge, will be written.
 3. DQM should mask invalid input data on precharge command cycle when asserting precharge before end of burst. Input data after Row precharge cycle will be masked internally.
 4. t_{DAL}, last data in to active delay, is 1CLK + 20ns

Page Read & Write Cycle at Same Bank @Burst Length=4, tRDL=2CLK



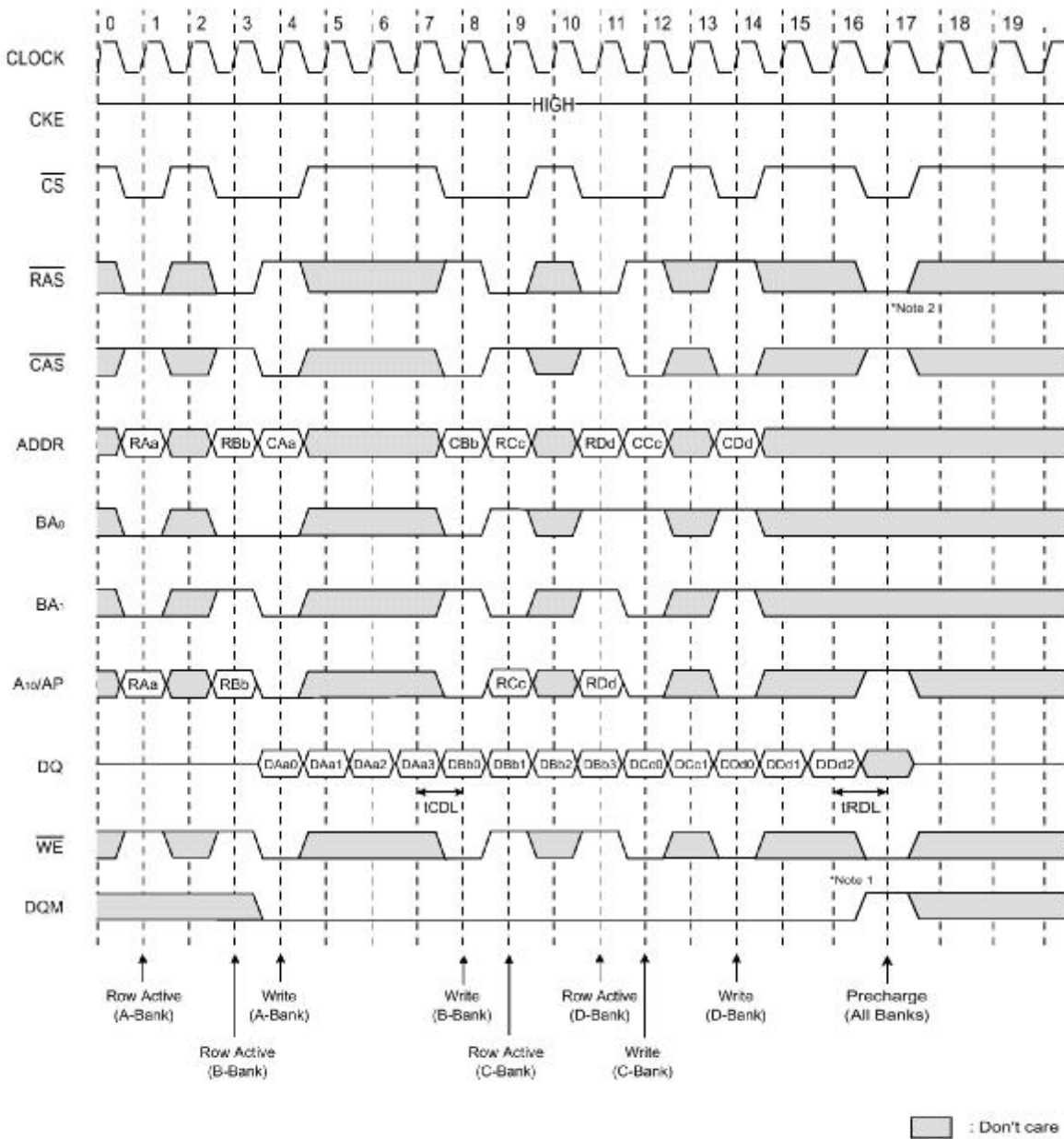
- *Note :**
1. To write data before burst read ends, DQM should be asserted three cycle prior to write command to avoid bus contention.
 2. Row precharge will interrupt writing. Last data input, tbcu before Row precharge, will be written.
 3. DQM should mask invalid input data on precharge command cycle when asserting precharge before end of burst. Input data after Row precharge cycle will be masked internally.
 4. tDAL (last data in to active delay, is 2CLK + 20ns).

