



SANYO Semiconductors

DATA SHEET

LC87F7LC8A — CMOS IC FROM 128K byte, RAM 4096 byte on-chip 8-bit 1-chip Microcontroller

Overview

The SANYO LC87F7LC8A is an 8-bit microcomputer that, centered around a CPU running at a minimum bus cycle time of 83.3ns, integrates on a single chip a number of hardware features such as 128K-byte flash ROM (onboard programmable), 4096-byte RAM, an on-chip debugger, a LCD controller/driver, sophisticated 16-bit timer/counter (may be divided into 8-bit timers), a 16-bit timer/counter (may be divided into 8-bit timers/counters or 8-bit PWMs), four 8-bit timers with a prescaler, a 16-bit timer with a prescaler (may be divided into 8-bit timers), a base timer serving as a time-of-day clock, a day and time counter, a synchronous SIO interface (with automatic block transmission/reception capabilities), an asynchronous/synchronous SIO interface, a UART interface (full duplex), an 8-bit 15-channel AD converter, two 12-bit PWM channels, a high-speed clock counter, a system clock frequency divider, a small signal detector, ROM correction function, remote control receive function, and a 28-source 10-vector interrupt feature.

Features

■Flash ROM

- Capable of on-board-programming with wide range, 3.0 to 5.5V, of voltage source
- Block-erasable in 128byte units
- 131072 × 8 bits (LC87F7LC8A)

■RAM

- 4096 × 9 bits (LC87F7LC8A)

■Minimum Bus Cycle Time

- 83.3ns (12MHz) $V_{DD}=3.0$ to 5.5V
- 125ns (8MHz) $V_{DD}=2.5$ to 3.0V
- 250ns (4MHz) $V_{DD}=2.2$ to 2.5V

Note: The bus cycle time here refers to the ROM read speed.

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■ Minimum Instruction Cycle Time (tCYC)

- 250ns (12MHz) $V_{DD}=3.0$ to $5.5V$
- 375ns (8MHz) $V_{DD}=2.5$ to $3.0V$
- 750ns (4MHz) $V_{DD}=2.2$ to $2.5V$

■ Ports

- Normal withstand voltage I/O ports
 - Ports whose I/O direction can be designated in 1 bit units 27(P1n, P30 to P35, P70 to P73, P8n, XT2)
 - Ports whose I/O direction can be designated in 4 bit units 8(P0n)
- Normal withstand voltage input port 1(XT1)
- LCD ports
 - Segment output 48(S00 to S47)
 - Common output 4(COM0 to COM3)
 - Bias terminals for LCD driver 3(V1 to V3)
- Other functions
 - Input/output ports 48(PAn, PBn, PCn, PDn, PEn, PFn)
 - Input ports 7(PLn)
- Dedicated oscillator ports 2(CF1, CF2)
- Reset pin 1(\overline{RES})
- Power supply 6(V_{SS1} to V_{SS3} , V_{DD1} to V_{DD3})

■ LCD Controller

- 1) Seven display modes are available (static, 1/2, 1/3, 1/4 duty \times 1/2, 1/3 bias)
- 2) Segment output and common output can be switched to general purpose input/output ports

■ Small Signal Detection (MIC signals etc)

- 1) Counts pulses with the level which is greater than a preset value
- 2) 2-bit counter

■ Timers

- Timer 0: 16-bit timer/counter with two capture registers.
 - Mode 0: 8-bit timer with an 8-bit programmable prescaler (with two 8-bit capture registers) \times 2 channels
 - Mode 1: 8-bit timer with an 8-bit programmable prescaler (with two 8-bit capture registers) + 8-bit counter (with two 8-bit capture registers)
 - Mode 2: 16-bit timer with an 8-bit programmable prescaler (with two 16-bit capture registers)
 - Mode 3: 16-bit counter (with two 16-bit capture registers)
- Timer1: 16-bit timer/counter that supports PWM/toggle outputs
 - Mode 0: 8-bit timer with an 8-bit prescaler (with toggle outputs) + 8-bit timer/counter with an 8-bit prescaler (with toggle outputs)
 - Mode 1: 8-bit PWM with an 8-bit prescaler \times 2 channels
 - Mode 2: 16-bit timer/counter with an 8-bit prescaler (with toggle outputs) (toggle outputs also possible from the lower-order 8 bits)
 - Mode 3: 16-bit timer with an 8-bit prescaler (with toggle outputs) (The lower-order 8 bits can be used as PWM.)
- Timer4: 8-bit timer with 6-bit prescaler
- Timer5: 8-bit timer with 6-bit prescaler
- Timer6: 8-bit timer with 6-bit prescaler (with toggle output)
- Timer7: 8-bit timer with 6-bit prescaler (with toggle output)
- Timer8: 16-bit timer
 - Mode 0: 8-bit timer with an 8-bit prescaler \times 2 channels (with toggle output)
 - Mode 1: 16-bit timer with an 8-bit prescaler (with toggle output)
- Base Timer
 - 1) The clock is selectable from the subclock (32.768kHz crystal oscillation), system clock, and timer 0 prescaler output.
 - 2) Interrupts programmable in 5 different time schemes
- Day and time counter
 - 1) Using with a base timer, it can be used as 65000 day + minute + second counter.

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■High-speed Clock Counter

- 1) Can count clocks with a maximum clock rate of 20MHz (at a main clock of 10MHz).
- 2) Can generate output real-time.

■SIO

• SIO0: 8-bit synchronous serial interface

- 1) LSB first/MSB first is selectable
- 2) Built-in 8-bit baudrate generator (maximum transfer clock cycle=4/3tCYC)
- 3) Automatic continuous data transmission (1 to 256 bits specifiable in 1 bit units, suspension and resumption of data transmission possible in 1 byte units)

• SIO1: 8-bit asynchronous/synchronous serial interface

- Mode 0: Synchronous 8-bit serial I/O (2- or 3-wire configuration, 2 to 512 tCYC transfer clocks)
Mode 1: Asynchronous serial I/O (half-duplex, 8 data bits, 1 stop bit, 8 to 2048 tCYC baudrates)
Mode 2: Bus mode 1 (start bit, 8 data bits, 2 to 512 tCYC transfer clocks)
Mode 3: Bus mode 2 (start detect, 8 data bits, stop detect)

■UART

- 1) Full duplex
- 2) 7/8/9 bit data bits selectable
- 3) 1 stop bit (2-bit in continuous data transmission)
- 4) Built-in baudrate generator

■AD Converter

- 8 bits × 15 channels

■PWM

- Multi frequency 12-bit PWM × 2 channels

■Remote Control Receiver Circuit

- 1) Noise rejection function (Units of noise rejection filter: about 120μs, when selecting a 32.768kHz crystal oscillator as a clock)
- 2) Supporting reception formats with a guide-pulse of half-clock/clock/none.
- 3) Determines a end of reception by detecting a no-signal periods (No carrier).
(Supports same reception format with a different bit length.)
- 4) X'tal HOLD mode release function

■Watchdog Timer

- 1) External RC watchdog timer
- 2) Interrupt and reset signals selectable

■Clock Output Function

- 1) Able to output selected oscillation clock 1/1, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64 as system clock.
- 2) Able to output oscillation clock of sub clock.

