

## 1V HIGH EFFICIENCY SYNCHRONOUS STEP UP CONVERTER

### 1 Features

- 0.6 TO 5.5V OPERATING INPUT VOLTAGE
- 1V START UP INPUT VOLTAGE
- INTERNAL SYNCHRONOUS RECTIFIER
- ZERO SHUT DOWN CURRENT
- 3.3V AND 5V FIXED OR ADJUSTABLE OUTPUT VOLTAGE (2V UP TO 5.2V)
- 120mΩ INTERNAL ACTIVE SWITCH
- LOW BATTERY VOLTAGE DETECTION
- REVERSE BATTERY PROTECTION

#### 1.1 Applications

- ONE TO THREE CELL BATTERY DEVICES
- PDA AND HAND HELD INSTRUMENTS
- CELLULAR PHONES - DIGITAL CORDLESS PHONE
- PAGERS
- GPS
- DIGITAL CAMERAS

Figure 1. Package

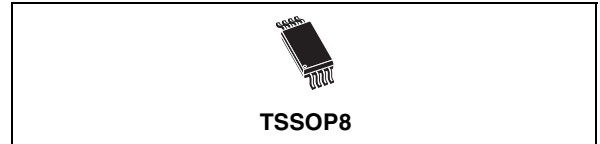


Table 1. Order Codes

Part Number	Package
L6920D	TSSOP8 Tube
L6920DTR	Tape & Reel

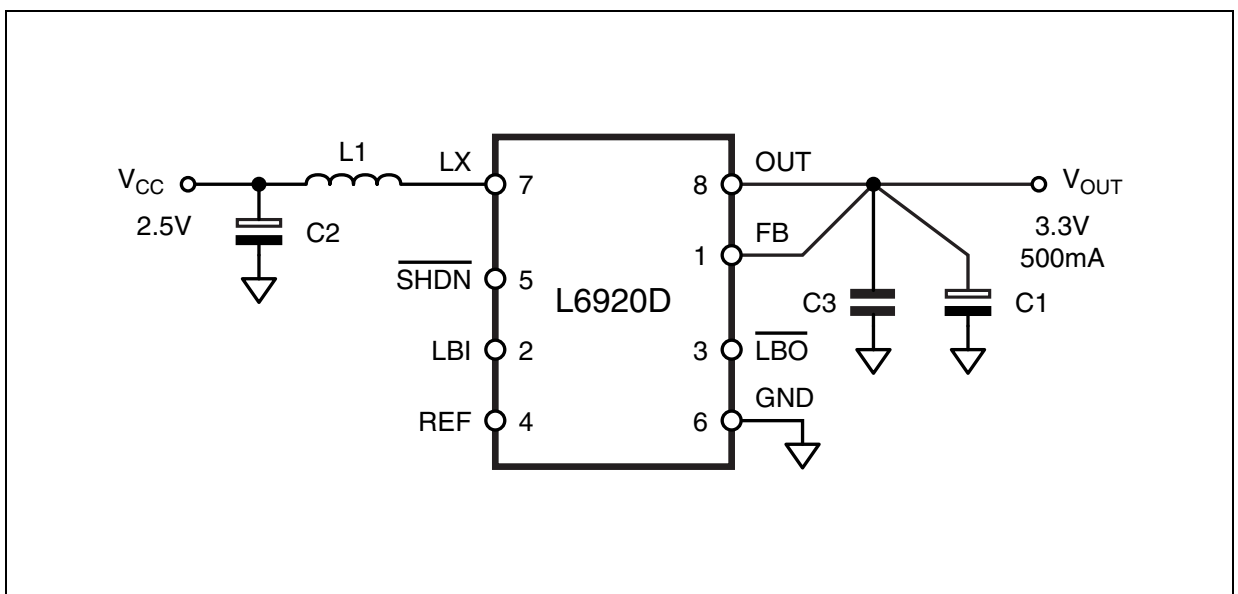
### 2 Description

The L6920 is a high efficiency step-up controller requiring only three external components to realize the conversion from the battery voltage to the selected output voltage.

The start up is guaranteed at 1V and the device is operating down to 0.6V.

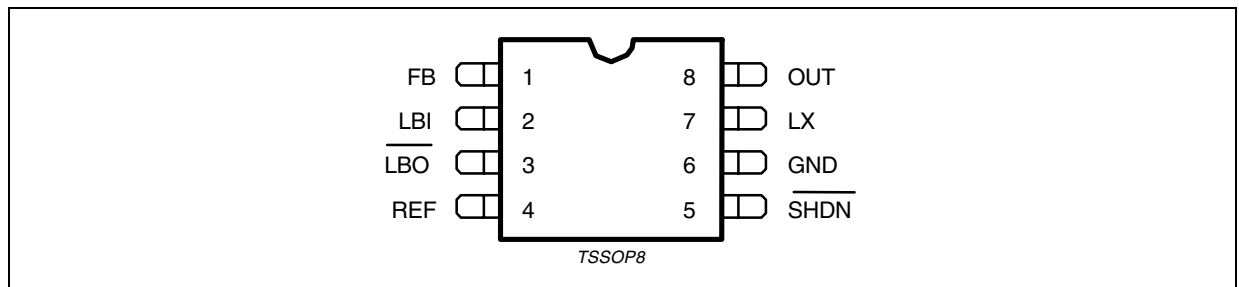
Internal synchronous rectifier is implemented with a 120mΩ P-channel MOSFET and, in order to improve the efficiency, a variable frequency control is implemented.