Page Read Cycle at Different Bank @Burst Length=4



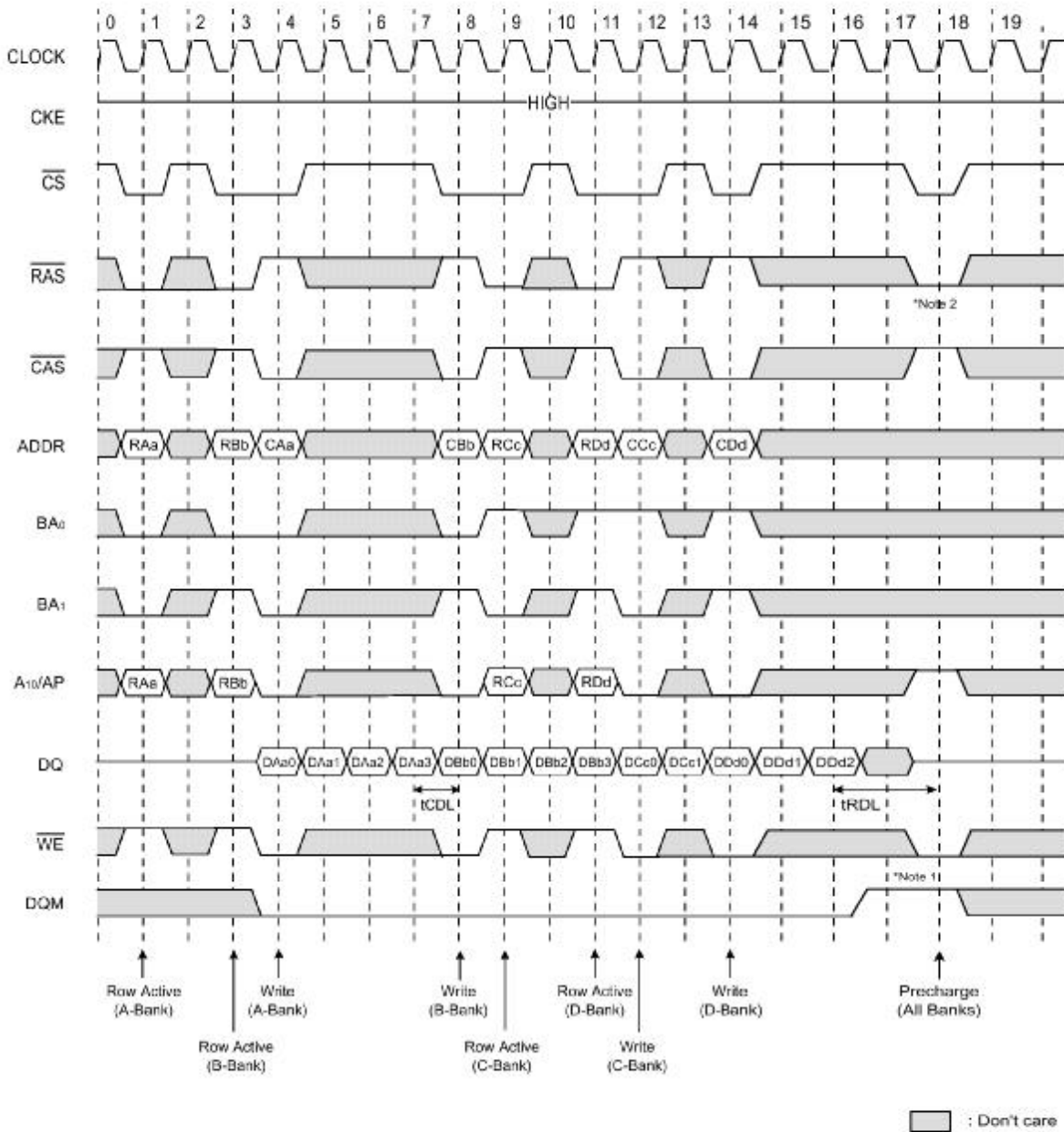
*Note : 1. CS can be don't cared when RAS, CAS and WE are high at the clock high going dege.
 2. To interrupt a burst read by row precharge, both the read and the precharge banks must be the same.

Page Write Cycle at Different Bank @Burst Length=4, tRDL=1CLK



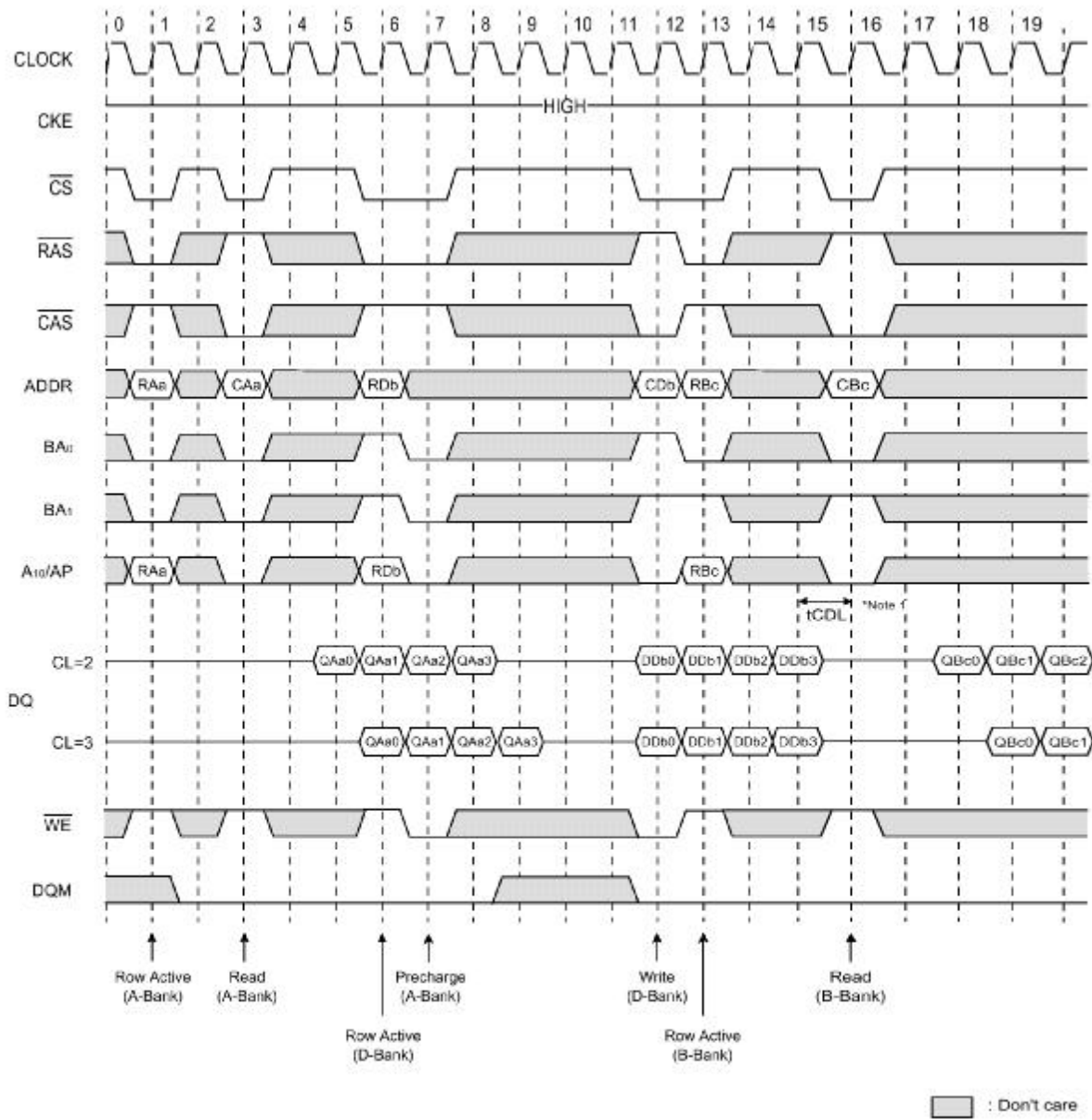
*Note : 1. To interrupt burst write by Row precharge, DQM should be asserted to mask invalid input data.
 2. To interrupt burst write by Row precharge, both the write and the precharge banks must be the same.