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■ Interrupts

- 28 sources, 10 vector addresses

- 1) Provides three levels (low (L), high (H), and highest (X)) of multiplex interrupt control. Any interrupt requests of the level equal to or lower than the current interrupt are not accepted.
- 2) When interrupt requests to two or more vector addresses occur at the same time, the interrupt of the highest level takes precedence over the other interrupts. For interrupts of the same level, the interrupt into the smallest vector address takes precedence.

No.	Vector Address	Level	Interrupt Source
1	00003H	X or L	INT0
2	0000BH	X or L	INT1
3	00013H	H or L	INT2/T0L/INT4/remote control receiver
4	0001BH	H or L	INT3/base timer/INT5
5	00023H	H or L	T0H/INT6
6	0002BH	H or L	T1L/T1H/INT7
7	00033H	H or L	SIO0/UART1 receive/T8L/T8H
8	0003BH	H or L	SIO1/UART1 transmit
9	00043H	H or L	ADC/MIC/T6/T7/PWM4,5
10	0004BH	H or L	Port 0/T4/T5

- Priority levels $X > H > L$
- Of interrupts of the same level, the one with the smallest vector address takes precedence.

- IFLG (List of interrupt source flag function)

- 1) Shows a list of interrupt source flags that caused a branching to a particular vector address (shown in the diagram above).

■ Subroutine Stack Levels

- 2048 levels (the stack is allocated in RAM)

■ High-speed Multiplication/Division Instructions

- 16-bits \times 8-bits (5 tCYC execution time)
- 24-bits \times 16-bits (12 tCYC execution time)
- 16-bits \div 8-bits (8 tCYC execution time)
- 24-bits \div 16-bits (12 tCYC execution time)

■ Oscillation Circuits

- RC oscillation circuit (internal): For system clock
- CF oscillation circuit: For system clock, with internal Rf, external Rd
- Crystal oscillation circuit: For low-speed system clock, with internal Rf, external Rd
- Frequency variable RC oscillation circuit (internal): For system clock
 - 1) Adjustable in $\pm 4\%$ (typ.) step from a selected center frequency.
 - 2) Measures oscillation clock using a input signal from XT1 as a reference.

■ System Clock Divider Function

- Can run on low current.
- The minimum instruction cycle selectable from 300ns, 600ns, 1.2 μ s, 2.4 μ s, 4.8 μ s, 9.6 μ s, 19.2 μ s, 38.4 μ s, and 76.8 μ s (at a main clock rate of 10MHz).

LC87F7LC8A

■ Standby Function

- HALT mode: Halts instruction execution while allowing the peripheral circuits to continue operation. (Some parts of the serial transfer function stops operation.)
 - 1) Oscillation is not halted automatically.
 - 2) Canceled by a system reset or occurrence of an interrupt
- HOLD mode: Suspends instruction execution and the operation of the peripheral circuits.
 - 1) The CF, RC, X'tal, and frequency variable RC oscillators automatically stop operation.
 - 2) There are three ways of resetting the HOLD mode.
 - (1) Setting the reset pin to the low level
 - (2) Setting at least one of the INT0, INT1, INT2, INT4, and INT5 pins to the specified level
 - (3) Having an interrupt source established at port 0
- X'tal HOLD mode: Suspends instruction execution and the operation of the peripheral circuits except the base timer and the remote control receiver circuit.
 - 1) The CF, RC, and frequency variable RC oscillators automatically stop operation.
 - 2) The state of crystal oscillation established when the X'tal HOLD mode is entered is retained.
 - 3) There are five ways of resetting the X'tal HOLD mode.
 - (1) Setting the reset pin to the low level
 - (2) Setting at least one of the INT0, INT1, INT2, INT4, and INT5 pins to the specified level
 - (3) Having an interrupt source established at port 0
 - (4) Having an interrupt source established in the base timer circuit
 - (5) Having an interrupt source established in the remote control receiver circuit

■ ROM Correction Function

- Executes the correction program on detection of a match with the program counter value.
- Correction program area size: 128 bytes

■ On-chip Debugger

- Supports software debugging with the IC mounted on the target board.

■ Package Form

- QIP100E(14×20): Lead-free type
- TQFP100(14×14): Lead-free type

■ Development Tools

- On-chip Debugger: TCB87-TypeA or TCB87-TypeB + LC87F7LC8A

■ Flash ROM Programming boards

Package	Programming Boards
QIP100E(14×20)	W87FQ100
TQFP100(14×14)	W87FSQ100

■ Flash ROM Programmer

Maker	Model	Supported version (Note)	Device
Flash Support Group, Inc. (Single)	AF9708/AF9709/AF9709B (including product of Ando Electric Co., Ltd.)	After 02.54	LC87F75C8A
Flash Support Group, Inc. (Gang)	AF9723 (Main body) (including product of Ando Electric Co., Ltd.)	After 02.03D	LC87F5JC8A
	AF9833 (Unit) (including product of Ando Electric Co., Ltd.)	After 01.82G	
SANYO	SKK (SANYO FWS)	Application Version 1.03	LC87F7LC8A
		Chip Data Version 2.05	

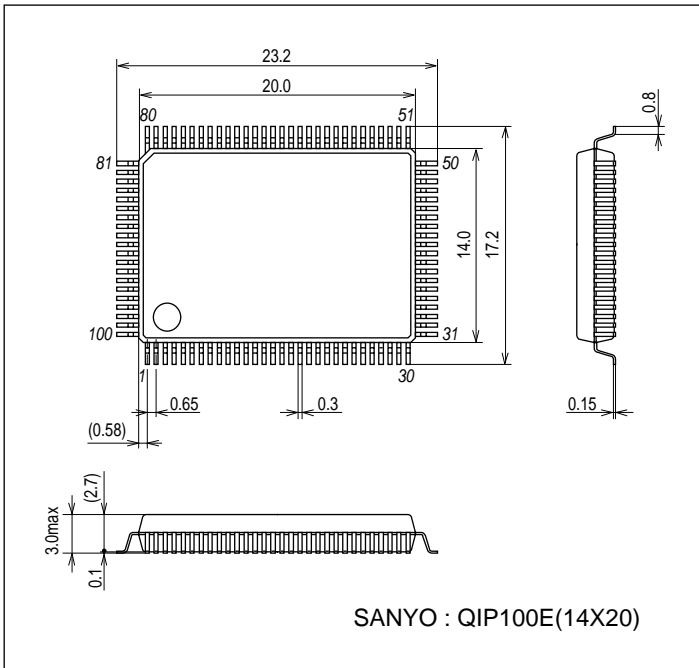
Note: Please check the latest version.