Figure 1. Application Circuit



**Table 1. Pin Description**

Pin	Name	Function
1	FB	Output voltage selector. Connect FB to GND for $V_{out}=5V$ or to OUT for $V_{out}=3.3V$ . Connect FB to an external resistor divider for adjustable output voltage (from 2V to 5.2V) [see R4 and R5, fig. 7].
2	LBI	Battery low voltage detector input. The internal threshold is set to 1.23V. A resistor divider is needed to adjust the desired low battery threshold: $V_{LBI} = 1.23V \cdot \left(1 + \frac{R1}{R2}\right)$ [see R1 and R2, fig. 7]
3	$\overline{LBO}$	Battery low voltage detector output. If the voltage at the LBI pin drops below the internal threshold typ. 1.23V, $\overline{LBO}$ goes low. The $\overline{LBO}$ is an open drain output and so a pull-up resistor (about 200K $\Omega$ ) has to be added for correct output setting [see R3, fig. 7].
4	REF	1.23V reference voltage. Bypass this output to GND with a 100nF capacitor for filtering high frequency noise. No capacitor is required for stability
5	$\overline{SHDN}$	Shutdown pin. When pin 5 is below 0.2V the device is in shutdown, when pin 5 is above 0.6V the device is operating.
6	GND	Ground pin
7	LX	Step-up inductor connection
8	OUT	Power OUTPUT pin

**Figure 2. Pin Connection (Top view)****Table 2. Absolute Maximum Ratings**

Symbol	Parameter	Value	Unit
$V_{ccmax}$	$V_{cc}$ to GND	6	V
	LBI, SHDN, FB to GND	6	V
$V_{out max}$	$V_{out}$ to GND	6	V

**Table 3. Thermal Data**

Symbol	Parameter	Value	Unit
$R_{th j-amb}$	Thermal Resistance Junction to Ambient	250	$^{\circ}C/W$
$T_j$	Maximum Junction Temperature	150	$^{\circ}C$

**Table 4. Electrical Characteristics**(V<sub>in</sub> = 2V, FB = GND, T<sub>amb</sub> = -40°C to 85°C and T<sub>j</sub> < 125°C unless otherwise specified)

Symbol	Parameter	Test Condition	Min.	Typ.	Max.	Unit
<b>V<sub>CC</sub> SECTION</b>						
V <sub>in</sub>	Minimum operating Input Voltage		0.6			V
V <sub>in</sub>	Minimum Start Up Input Voltage				1	V
I <sub>q</sub>	Quiescent Current	I <sub>l</sub> = 0 mA, FB = 1.4V, V <sub>out</sub> = 3.3V LBI = SHDN = 2V, T <sub>j</sub> = T <sub>amb</sub>		9	15	μA
		I <sub>l</sub> = 0 mA, FB = 1.4V, V <sub>out</sub> = 5V LBI = SHDN = 2V, T <sub>j</sub> = T <sub>amb</sub>		11	18	μA
I <sub>sd</sub>	Shut Down Current	V <sub>in</sub> = 5V, I <sub>l</sub> = 0 mA		0.1	1	μA
I <sub>rev</sub>	Reverse battery current	V <sub>in</sub> = -4V, T <sub>j</sub> = T <sub>amb</sub>		0.1	2	μA
<b>POWER SECTION</b>						
R <sub>on-N</sub>	Active switch ON resistance			120	250	mΩ
R <sub>on-P</sub>	Synchronous switch ON resistance			120	250	mΩ
<b>CONTROL SECTION</b>						
V <sub>out</sub>	Output voltage	FB = OUT, I <sub>l</sub> = 0 mA	3.2	3.3	3.4	V
		FB = GND, I <sub>l</sub> = 0 mA	4.9	5	5.1	V
	Output voltage range	External divider	2		5.2	V
V <sub>LBI</sub>	LBI threshold		1.18	1.23	1.27	V
		0°C < T <sub>j</sub> < 70°C	1.205	1.23	1.255	V
V <sub>LBO</sub>	$\overline{\text{LBO}}$ logic LOW	I <sub>l</sub> sink < 250μA		0.2	0.4	V
I <sub>lim</sub>	LX switch current limit		0.8	1	1.2	A
T <sub>onmax</sub>	Maximum on time	V <sub>out</sub> = 2V to 5.3V	3.75	5	6.25	μs
T <sub>offmin</sub>	Minimum off time	V <sub>out</sub> = 2V to 5.3V	0.75	1	1.25	μs
$\overline{\text{SHDN}}$	$\overline{\text{SHDN}}$ logic LOW				0.2	V
	$\overline{\text{SHDN}}$ logic HIGH		0.6			V
V <sub>ref</sub>	Reference Voltage		1.18	1.23	1.27	V