Page Write Cycle at Different Bank @Burst Length=4, tRDL=2CLK



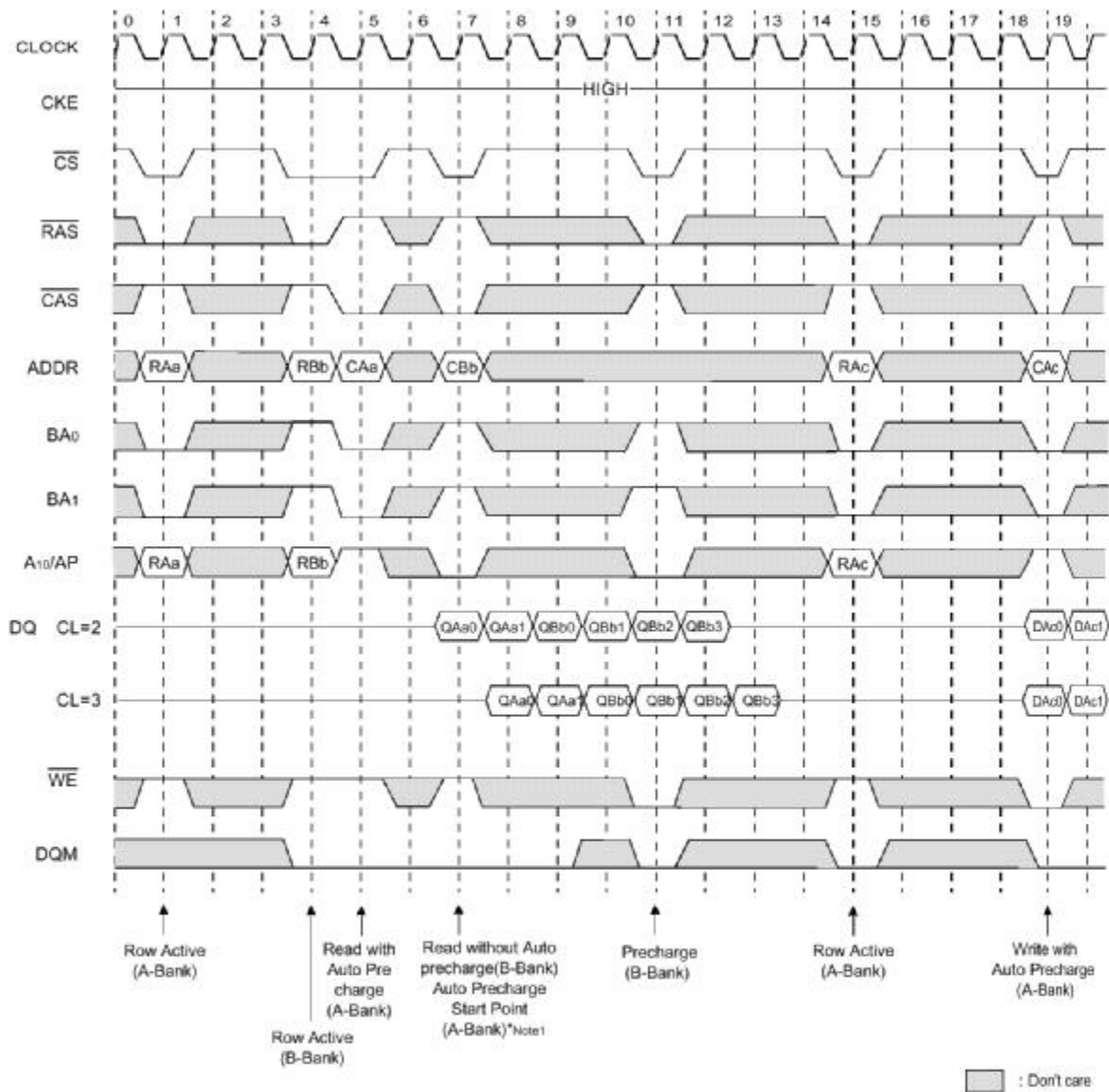
***Note :** 1. To interrupt burst write by Row precharge, DQM should be asserted to mask invalid input data.
 2. To interrupt burst write by Row precharge, both the write and the precharge banks must be the same.

Read & Write Cycle at Different Bank @Burst Length=4



*Note : 1. tCDL₁ should be met to complete write.

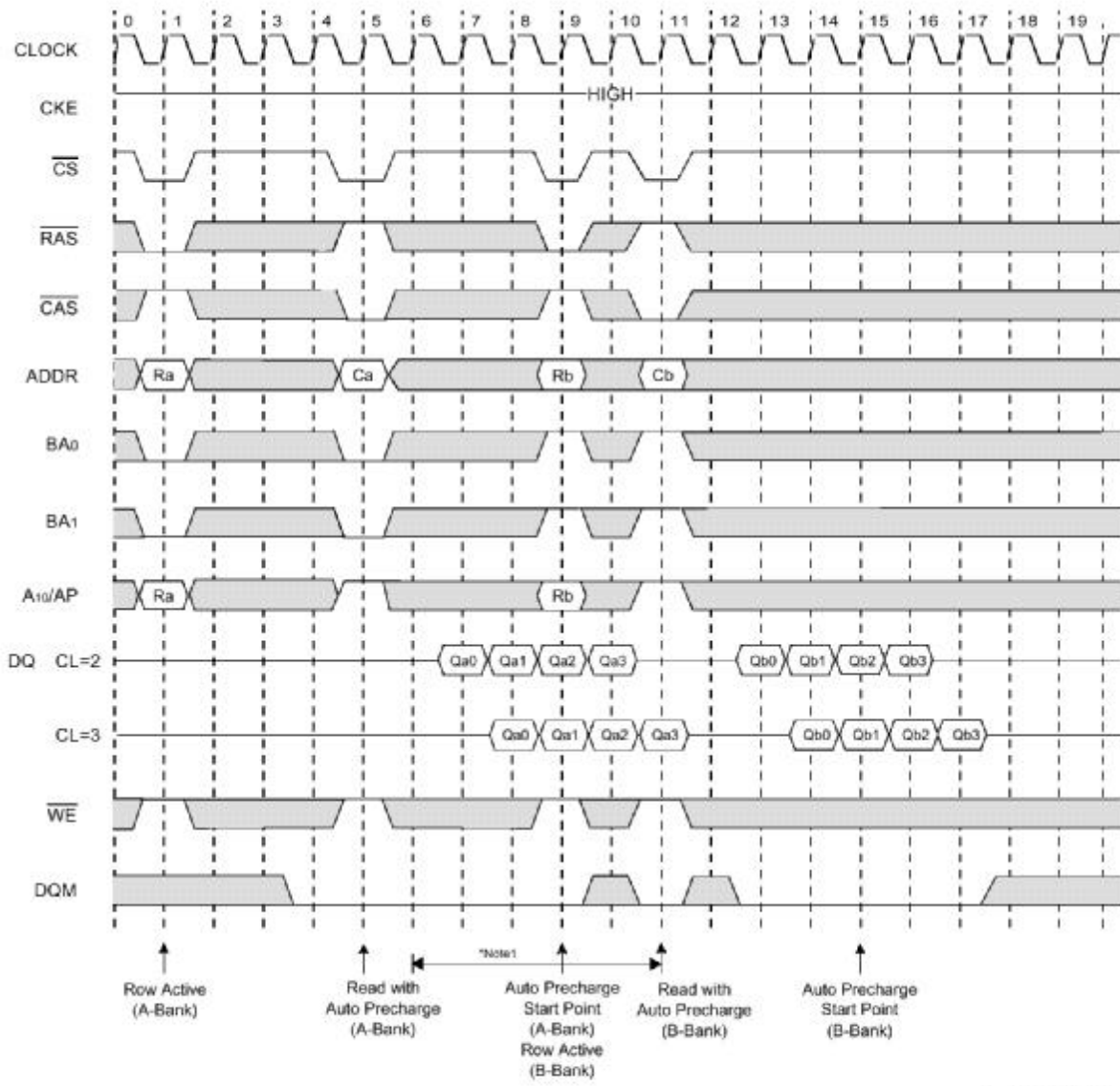
Read & Write Cycle with Auto Precharge I @Burst Length=4