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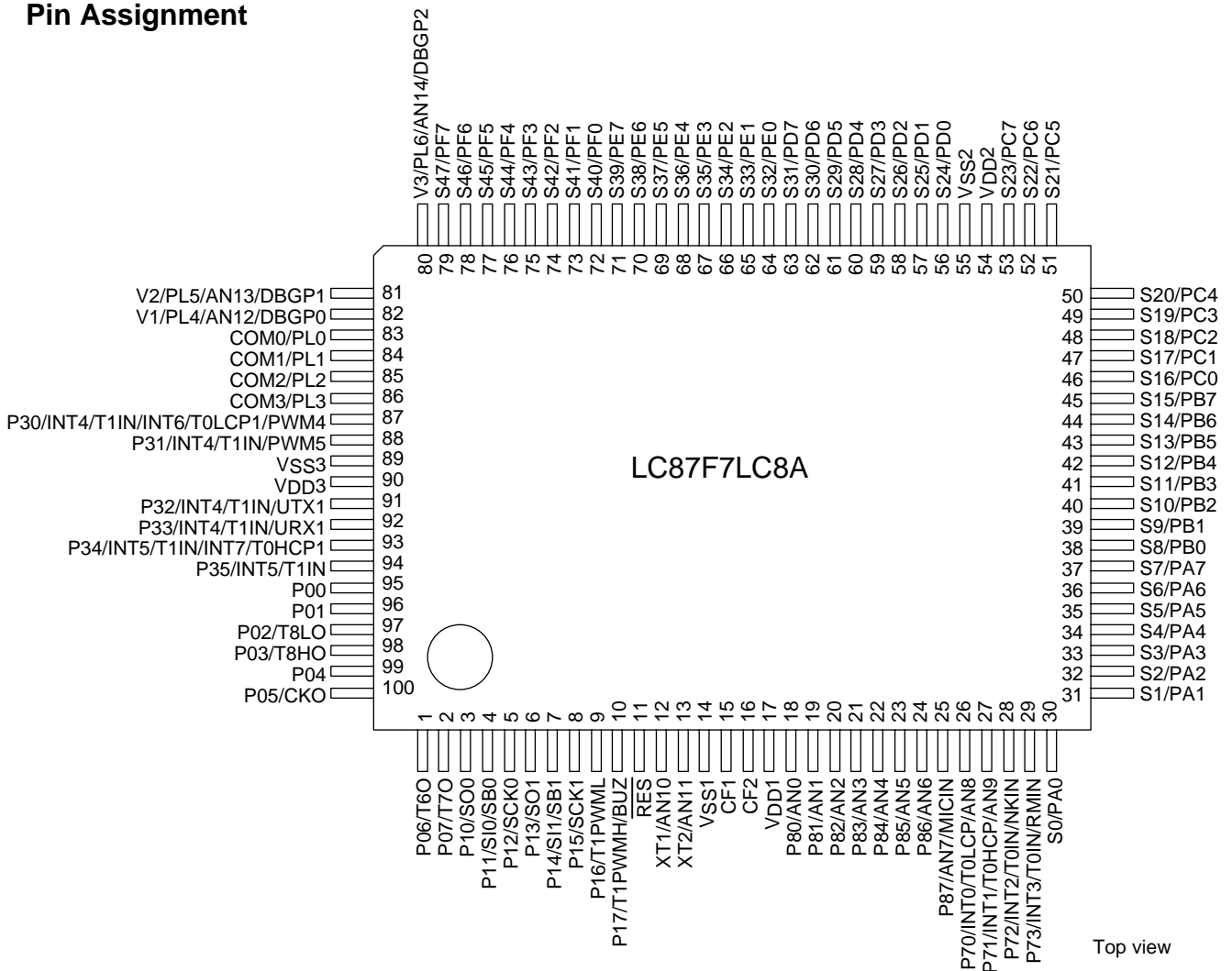
Package Dimensions

unit : mm (typ)