Figure 3. Efficiency vs. Output Current

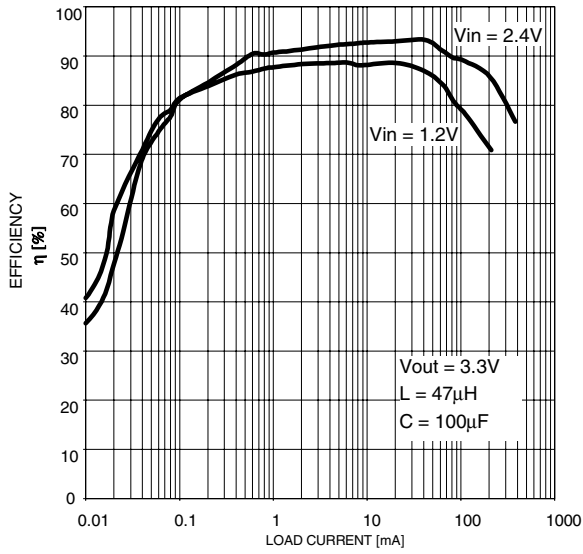


Figure 5. Startup Voltage vs Output Current

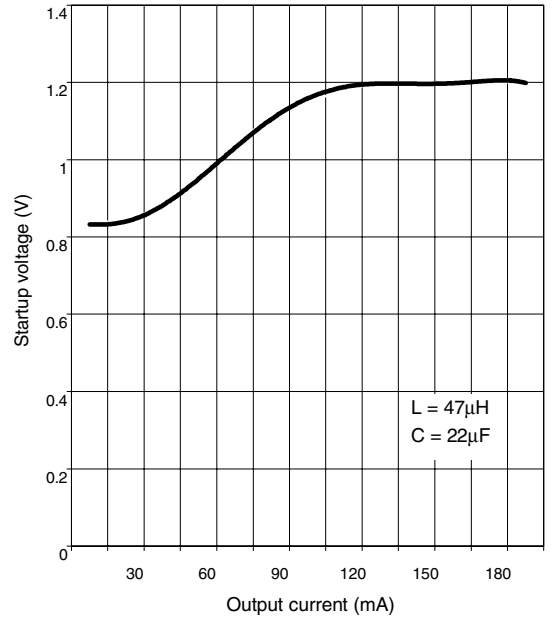
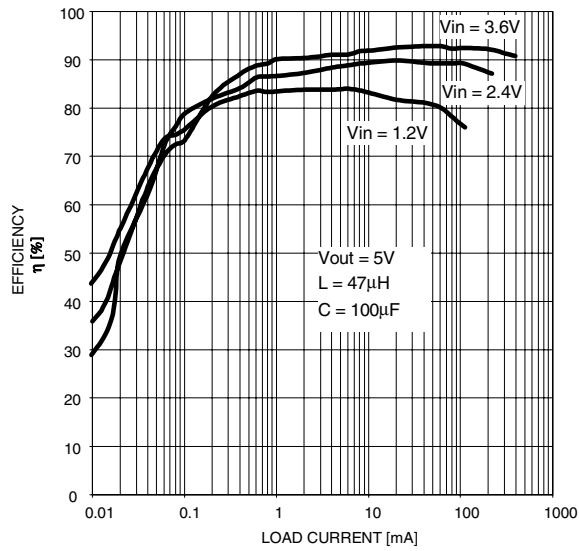