***Note1:** When Read(Write) command with auto precharge is issued at A-Bank after A and B Bank activation.

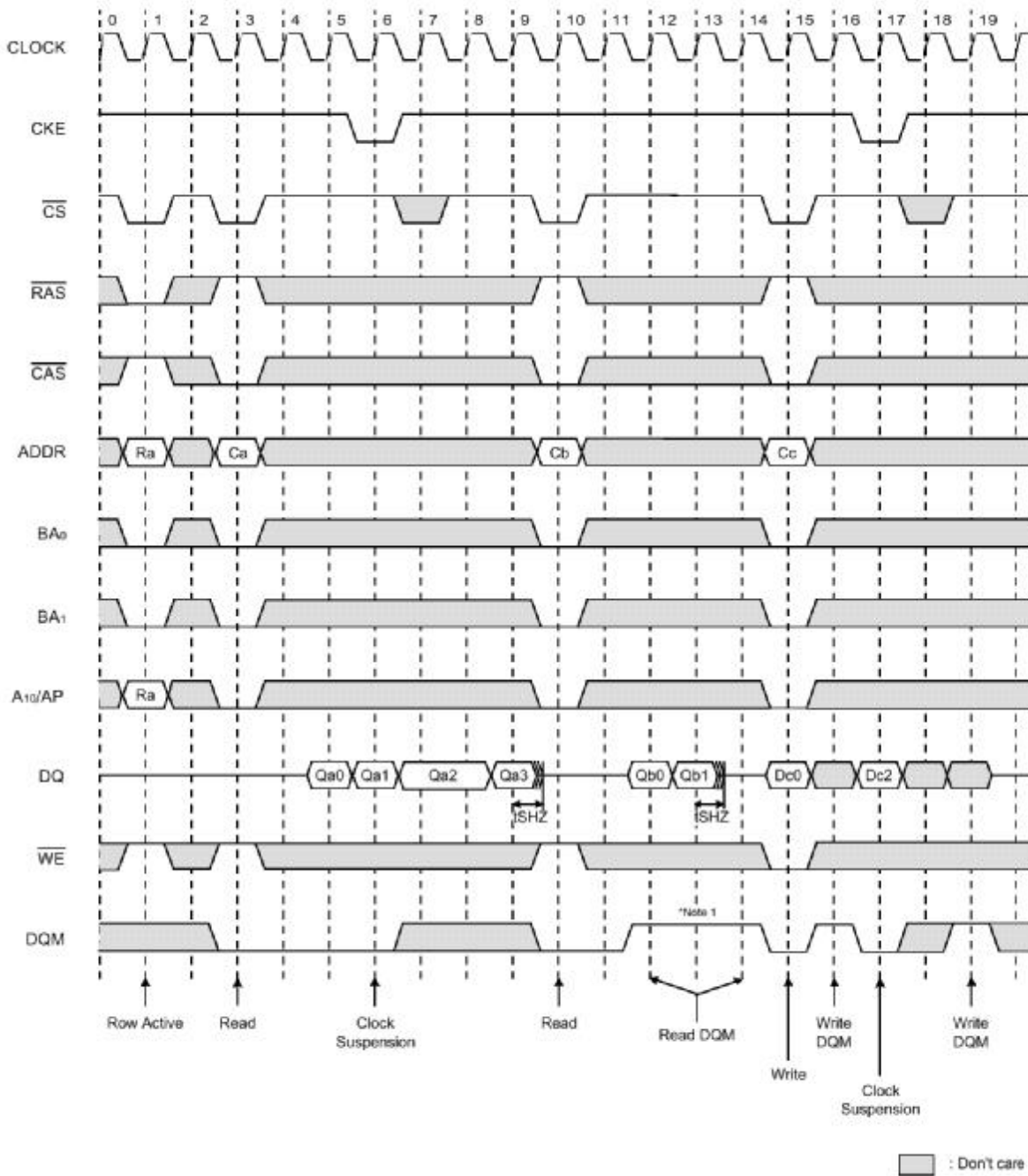
- if Read(Write) command without auto precharge is issued at B-Bank before A-Bank auto precharge starts, A-Bank auto precharge will start at B-Bank read command input point.
- any command can not be issued at A-Bank during tRP after A-Bank auto precharge starts.