3151A



Pin Assignment



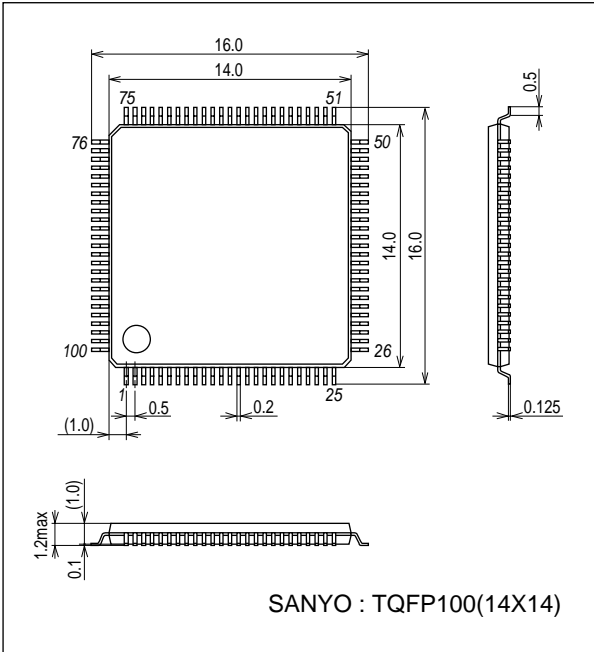
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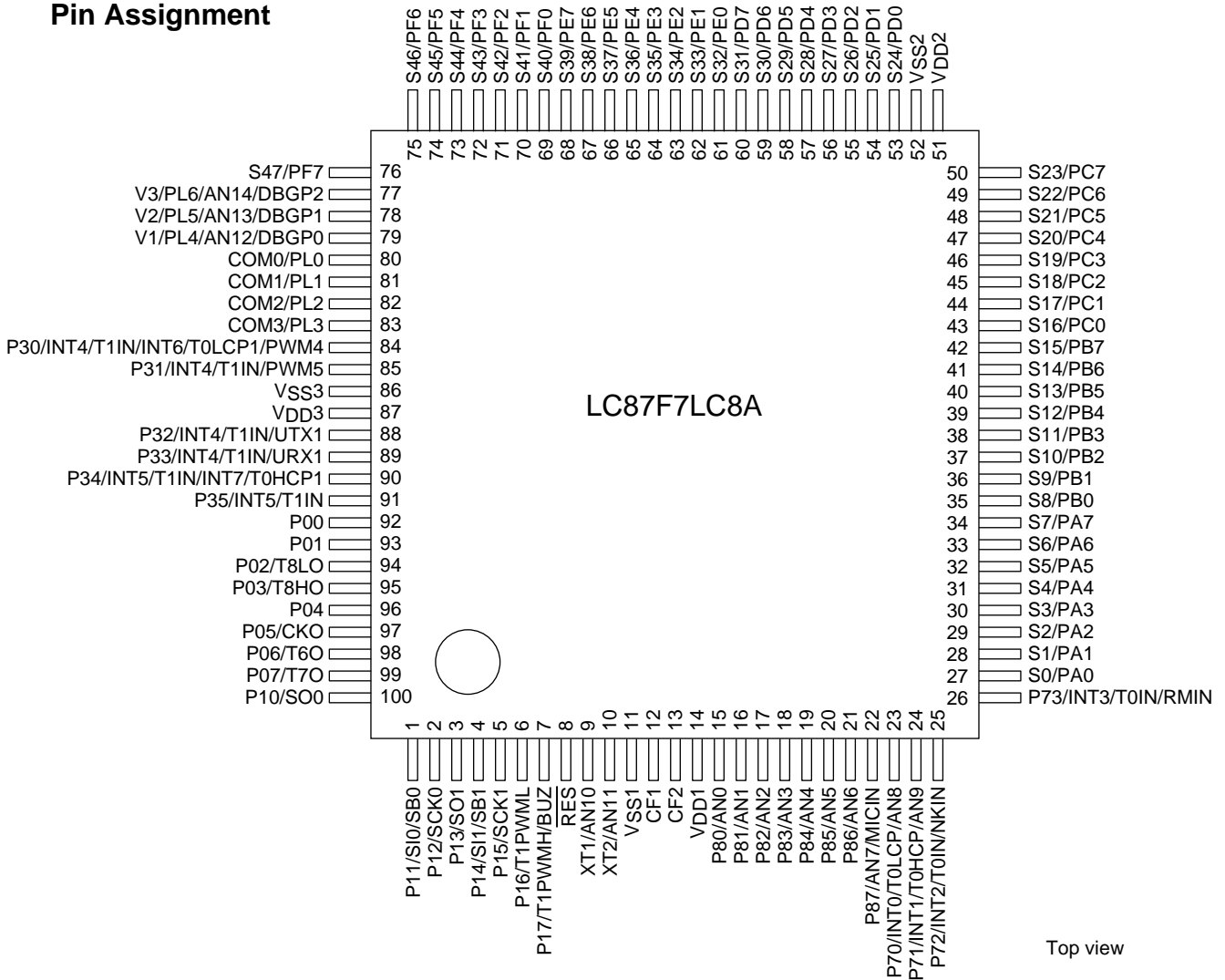
Package Dimensions

unit : mm (typ)

3274



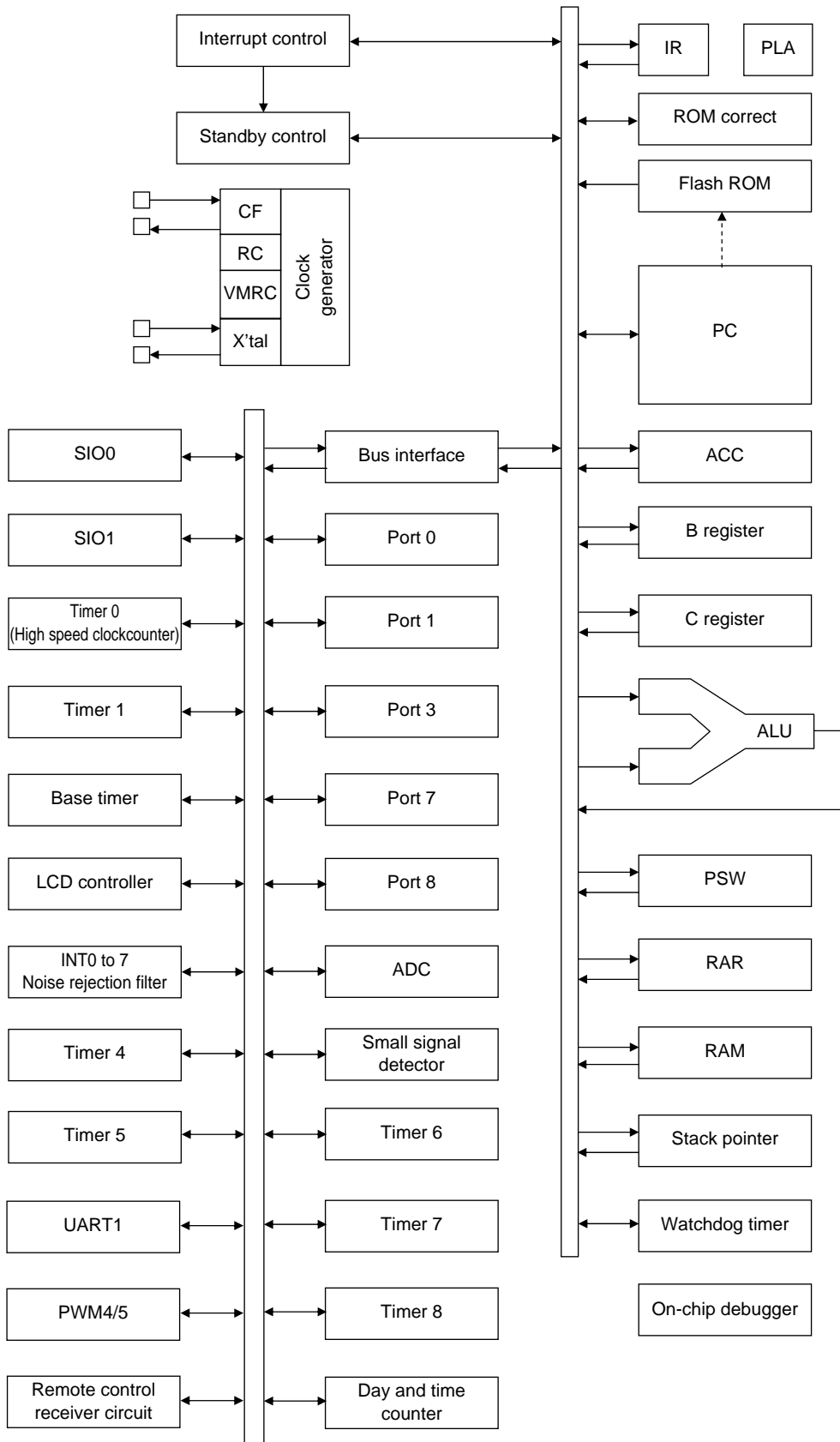
Pin Assignment



SANYO: TQFP100(14×14) "Lead-free Type"