Figure 4. Efficiency vs. Output Current



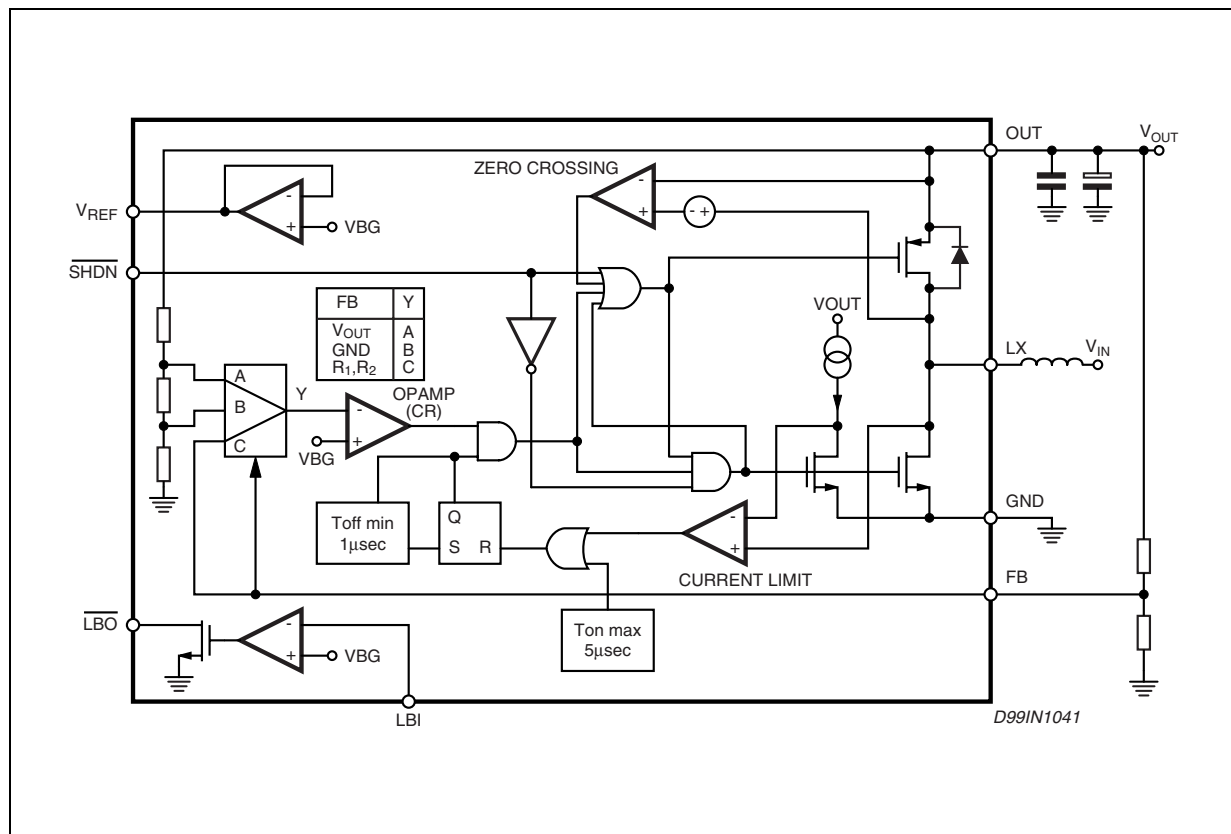
### 3 Detailed Description

The L6920 is a high efficiency, low voltage step-up DC/DC converter particularly suitable for 1 to 3 cells (Li-Ion/polymer, NiMH respectively) battery up conversion.

These performances are achieved via a strong reduction of quiescent current (10 $\mu$ A only) and adopting a synchronous rectification, that implies also a reduced cost in the application (no external diode required).

Operation is based on maximum ON time - minimum OFF time control, tailored by a current limit set to 1A. A simplified block diagram is shown here below.

**Figure 6. Simplified Block Diagram**



### 4 Principle of Operation

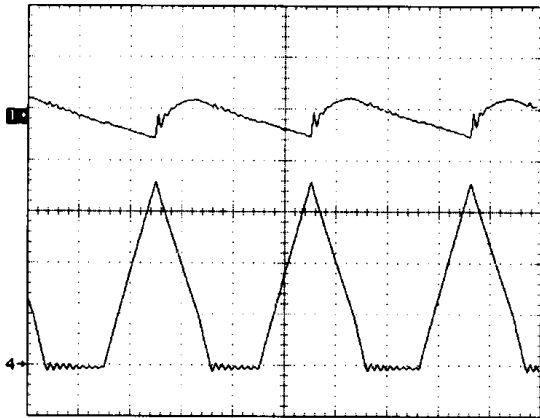
In L6920 the control is based on a comparator that continuously checks the status of output voltage.

If the output voltage is lower than the expected value, the control function of the L6920 directs the energy stored in the inductor to be transferred to the load. This is accomplished by alternating between two basic steps:

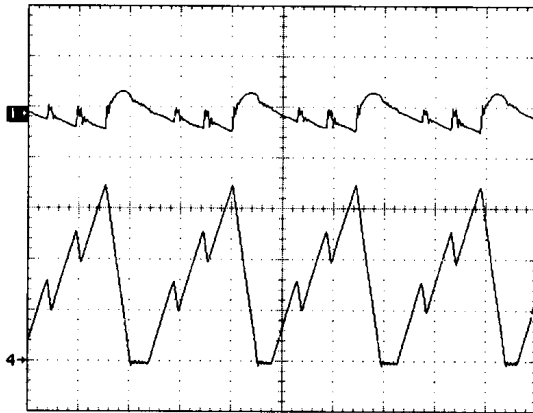
- TON phase: the energy is transferred from the battery to the inductor by shorting LX node to ground via the N-channel power switch. The switch is turned off if the current flowing in the inductor reaches 1A or after a maximum on time set to 5 $\mu$ s.
- TOFF phase: the energy stored in the inductor is transferred to the load through the synchronous switch for at least a minimum off time equal to 1 $\mu$ s. After this, the synchronous switch is turned off as soon as the output voltage goes lower than the regulated voltage or the current flowing in the inductor goes down to zero.

So, in case of light load, the device works in PFM mode, as shown in figures 7 to 10.

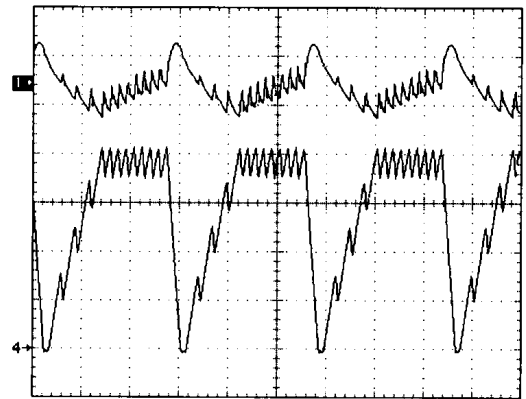
**Figure 7. PFM mode Condition:  $V_{out} = 5V$ ;  $V_{in} = 1.5V$ .  
Trace1:  $V_{out}$  (50mV~/div) Trace 4:  $I_L$  (100mA/div)  
Time div.: 5 $\mu$ s/div**



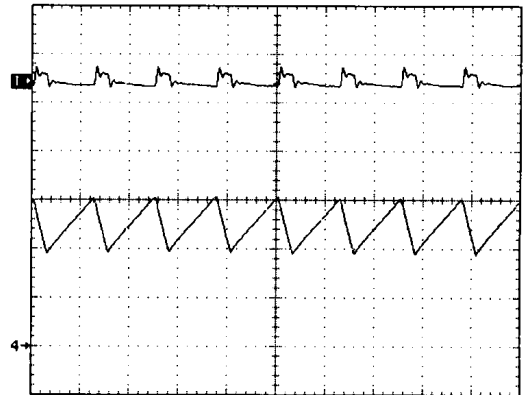
**Figure 8. Heavier load - Train pulses overlapping.  
Trace1:  $V_{out}$  (100mV~/div) Trace 4:  $I_L$  (200mA/div)  
Time div.: 10  $\mu$ s/div**