Read & Write Cycle with Auto Precharge II @Burst Length=4



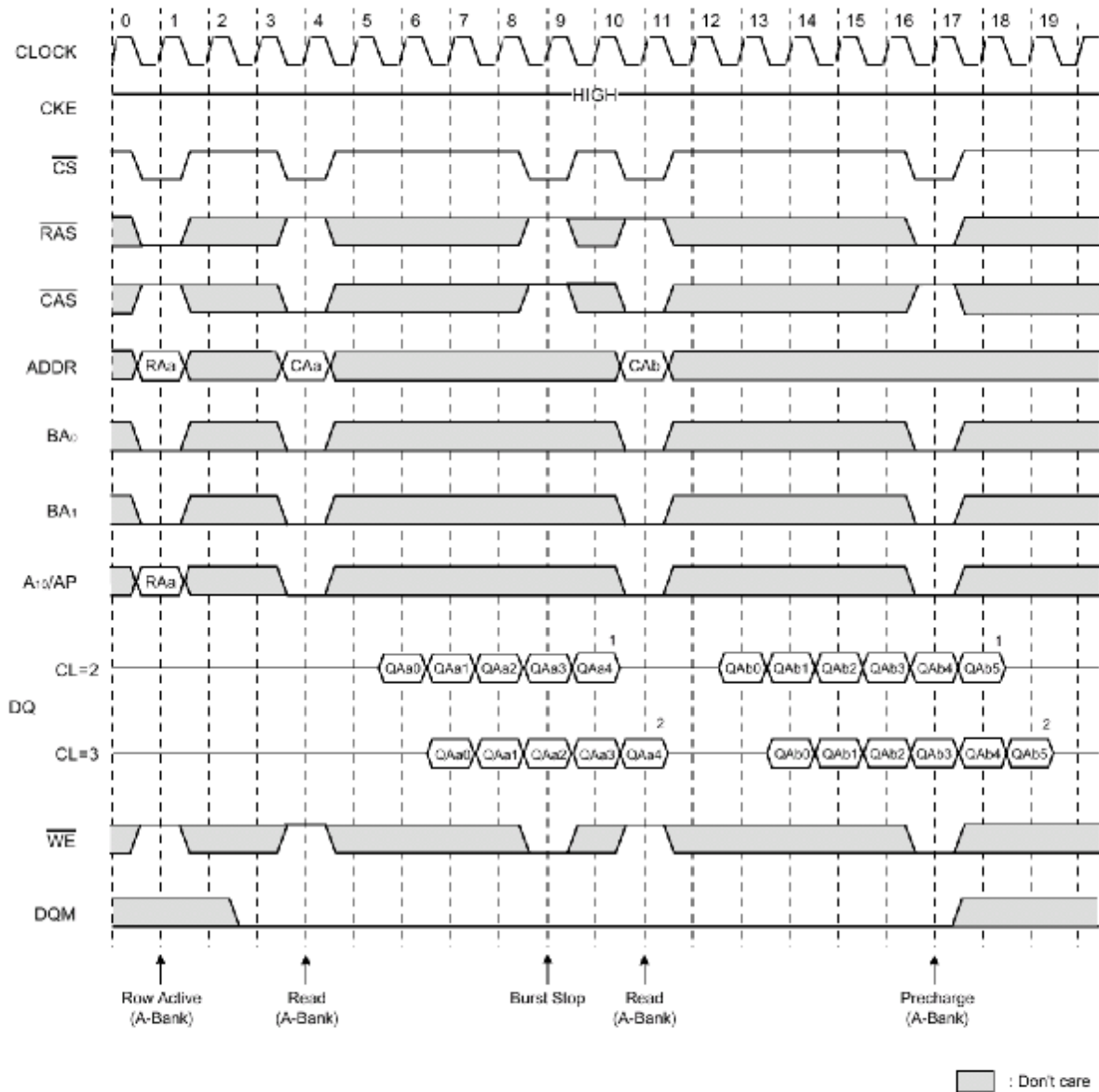
***Note 1:** Any command to A-bank is not allowed in this period. tRP is determined from at auto precharge start point.

Clock Suspension & DQM Operation Cycle @CAS Latency=2, Burst Length=4



*Note1 : DQM is needed to prevent bus contention.

Read Interrupted by Precharge Command & Read Burst Stop Cycle @ Full Page Burst



- *Note :**
1. At full page mode, burst is end at the end of burst. So auto precharge is possible.
 2. About the valid DCs after burst stop, it is same as the case of RAS interrupt. Both cases are illustrated above timing diagram. See the label 1, 2 on them. But at burst write, Burst stop and RAS interrupt should be compared carefully. Refer the timing diagram of "Full page write burst stop cycle".