LC87F7LC8A

System Block Diagram



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Pin Description

Pin Name	I/O	Description	Option																														
V _{SS} 1 V _{SS} 2 V _{SS} 3	-	- power supply pin	No																														
V _{DD} 1 V _{DD} 2 V _{DD} 3	-	+ power supply pin	No																														
Port 0 P00 to P07	I/O	<ul style="list-style-type: none"> • 8-bit I/O port • I/O specifiable in 4-bit units • Pull-up resistors can be turned on and off in 4-bit units. • Input for HOLD release • Input for port 0 interrupt • Shared pins <ul style="list-style-type: none"> P02: Timer 8L toggle output P03: Timer 8H toggle output P05: Clock output (system clock/can selected from sub clock) P06: Timer 6 toggle output P07: Timer 7 toggle output 	Yes																														
Port 1 P10 to P17	I/O	<ul style="list-style-type: none"> • 8-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1-bit units. • Shared pins <ul style="list-style-type: none"> P10: SIO0 data output P11: SIO0 data input/bus I/O P12: SIO0 clock I/O P13: SIO1 data output P14: SIO1 data input/bus I/O P15: SIO1 clock I/O P16: Timer 1PWML output P17: Timer 1PWMLH output/beeper output 	Yes																														
Port 3 P30 to P35	I/O	<ul style="list-style-type: none"> • 6-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1-bit units. • Shared pins <ul style="list-style-type: none"> P30 to P33: INT4 input/HOLD release input/timer 1 event input/timer 0L capture input/ timer 0H capture input P34 to P35: INT5 input/HOLD release input/timer 1 event input/timer 0L capture input/ timer 0H capture input P30: PWM4 output/INT6 input/timer 0L capture 1 input P31: PWM5 output P32: UART1 transmit P33: UART1 receive P34: INT7 input/timer 0H capture 1 input <p>Interrupt acknowledge type</p> <table border="1" style="width: 100%; border-collapse: collapse; text-align: center;"> <thead> <tr> <th></th> <th>Rising</th> <th>Falling</th> <th>Rising & Falling</th> <th>H level</th> <th>L level</th> </tr> </thead> <tbody> <tr> <td>INT4</td> <td>enable</td> <td>enable</td> <td>enable</td> <td>disable</td> <td>disable</td> </tr> <tr> <td>INT5</td> <td>enable</td> <td>enable</td> <td>enable</td> <td>disable</td> <td>disable</td> </tr> <tr> <td>INT6</td> <td>enable</td> <td>enable</td> <td>enable</td> <td>disable</td> <td>disable</td> </tr> <tr> <td>INT7</td> <td>enable</td> <td>enable</td> <td>enable</td> <td>disable</td> <td>disable</td> </tr> </tbody> </table>		Rising	Falling	Rising & Falling	H level	L level	INT4	enable	enable	enable	disable	disable	INT5	enable	enable	enable	disable	disable	INT6	enable	enable	enable	disable	disable	INT7	enable	enable	enable	disable	disable	Yes
	Rising	Falling	Rising & Falling	H level	L level																												
INT4	enable	enable	enable	disable	disable																												
INT5	enable	enable	enable	disable	disable																												
INT6	enable	enable	enable	disable	disable																												
INT7	enable	enable	enable	disable	disable																												

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LC87F7LC8A

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Pin Name	I/O	Description	Option																														
Port 7 P70 to P73	I/O	<ul style="list-style-type: none"> • 4-bit I/O port • I/O specifiable in 1-bit units • Pull-up resistors can be turned on and off in 1-bit units. • Shared pins <p>P70: INT0 input/HOLD release input/timer 0L capture input/watchdog timer output P71: INT1 input/HOLD release input/timer 0H capture input P72: INT2 input/HOLD release input/timer 0 event input/timer 0L capture input/ high speed clock counter input P73: INT3 input (with noise filter)/timer 0 event input/timer 0H capture input/ remote control receiver input</p> <p>AD converter input ports: AN8 (P70), AN9 (P71)</p> <p>Interrupt acknowledge type</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th></th> <th>Rising</th> <th>Falling</th> <th>Rising & Falling</th> <th>H level</th> <th>L level</th> </tr> </thead> <tbody> <tr> <td>INT0</td> <td>enable</td> <td>enable</td> <td>disable</td> <td>enable</td> <td>enable</td> </tr> <tr> <td>INT1</td> <td>enable</td> <td>enable</td> <td>disable</td> <td>enable</td> <td>enable</td> </tr> <tr> <td>INT2</td> <td>enable</td> <td>enable</td> <td>enable</td> <td>disable</td> <td>disable</td> </tr> <tr> <td>INT3</td> <td>enable</td> <td>enable</td> <td>enable</td> <td>disable</td> <td>disable</td> </tr> </tbody> </table>		Rising	Falling	Rising & Falling	H level	L level	INT0	enable	enable	disable	enable	enable	INT1	enable	enable	disable	enable	enable	INT2	enable	enable	enable	disable	disable	INT3	enable	enable	enable	disable	disable	No
	Rising	Falling	Rising & Falling	H level	L level																												
INT0	enable	enable	disable	enable	enable																												
INT1	enable	enable	disable	enable	enable																												
INT2	enable	enable	enable	disable	disable																												
INT3	enable	enable	enable	disable	disable																												
Port 8 P80 to P87	I/O	<ul style="list-style-type: none"> • 8-bit I/O port • I/O specifiable in 1-bit units • Shared pins <p>AD converter input ports: AN0 (P80) to AN7 (P87) Small signal detector input port: MICIN (P87)</p>	No																														
S0/PA0 to S7/PA7	I/O	<ul style="list-style-type: none"> • Segment output for LCD • Can be used as general-purpose I/O port (PA) 	No																														
S8/PB0 to S15/PB7	I/O	<ul style="list-style-type: none"> • Segment output for LCD • Can be used as general-purpose I/O port (PB) 	No																														
S16/PC0 to S23/PC7	I/O	<ul style="list-style-type: none"> • Segment output for LCD • Can be used as general-purpose I/O port (PC) 	No																														
S24/PD0 to S31/PD7	I/O	<ul style="list-style-type: none"> • Segment output for LCD • Can be used as general-purpose I/O port (PD) 	No																														
S32/PE0 to S39/PE7	I/O	<ul style="list-style-type: none"> • Segment output for LCD • Can be used as general-purpose I/O port (PE) 	No																														
S40/PF0 to S47/PF7	I/O	<ul style="list-style-type: none"> • Segment output for LCD • Can be used as general-purpose I/O port (PF) 	No																														
COM0/PL0 to COM3/PL3	I/O	<ul style="list-style-type: none"> • Common output for LCD • Can be used as general-purpose input port (PL) 	No																														
V1/PL4 to V3/PL6	I/O	<ul style="list-style-type: none"> • LCD output bias power supply • Can be used as general-purpose input port (PL) • Shared pins <p>AD converter input ports: AN12 (V1) to AN14 (V3) On-chip debugger pins: DBGPO (V1) to DBGP2 (V3)</p>	No																														
$\overline{\text{RES}}$	Input	Reset pin	No																														
XT1	Input	<ul style="list-style-type: none"> • 32.768kHz crystal oscillator input pin • Shared pins <p>General-purpose input port Must be connected to V_{DD1} if not to be used. AD converter input port: AN10</p>	No																														
XT2	I/O	<ul style="list-style-type: none"> • 32.768kHz crystal oscillator output pin • Shared pins <p>General-purpose I/O port Must be set for oscillation and kept open if not to be used. AD converter input port: AN11</p>	No																														
CF1	Input	Ceramic resonator input pin	No																														
CF2	Output	Ceramic resonator output pin	No																														