**Figure 9. Heavy load - Inductor current ripples below  $I_{lim}$  Trace1:  $V_{out}$  (100mV~/div) Trace 4:  $I_L$  (200mA/div) Time div.: 20  $\mu$ s/div**



**Figure 10. Heavy load and High ESR. Regulation falls in continuous mode of operation. Trace1:  $V_{out}$  (100mV~/div) Trace 4:  $I_L$  (200mA/div). Time div.: 5  $\mu$ s/div**



When Iload is heavier, the pulse trains are overlapped. Figures 7 - 8 show some possible behaviors.

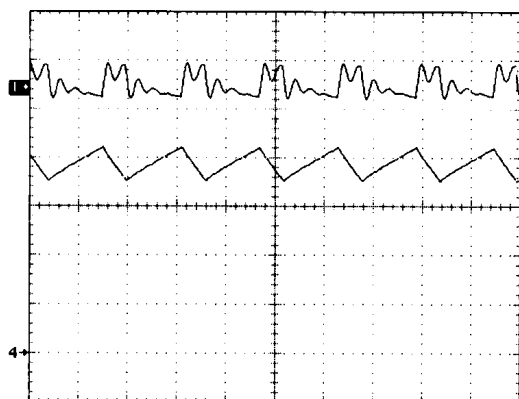
Considering that current in the inductor is limited to 1A, the maximum load current is defined by the following relationship:

$$I_{load\_lim} = \frac{V_{in}}{V_{out}} \cdot \left( I_{lim} - T_{off\ min} \cdot \frac{V_{out} - V_{in}}{2 \cdot L} \right) \cdot \eta \quad \text{eq. (1)}$$

Where  $\eta$  is the efficiency and  $I_{lim} = 1A$ .

Of course, if Iload is greater than Iload\_lim the regulation is lost (figure 11).

**Figure 11. No regulation.  $I_{load} > I_{load\_lim}$**   
**Trace1:  $V_{out}$  (100mV~/div) Trace 4:  $I_L$  (200mA/div).**  
**Time div.: 5  $\mu$ s/div**



#### 4.1 Start-up

One of the key features of L6920 is the startup at supply voltage down to 1V (please see the diagram in Figure 5. in case of heavy load).

The device leaves the startup mode of operation as soon as  $V_{OUT}$  goes over 1.4V. During startup, the synchronous switch is off and the energy is transferred to the load through its intrinsic body diode.

The N-channel switches with a very low  $R_{DSon}$  thanks to an internal charge pump used to bias the power mos gate. Because of this modified behavior, TON/TOFF times are lengthened. Current limit and zero crossing detection are still available.

#### 4.2 Shutdown

In shutdown mode ( $\overline{SHDN}$  pulled low) all internal circuitries are turned off, minimizing the current provided by the battery ( $I_{SHDN} < 100$  nA, in typical case). Both switches are turned off, and the low battery comparator output is forced in high impedance state.

The synchronous switch body diode causes a parasitic path between power supply and output that can't be avoided also in shutdown.

#### 4.3 Low battery detection

The L6920 includes a low battery detector comparator. Threshold is  $V_{REF}$  voltage and a 1.3% hysteresis is added to avoid oscillations when input crosses the threshold slowly. The  $LBO$  is an open drain output so a pull up resistor is required for a proper use.

#### 4.4 Reverse polarity

A protection circuit has been implemented to avoid that L6920 and the battery are destroyed in case of wrong battery insertion.

In addition, this circuit has been designed so that the current required by the battery is zero also in reverse polarity.

## 5 Application Information

#### 5.1 Output voltage selection

Output voltage must be selected acting on FB pin. Three choices are available: fixed 3.3V, 5V or adjustable output set via an external resistor divider.

**Table 5. Output Voltage Selection**

$V_{OUT} = 3.3V$	FB pin connected to OUT (see application circuit)
$V_{OUT} = 5V$	FB pin connected to GND
$2V \leq V_{OUT} \leq 5.2V$	FB pin connected to a resistive divider $V_{OUT} = 1.23V \left( 1 + \frac{R4}{R5} \right)$