 3. Burst stop is valid at every burst length.

Write Interrupted by Precharge Command & Write Burst Stop Cycle @ Full Page Burst, tRDL=1CLK



- *Note :**
1. At full page mode, burst is end at the end of burst. So auto precharge is possible.
 2. Data-in at the cycle of interrupted by precharge can not be written into the corresponding memory cell. It is defined by AC parameter of tRDL.
DQM at write interrupted by precharge command is needed to prevent invalid write.
DQM should mask invalid input data on precharge command cycle when asserting precharge before end of burst. Input data after Row precharge cycle will be masked internally.
 3. Burst stop is valid at every burst length.

□ : Don't care

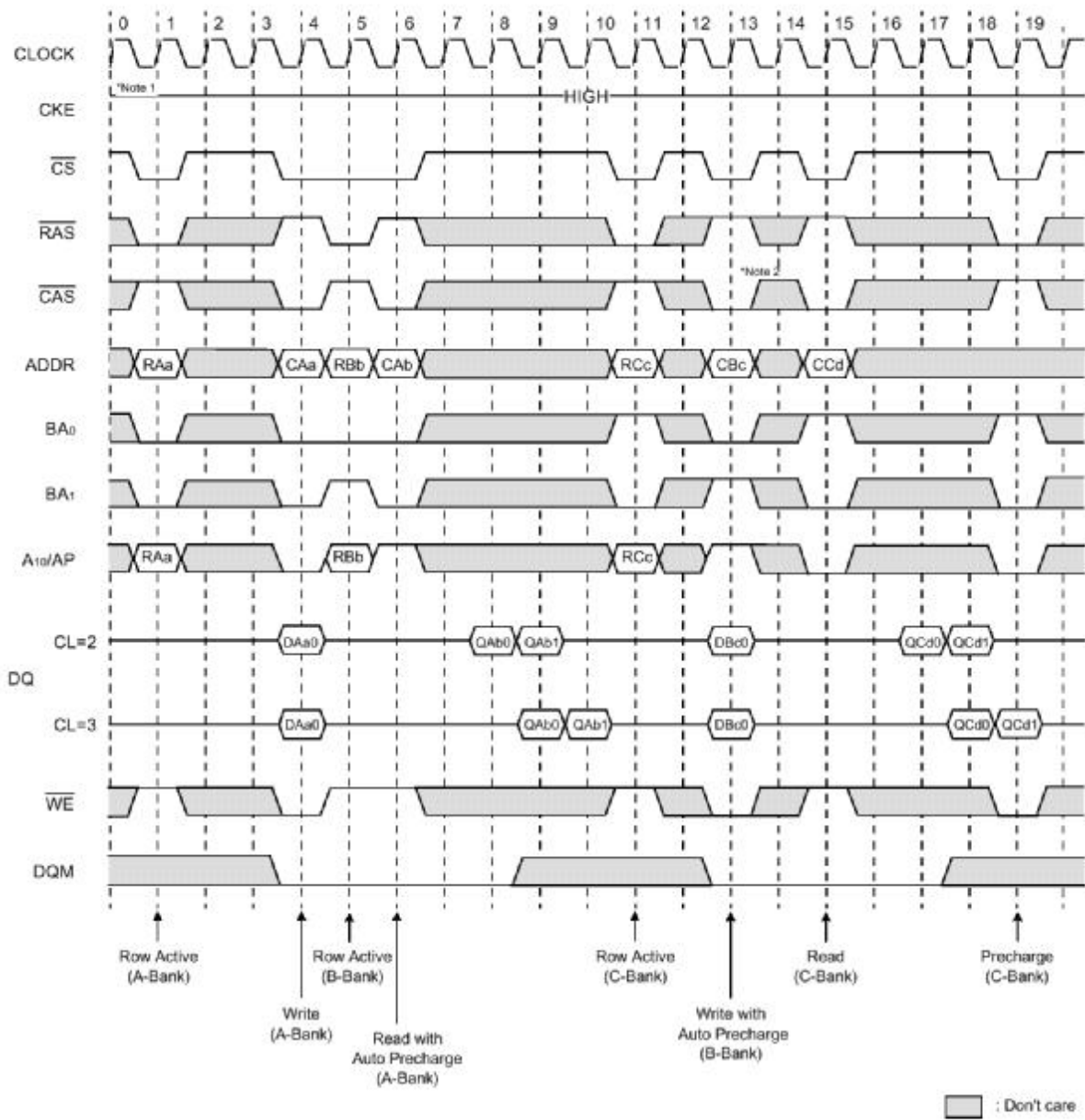
Write Interrupted by Precharge Command & Write Burst Stop Cycle @ Full Page Burst, tRDL=2CLK