LC87F7LC8A

Port Output Types

The table below lists the types of port outputs and the presence/absence of a pull-up resistor.

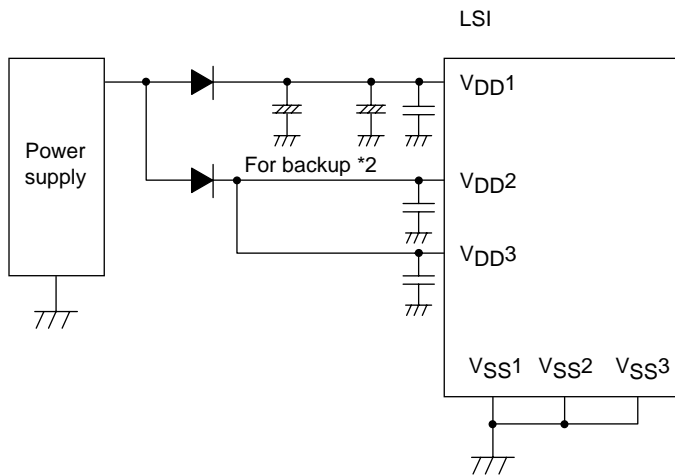
Data can be read into any input port even if it is in the output mode

Port Name	Option Selected in Units of	Option Type	Output Type	Pull-up Resistor
P00 to P07	each bit	1	CMOS	Programmable (Note)
		2	Nch-open drain	No
P10 to P17	each bit	1	CMOS	Programmable
		2	Nch-open drain	Programmable
P30 to P35	each bit	1	CMOS	Programmable
		2	Nch-open drain	Programmable
P70	-	No	Nch-open drain	Programmable
P71 to P73	-	No	CMOS	Programmable
P80 to P87	-	No	Nch-open drain	No
S0/PA0 to S47/PF7	-	No	CMOS	Programmable
COM0/PL0 to COM3/PL3	-	No	Input only	No
V1/PL4 to V3/PL6	-	No	Input only	No
XT1	-	No	Input for 32.768kHz crystal oscillator (Input only)	No
XT2	-	No	Output for 32.768kHz crystal oscillator (Nch-open drain when in general-purpose output mode)	No

Note 1: Programmable pull-up resistors for port 0 are controlled in 4 bit units (P00 to 03, P04 to 07).

*1: Connect the IC as shown below to minimize the noise input to the V_{DD1} pin.

Be sure to electrically short the V_{SS1} , V_{SS2} , and V_{SS3} pins.



*2: The internal memory is sustained by V_{DD1} . If none of V_{DD2} and V_{DD3} are backed up, the high level output at the ports are unstable in the HOLD backup mode, allowing through current to flow into the input buffer and thus shortening the backup time.

Make sure that the port outputs are held at the low level in the HOLD backup mode.

LC87F7LC8A

Absolute Maximum Ratings at Ta = 25°C, VSS1 = VSS2 = VSS3 = 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				unit
				V _{DD} [V]	min	typ	max	
Maximum supply voltage	V _{DD} max	V _{DD1} , V _{DD2} , V _{DD3}	V _{DD1} =V _{DD2} =V _{DD3}		-0.3		+6.5	V
supply voltage for LCD	VLCD	V1/PL4, V2/PL5, V3/PL6	V _{DD1} =V _{DD2} =V _{DD3}		-0.3		V _{DD}	
Input voltage	V _I (1)	Port L XT1, CF1, $\overline{\text{RES}}$			-0.3		V _{DD} +0.3	
Input/output voltage	V _{IO} (1)	Ports 0, 1, 3, 7, 8 Ports A, B, C, D, E, F XT2			-0.3		V _{DD} +0.3	
High level output current	Peak output current	IOPH(1)	Ports 0, 1, 32 to 35	• CMOS output selected • Current at each pin			-10	mA
		IOPH(2)	Ports 30, 31	• CMOS output selected • Current at each pin			-20	
		IOPH(3)	Ports 71 to 73	Current at each pin			-5	
		IOPH(4)	Ports A, B, C, D, E, F	Current at each pin			-5	
	Mean output current (Note 1-1)	IOMH(1)	Ports 0, 1, 32 to 35	• CMOS output selected • Current at each pin			-7.5	
		IOMH(2)	Ports 30, 31	• CMOS output selected • Current at each pin			-15	
		IOMH(3)	Ports 71 to 73	Current at each pin			-3	
		IOMH(4)	Ports A, B, C, D, E, F	Current at each pin			-3	
	Total output current	ΣIOAH(1)	Ports 0, 1, 32 to 35	Total of all pins			-25	
		ΣIOAH(2)	Ports 30, 31	Total of all pins			-25	
		ΣIOAH(3)	Ports 0, 1, 3	Total of all pins			-45	
		ΣIOAH(4)	Ports 71 to 73	Total of all pins			-5	
		ΣIOAH(5)	Ports A, B, C	Total of all pins			-25	
		ΣIOAH(6)	Ports D, E, F	Total of all pins			-25	
ΣIOAH(7)		Ports A, B, C, D, E, F	Total of all pins			-45		
Low level output current	Peak output current	IOPL(1)	Ports 0, 1, 32 to 35	Current at each pin			20	
		IOPL(2)	Ports 30, 31	Current at each pin			30	
		IOPL(3)	Ports 7, 8 XT2	Current at each pin			10	
		IOPL(4)	Ports A, B, C, D, E, F	Current at each pin			10	
	Mean output current (Note 1-1)	IOML(1)	Ports 0, 1, 32 to 35	Current at each pin			15	
		IOML(2)	Ports 30, 31	Current at each pin			20	
		IOML(3)	Ports 7, 8 XT2	Current at each pin			7.5	
		IOML(4)	Ports A, B, C, D, E, F	Current at each pin			7.5	
	Total output current	ΣOAL(1)	Ports 0,1,32 to 35	Total of all pins			45	
		ΣIOAL(2)	Ports 30, 31	Total of all pins			45	
		ΣIOAL(3)	Ports 0, 1, 3	Total of all pins			80	
		ΣIOAL(4)	Ports 7, 8 XT2	Total of all pins			20	
		ΣIOAL(5)	Ports A, B, C	Total of all pins			45	
ΣIOAL(6)		Ports D, E, F	Total of all pins			45		
ΣIOAL(7)		Ports A, B, C, D, E, F	Total of all pins			80		
Power dissipation	Pd max	QIP100E(14×20)	Ta=-20 to +70°C				461	mW
		TQFP100(14×14)	Ta=-20 to +70°C				331	
Operating ambient temperature	T _{opr}				-20		+70	°C
Storage ambient temperature	T _{stg}				-55		+125	