Figure 12. Demoboard Circuit

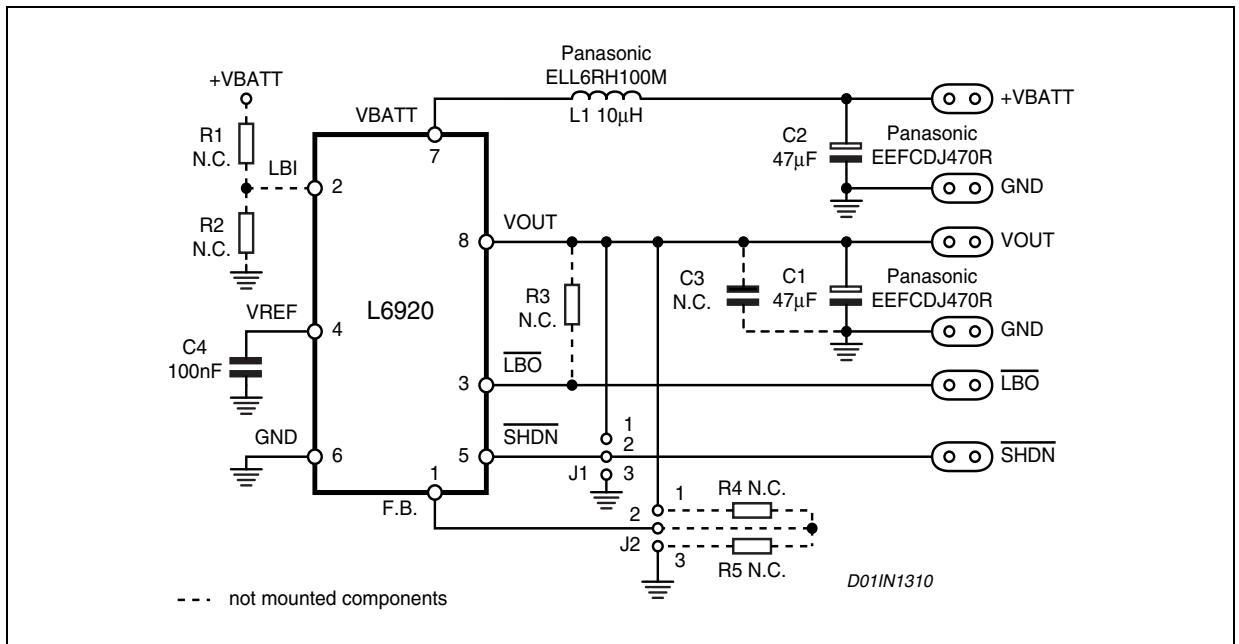


Table 6.

Jumper	Position	Function
J1	1-2	Device enabled
	2-3	Device disabled
J2	None	Adjustable using R4 and R5 [not mounted]
	1-2	3.3V output voltage
	2-3	5V output voltage

R4, R5 should be selected in the range of 100kΩ - 10MΩ to minimize consumption and error due to current sunk by FB pin (few nA).

### 5.2 Output capacitor selection

The output capacitor affects both efficiency and output ripple so its choice has to be considered with particular care.

The capacitance value should be in the range of about 10µF-100µF.

An additional, smaller, low ESR capacitor can be in parallel for high frequency filtering. A typical value can be around 1µF.

If very high performances, in terms of efficiency and output voltage ripple, are required, a very low ESR capacitor has to be chosen.

Ceramic capacitors are the lowest ESR but they are very expensive.

Other possibilities are low-ESR tantalum capacitors, available from KEMET, AVX and other sources. POSCAP capacitors from SANYO and polymeric capacitors from PANASONIC are also good.

Below there is a list of some capacitors suppliers. The cap values and rated voltages are only a suggested possibility



**Table 7. Capacitors distributors main list**

Manufacturer	Series	Cap Value ( $\mu\text{F}$ )	Rated Voltage (V)	ESR ( $\text{m}\Omega$ )
AVX	TPS	15 to 470	6.3	50 to 1500
KEMET	T510/T494/ T495	10 to 470	6	30 to 1000
PANASONIC	EEFCD	22 to 47	6.3	50 to 700
SANYO POSCAP	TPA/B/C	22 to 230	6.3	40 to 80
SPRAGUE	595D	100 to 390	6.3	160 to 700

### 5.3 Inductor selection

Usually, inductors ranging between  $5\mu\text{H}$  to  $40\mu\text{H}$  satisfy most of the applications.

Small value inductors have smaller physical size and guarantee a faster response to load transient but in steady state condition a bigger ripple on output voltage is generated. In fact the output ripple voltage is given by  $I_{\text{peak}}$  multiplied by ESR. Furthermore, as shown in equation (1), inductor size affects also the maximum current deliverable to the load. Lastly, a low series resistance is suggested if very high efficiency values are needed. Anyway, the saturation current of the choke should be higher than the peak current limit of the device (1A).

Good surface mounting inductors are available from COILCRAFTS, COILTRONICS, MURATA and other sources. In the following table are listed some suggested components.

**Table 8. Inductors distributors main list**

Manufacturer	Series	Inductor Value ( $\mu\text{H}$ )	Saturation Current (A)
Coilcraft	DO1813HC	22 to 33	1 to 1.2
	DO1608	4.7 to 15	0.9 to 1.5
Coiltronics	UP1B	22 to 33	1 to 1.2
	TP3	4.7 to 15	0.97 to 1.6
BI	HM76-2	22 to 33	1 to 1.2
	HM76-1	4.7 to 10	1 to 1.5
Murata	LQN6C	10 to 22	1.2 to 1.7
Panasonic	ELL6SH	10 to 22	0.9 to 1.5
	ELL6RH	5.1 to 10	11 to 1.55
Sumida	CR43	4.7 to 10	0.84 to 1.15

### 5.4 Layout Guidelines

The board layout is very important in order to minimize noise, high frequency resonance problems and electromagnetic interference.

It is essential to keep as small as possible the high switching current circulating paths to reduce radiation and resonance problems. So, the output and input cap should be very close to the device.

The external resistor dividers, if used, should be as close as possible to the pins of the device (FB and LBI) and as far as possible from the high current circulating paths, to avoid pick up noise.

Large traces for high current paths and an extended groundplane, help to reduce the noise and increase the efficiency.

For an example of recommended layout see the following evaluation board.

Figure 13. Demoboard Components (Top side).