- *Note :**
1. At full page mode, burst is end at the end of burst. So auto precharge is possible.
 2. Data-in at the cycle of interrupted by precharge can not be written into the corresponding memory cell. It is defined by AC parameter of tRPC.
DQM at write interrupted by precharge command is needed to prevent invalid write.
DQM should mask invalid input data on precharge command cycle when asserting precharge before end of burst. Input data after Row precharge cycle will be masked internally.
 3. Burst stop is valid at every burst length.

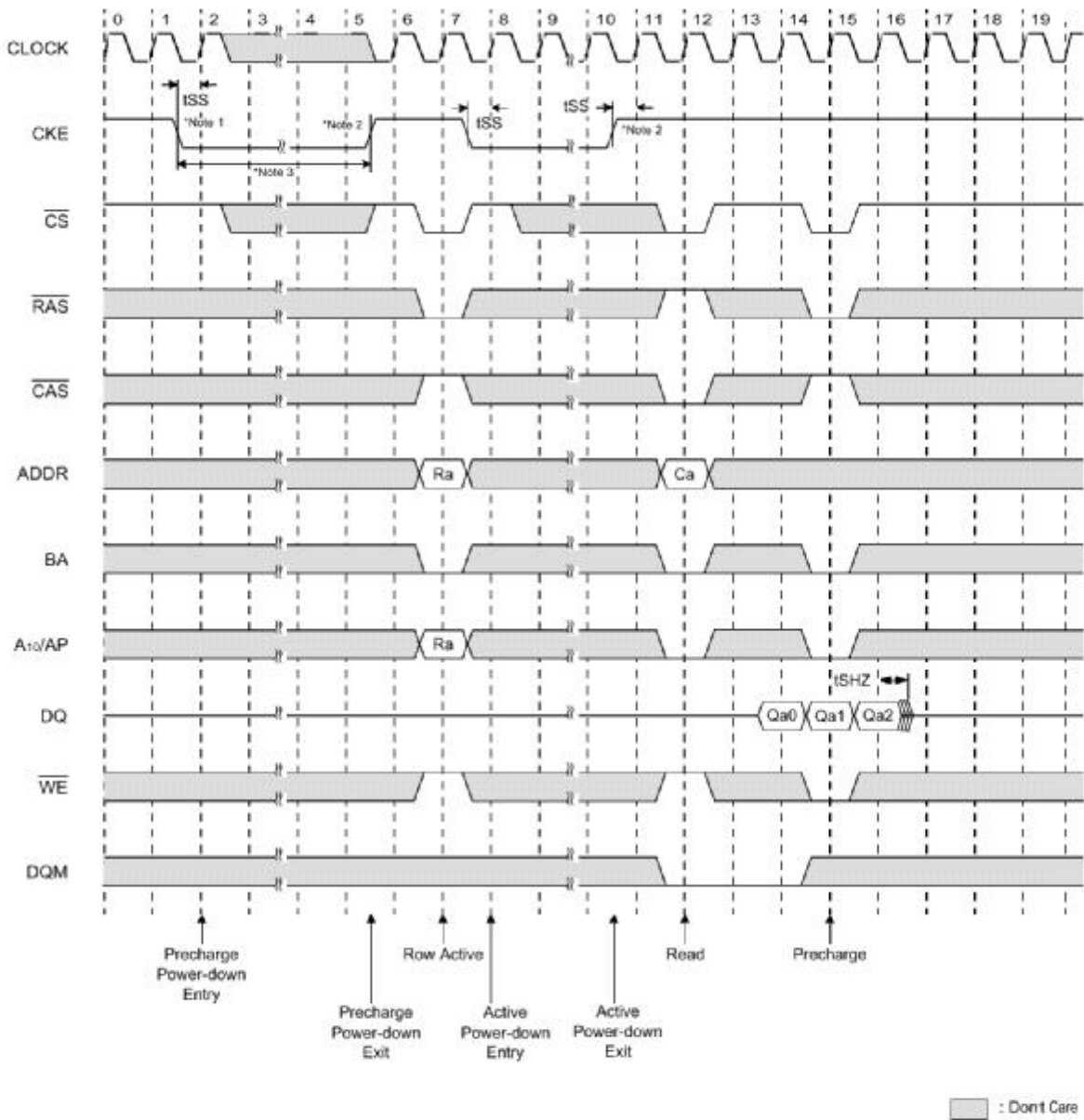
□ : Don't care

Burst Read Single bit Write Cycle @Burst Length=2



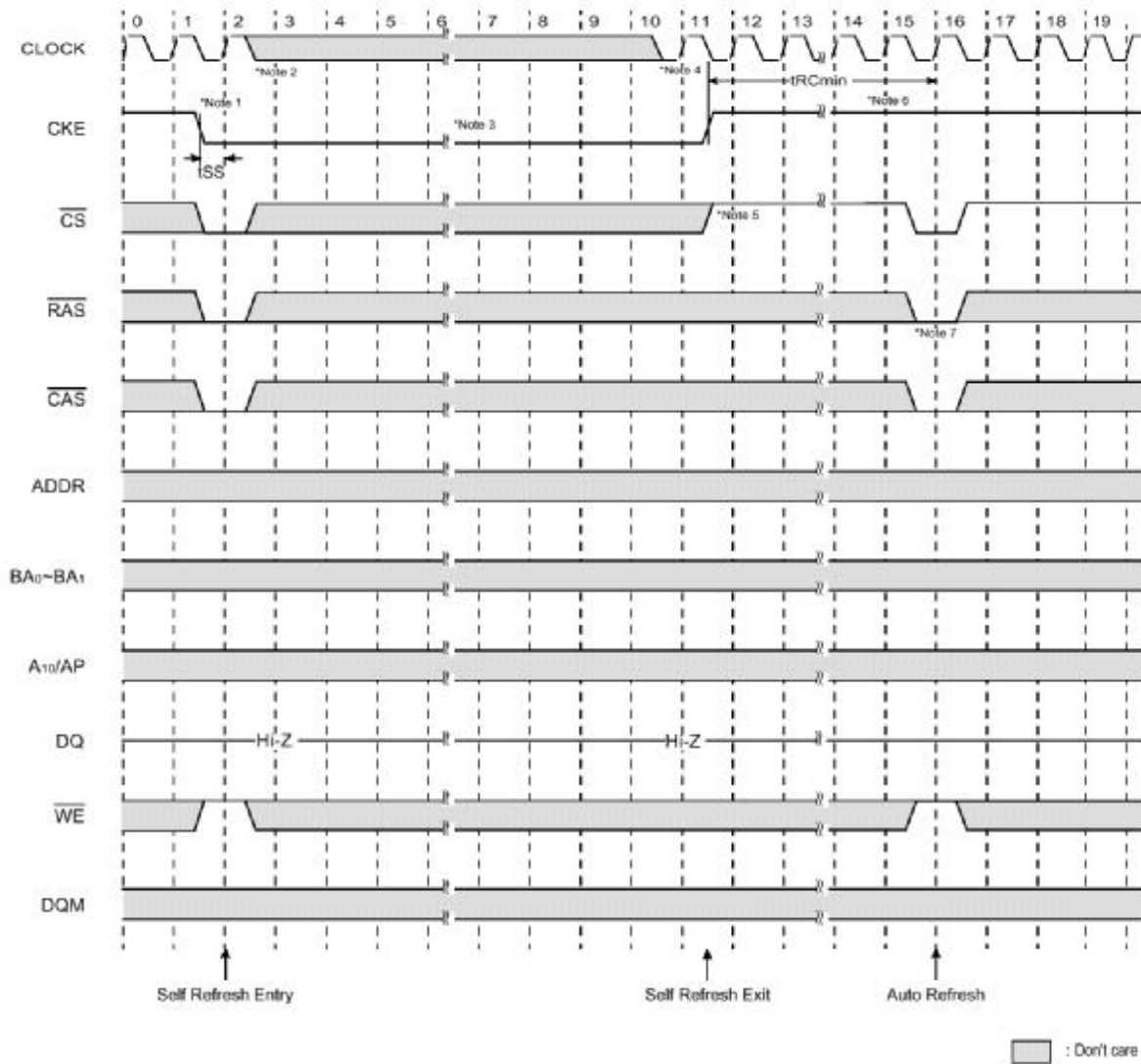
- *Note :**
1. BRSW modes is enabled by setting A9 "High" at MRS (Mode Register Set).
At the BRSW Mode, the burst length at write is fixed to "1" regardless of programmed burst length.
 2. When BRSW write command with auto precharge is executed, keep it in mind that tRAS should not be violated.
Auto precharge is executed at the burst-end cycle, so in the case of BRSW write command, the next cycle starts the precharge.

Active/Precharge Power Down Mode @CAS Latency=2, Burst Length=4



- *Note :**
1. Both banks should be in idle state prior to entering precharge power down mode.
 2. CKE should be set high at least 1CLK + tss prior to Row active command.
 3. Can not violate minimum refresh specification. (64ms)