Note 1-1: The mean output current is a mean value measured over 100ms.

LC87F7LC8A

Allowable Operating Conditions at Ta = -20°C to +70°C, V_{SS1} = V_{SS2} = V_{SS3} = 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				unit
				V _{DD} [V]	min	typ	max	
Operating supply voltage (Note 2-1)	V _{DD} (1)	V _{DD1} =V _{DD2} =V _{DD3}	0.237μs≤tCYC≤200μs		3.0		5.5	V
	V _{DD} (2)		0.356μs≤tCYC≤200μs		2.5		5.5	
	V _{DD} (3)		0.712μs≤tCYC≤200μs		2.2		5.5	
Memory sustaining supply voltage	V _{HD}	V _{DD1}	RAM and register contents sustained in HOLD mode.		2.0		5.5	
High level input voltage	V _{IH} (1)	Ports 0, 3, 8 Ports A, B, C, D, E, F Port L	Output disabled	2.2 to 5.5	0.3V _{DD} +0.7		V _{DD}	V
	V _{IH} (2)	Port 1 Ports 71 to 73 P70 port input/ interrupt side	• Output disabled • When INT1VTSL=0 (P71 only)	2.2 to 5.5	0.3V _{DD} +0.7		V _{DD}	
	V _{IH} (3)	P71 interrupt side	• Output disabled • When INT1VTSL=1	2.2 to 5.5	0.85V _{DD}		V _{DD}	
	V _{IH} (4)	P87 small signal input side	Output disabled	2.2 to 5.5	0.75V _{DD}		V _{DD}	
	V _{IH} (5)	P70 watchdog timer side	Output disabled	2.2 to 5.5	0.9V _{DD}		V _{DD}	
	V _{IH} (6)	XT1, XT2, CF1, RES		2.2 to 5.5	0.75V _{DD}		V _{DD}	
Low level input voltage	V _{IL} (1)	Ports 0, 3, 8 Ports A, B, C, D, E, F Port L	Output disabled	4.0 to 5.5	V _{SS}		0.15V _{DD} +0.4	V
				2.2 to 4.0	V _{SS}		0.2V _{DD}	
	V _{IL} (2)	Port 1 Ports 71 to 73 P70 port input/ interrupt side	• Output disabled • When INT1VTSL=0 (P71 only)	4.0 to 5.5	V _{SS}		0.1V _{DD} +0.4	
				2.2 to 4.0	V _{SS}		0.2V _{DD}	
	V _{IL} (3)	P71 interrupt side	• Output disabled • When INT1VTSL=1	2.2 to 5.5	V _{SS}		0.45V _{DD}	
	V _{IL} (4)	P87 small signal input side	Output disabled	2.2 to 5.5	V _{SS}		0.25V _{DD}	
V _{IL} (5)	P70 watchdog timer side	Output disabled	2.2 to 5.5	V _{SS}		0.8V _{DD} -1.0		
V _{IL} (6)	XT1, XT2, CF1, RES		2.2 to 5.5	V _{SS}		0.25V _{DD}		
Instruction cycle time (Note 2-2)	tCYC			3.0 to 5.5	0.237		200	μs
				2.5 to 5.5	0.356		200	
				2.2 to 5.5	0.712		200	
External system clock frequency	FEXCF(1)	CF1	• CF2 pin open • System clock frequency division ratio=1/1 • External system clock duty=50±5%	3.0 to 5.5	0.1		12	MHz
				2.5 to 5.5	0.1		8	
				2.2 to 5.5	0.1		4	
				3.0 to 5.5	0.2		24.4	
				2.5 to 5.5	0.2		16	
				2.2 to 5.5	0.2		8	

Note 2-1: V_{DD} must be held greater than or equal to 3.0V in the flash ROM onboard programming mode.

Note 2-2: Relationship between tCYC and oscillation frequency is 3/FmCF at a division ratio of 1/1 and 6/FmCF at a division ratio of 1/2.

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LC87F7LC8A

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Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
Oscillation frequency range (Note 2-3)	FmCF(1)	CF1, CF2	<ul style="list-style-type: none"> 12MHz ceramic oscillation See Fig. 1. 	3.0 to 5.5		12		MHz
	FmCF(2)	CF1, CF2	<ul style="list-style-type: none"> 8MHz ceramic oscillation See Fig. 1. 	2.5 to 5.5		8		
	FmCF(3)	CF1, CF2	<ul style="list-style-type: none"> 4MHz ceramic oscillation See Fig. 1. 	2.2 to 5.5		4		
	FmRC		Internal RC oscillation	2.2 to 5.5	0.3	1.0	2.0	
	FmVMRC(1)		<ul style="list-style-type: none"> Frequency variable RC source oscillation When VMRAJ2 to 0=4, VMFAJ2 to 0=0, VMSL4M=0 	2.2 to 5.5		10		
	FmVMRC(2)		<ul style="list-style-type: none"> Frequency variable RC source oscillation When VMRAJ2 to 0=4, VMFAJ2 to 0=0, VMSL4M=1 	2.2 to 5.5		4		
	FsX'tal	XT1, XT2	<ul style="list-style-type: none"> 32.768kHz crystal oscillation See Fig. 2. 	2.2 to 5.5		32.768		kHz
Frequency variable RC oscillation usable range	OpVMRC(1)		When VMSL4M=0	2.2 to 5.5	8	10	12	MHz
	OpVMRC(2)		When VMSL4M=1	2.2 to 5.5	3.5	4	4.5	
Frequency variable RC oscillation adjustment range	VmADJ(1)		Each step of VMRAJn (Wide range)	2.2 to 5.5	8	24	64	%
	VmADJ(2)		Each step of VMFAJn (Small range)	2.2 to 5.5	1	4	8	

Note 2-3: See Tables 1 and 2 for the oscillation constants.