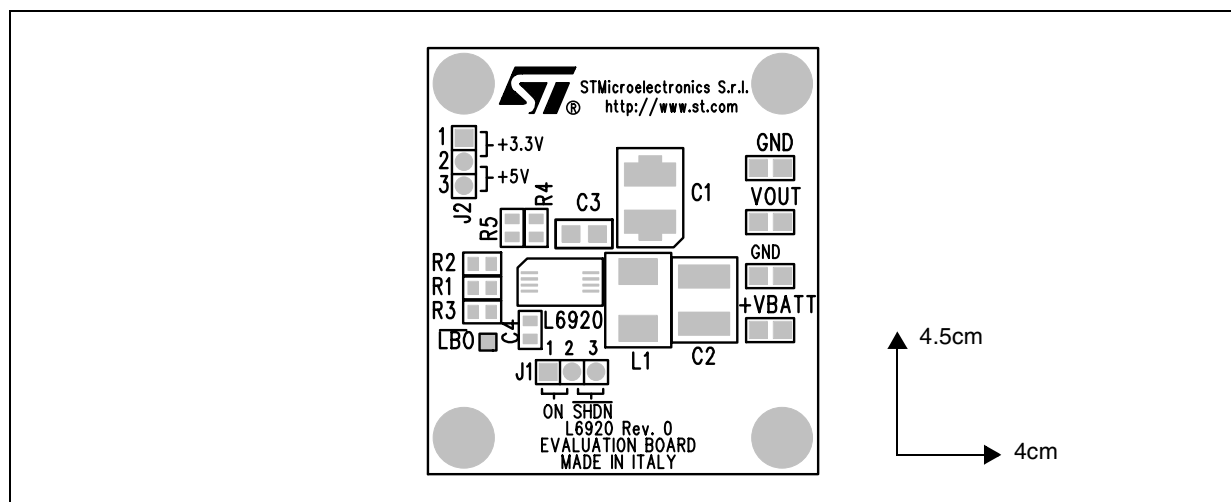


Figure 14. Demoboard Layout (Top side).

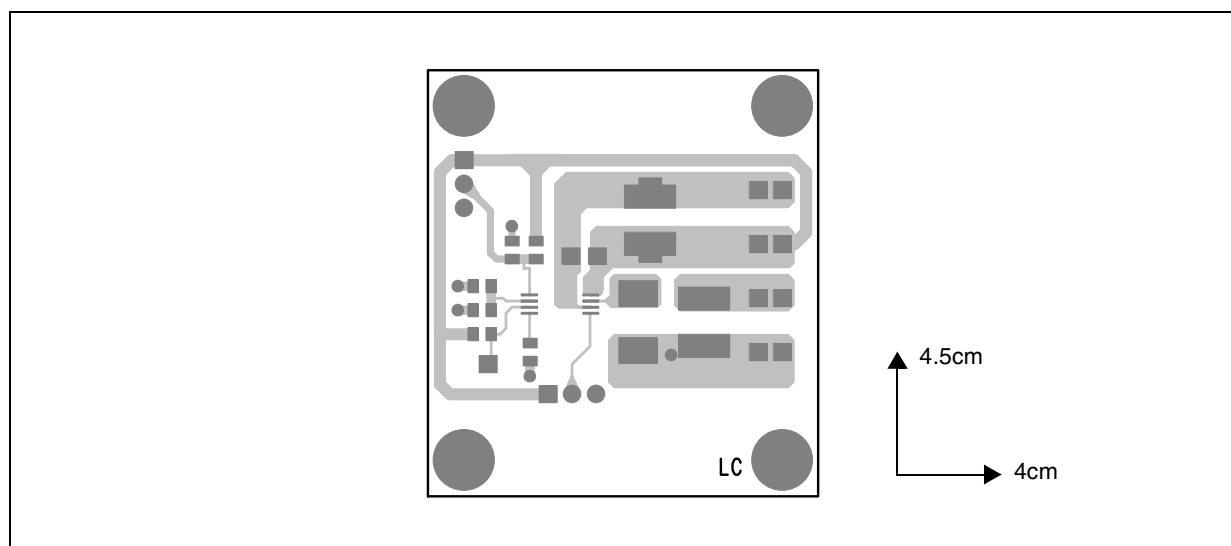
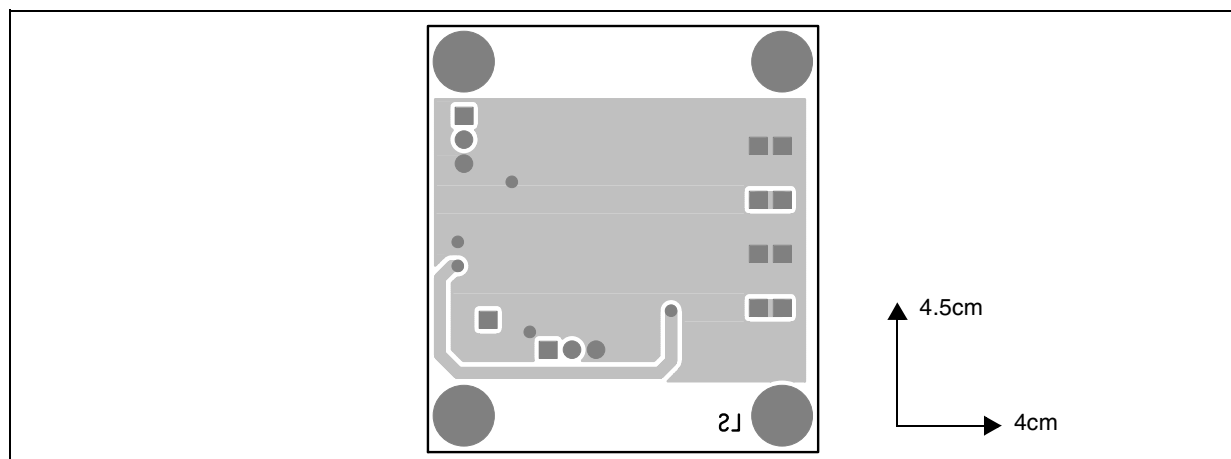


Figure 15. Demoboard Layout (Bottom side).