Self Refresh Entry & Exit Cycle

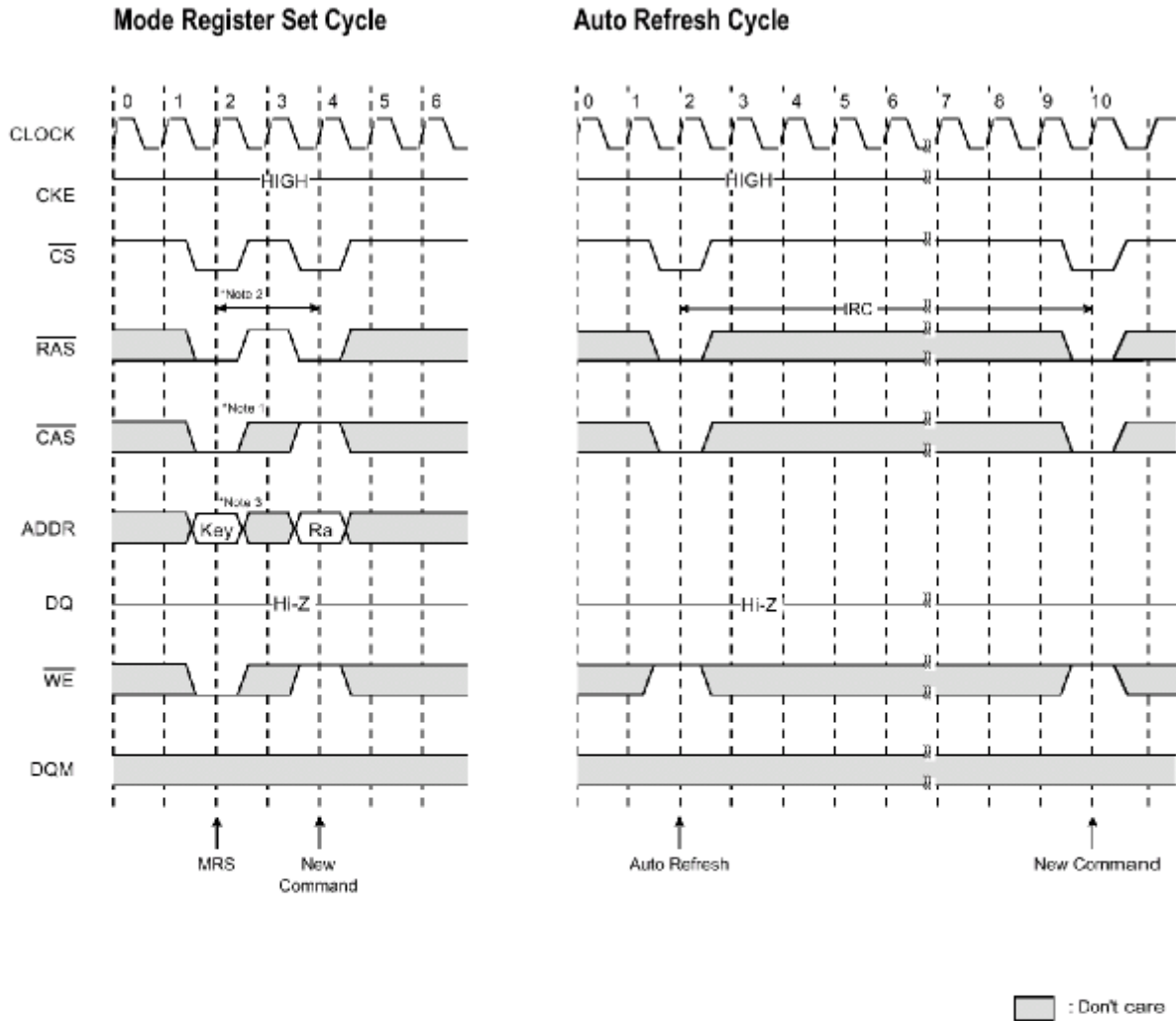


***Note : TO ENTER SELF REFRESH MODE**

1. \overline{CS} , \overline{RAS} & \overline{CAS} with CKE should be low at the same clock cycle.
2. After 1 clock cycle, all the inputs including the system clock can be don't care except for CKE.
3. The device remains in self refresh mode as long as CKE stays "Low".
 cf.) Once the device enters self refresh mode, minimum t_{RAS} is required before exit from self refresh.

TO EXIT SELF REFRESH MODE

4. System colck restart and be stable before returning CKE high.
5. \overline{CS} starts from high.
6. Minimum t_{RC} is required after CKE going high to complete self refresh exit.
7. 4K cycle(64Mb 5th, 128Mb 2nd/3rd) or 8K cycle(256Mb 2nd) of burst auto refresh is required before self refresh entry and after self refresh exit if the system uses burst refresh.



* All banks precharge should be completed before Mode Register Set cycle and auto refresh cycle.

MODE REGISTER SET CYCLE

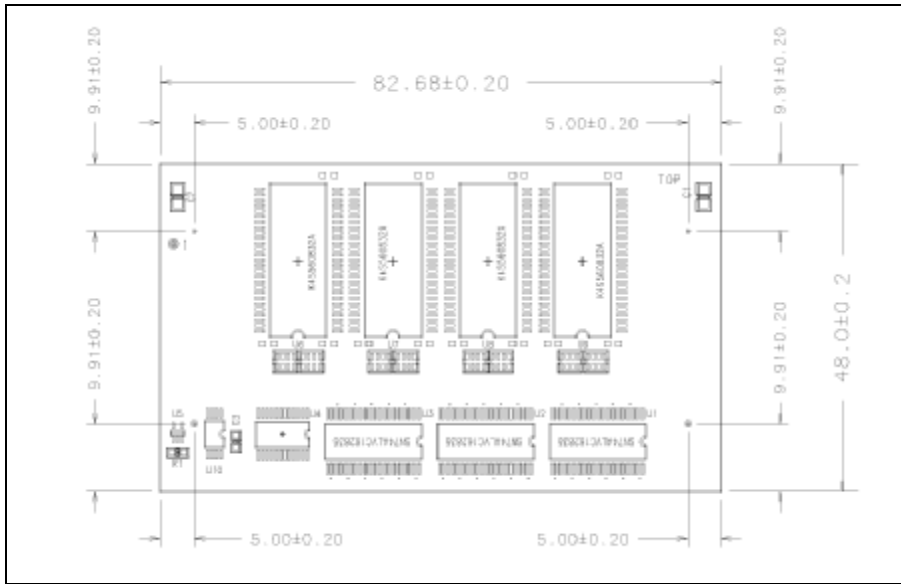
- *Note :**
1. CS, RAS, CAS, & WE activation at the same clock cycle with address key will set internal mode register.
 2. Minimum 2 clock cycles should be met before new RAS activation.
 3. Please refer to Mode Register Set table.

PACKAGING INFORMATION

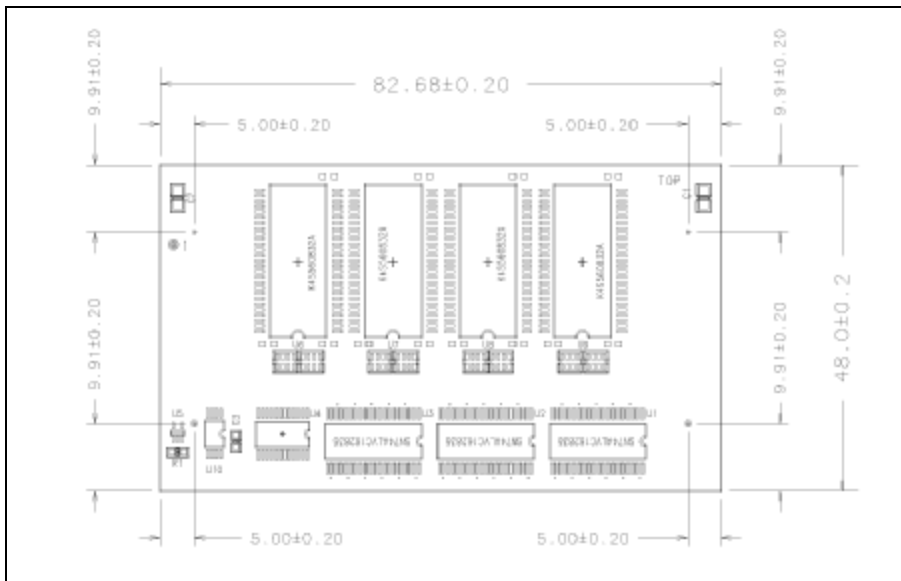
Unit : inch [mm]

Front –Side

TOLERANCE : ± 0.008 [± 0.20]



Rear-Side



ORDERING INFORMATION

| Part Number | Density | Org. | Package | Ref. | Vcc | MODE | MAX.frq |
|-----------------|----------|----------|---------------------|------|------|------|---------|
| HSD16M64F8K-10L | 128MByte | 16M x 64 | 120PIN STACKABLE | 4K | 3.3V | | 100Mhz |