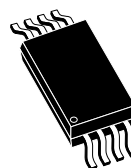
## 6 Package Information

Figure 16. TSSOP8 Mechanical Data & Package Dimensions

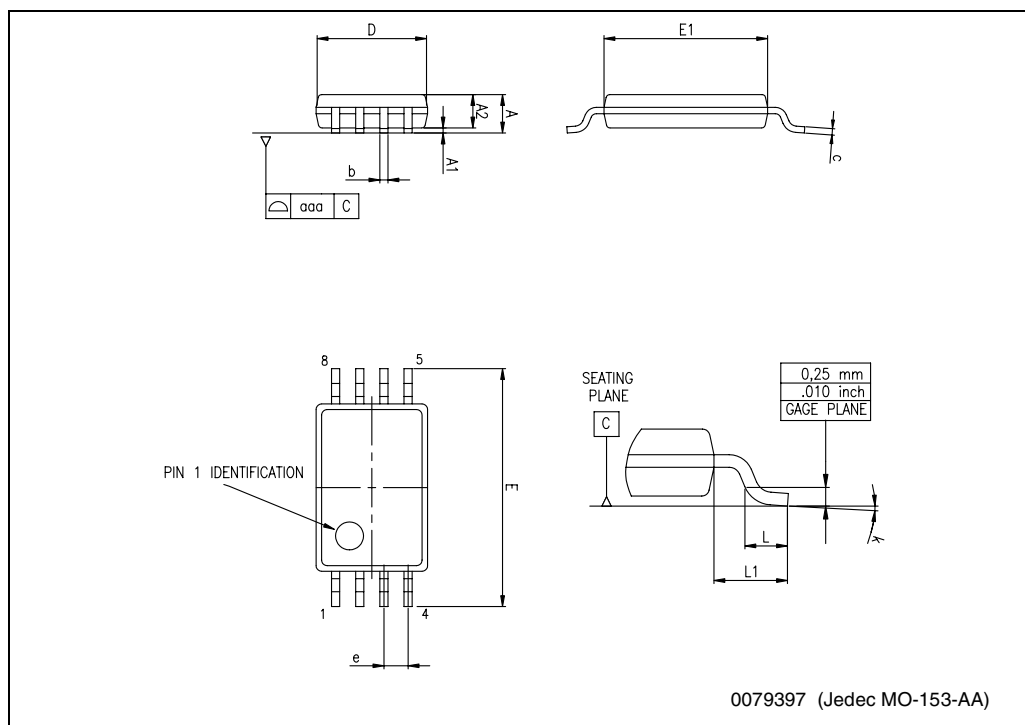
DIM.	mm			inch		
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
A			1.20			0.047
A1	0.050		0.150	0.002		0.006
A2	0.800	1.000	1.050	0.031	0.039	0.041
b	0.190		0.300	0.007		0.012
c	0.090		0.200	0.003		0.008
D (1)	2.900	3.000	3.100	0.114	0.118	0.122
E	6.200	6.400	6.650	0.244	0.252	0.260
E1 (1)	4.300	4.400	4.500	0.169	0.173	0.177
e		0.650			0.026	
L	0.450	0.600	0.750	0.018	0.024	0.027
L1		1.000			0.039	
k	0° (min.) 8° (max.)					
aaa			0.100			0.004

Note: 1. D and F does not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm (.006inch) per side.

### OUTLINE AND MECHANICAL DATA



### TSSOP8 (Body 4.4mm)



## 7 Revision History

**Table 9. Revision History**

Date	Revision	Description of Changes
May 2003	1	First Issue.
February 2005	2	Modified the max. value of the $I_{SD}$ parameter in the Table 4 pag. 3.

Information furnished is believed to be accurate and reliable. However, STMicroelectronics assumes no responsibility for the consequences of use of such information nor for any infringement of patents or other rights of third parties which may result from its use. No license is granted by implication or otherwise under any patent or patent rights of STMicroelectronics. Specifications mentioned in this publication are subject to change without notice. This publication supersedes and replaces all information previously supplied. STMicroelectronics products are not authorized for use as critical components in life support devices or systems without express written approval of STMicroelectronics.

The ST logo is a registered trademark of STMicroelectronics.  
All other names are the property of their respective owners

© 2005 STMicroelectronics - All rights reserved

STMicroelectronics group of companies

Australia - Belgium - Brazil - Canada - China - Czech Republic - Finland - France - Germany - Hong Kong - India - Israel - Italy - Japan - Malaysia - Malta - Morocco - Singapore - Spain - Sweden - Switzerland - United Kingdom - United States of America

[www.st.com](http://www.st.com)