Electrical Characteristics at Ta = -20°C to +70°C, V_{SS1} = V_{SS2} = V_{SS3} = 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
High level input current	I _{IH} (1)	Ports 0, 1, 3, 7, 8 Ports A, B, C, D, E, F Port L	<ul style="list-style-type: none"> Output disabled Pull-up resistor off V_{IN}=V_{DD} (Including output Tr's off leakage current) 	2.2 to 5.5			1	μA
	I _{IH} (2)	RES	V _{IN} =V _{DD}	2.2 to 5.5			1	
	I _{IH} (3)	XT1, XT2	<ul style="list-style-type: none"> For input port specification V_{IN}=V_{DD} 	2.2 to 5.5			1	
	I _{IH} (4)	CF1	V _{IN} =V _{DD}	2.2 to 5.5			15	
	I _{IH} (5)	P87 small signal input side	V _{IN} =VBIS+0.5V (VBIS: Bias voltage)	4.5 to 5.5	4.2	8.5	15	
Low level input current	I _{IL} (1)	Ports 0, 1, 3, 7, 8 Ports A, B, C, D, E, F Port L	<ul style="list-style-type: none"> Output disabled Pull-up resistor off V_{IN}=V_{SS} (Including output Tr's off leakage current) 	2.2 to 5.5	-1			μA
	I _{IL} (2)	RES	V _{IN} =V _{SS}	2.2 to 5.5	-1			
	I _{IL} (3)	XT1, XT2	<ul style="list-style-type: none"> For input port specification V_{IN}=V_{SS} 	2.2 to 5.5	-1			
	I _{IL} (4)	CF1	V _{IN} =V _{SS}	2.2 to 5.5	-15			
	I _{IL} (5)	P87 small signal input side	V _{IN} =VBIS-0.5V (VBIS: Bias voltage)	4.5 to 5.5	-15	-8.5	-4.2	
				2.2 to 4.5	-10	-5.5	-1.5	

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LC87F7LC8A

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Parameter	Symbol	Pin/Remarks	Conditions	Specification				unit
				V _{DD} [V]	min	typ	max	
High level output voltage	V _{OH} (1)	Ports 0, 1, 32 to 35	I _{OH} =-1mA	4.5 to 5.5	V _{DD} -1			V
	V _{OH} (2)		I _{OH} =-0.4mA	3.0 to 5.5	V _{DD} -0.4			
	V _{OH} (3)		I _{OH} =-0.2mA	2.2 to 5.5	V _{DD} -0.4			
	V _{OH} (4)	Ports 30, 31	I _{OH} =-10mA	4.5 to 5.5	V _{DD} -1.5			
	V _{OH} (5)		I _{OH} =-1.6mA	3.0 to 5.5	V _{DD} -0.4			
	V _{OH} (6)		I _{OH} =-1mA	2.2 to 5.5	V _{DD} -0.4			
	V _{OH} (7)	Ports 71 to 73	I _{OH} =-0.4mA	3.0 to 5.5	V _{DD} -0.4			
	V _{OH} (8)		I _{OH} =-0.2mA	2.2 to 5.5	V _{DD} -0.4			
	V _{OH} (9)	Ports A, B, C, D, E, F	I _{OH} =-1mA	4.5 to 5.5	V _{DD} -1			
	V _{OH} (10)		I _{OH} =-0.4mA	3.0 to 5.5	V _{DD} -0.4			
	V _{OH} (11)		I _{OH} =-0.2mA	2.2 to 5.5	V _{DD} -0.4			
Low level output voltage	V _{OL} (1)	Ports 0, 1, 32 to 35	I _{OL} =10mA	4.5 to 5.5			1.5	
	V _{OL} (2)	Ports 30, 31	I _{OL} =1.6mA	3.0 to 5.5			0.4	
	V _{OL} (3)	(PWM function output mode)	I _{OL} =1mA	2.2 to 5.5			0.4	
	V _{OL} (4)	Port 30, 31 (Port function output mode)	I _{OL} =30mA	4.5 to 5.5			1.5	
	V _{OL} (5)		I _{OL} =5mA	3.0 to 5.5		0.4		
	V _{OL} (6)		I _{OL} =2.5mA	2.2 to 5.5		0.4		
	V _{OL} (7)	Ports 7, 8	I _{OL} =1.6mA	3.0 to 5.5			0.4	
	V _{OL} (8)	XT2	I _{OL} =1mA	2.2 to 5.5			0.4	
	V _{OL} (9)	Ports A, B, C, D, E, F	I _{OL} =1.6mA	3.0 to 5.5			0.4	
	V _{OL} (10)		I _{OL} =1mA	2.2 to 5.5		0.4		
LCD output voltage regulation	VODLS	S0 to S47	<ul style="list-style-type: none"> • I_O=0mA • VLCD, 2/3VLCD, 1/3VLCD level output • See Fig. 8. 	2.2 to 5.5	0		±0.2	
	VODLC	COM0 to COM3	<ul style="list-style-type: none"> • I_O=0mA • VLCD, 2/3VLCD, 1/2VLCD, 1/3VLCD level output • See Fig. 8. 	2.2 to 5.5	0		±0.2	
LCD bias resistor	RLCD(1)	Resistance per one bias resistor	See Fig. 8.	2.2 to 5.5		60		kΩ
	RLCD(2)	Resistance per one bias resistor 1/2R mode	See Fig. 8.	2.2 to 5.5		30		
Resistance of pull-up MOS Tr.	R _{pu} (1)	Ports 0, 1, 3, 7	V _{OH} =0.9V _{DD}	4.5 to 5.5	15	35	80	
	R _{pu} (2)	Ports A, B, C, D, E, F		2.2 to 5.5	18	50	150	
Hysteresis voltage	VHYS(1)	Ports 1, 7 RES		2.2 to 5.5		0.1V _{DD}		V
	VHYS(2)	P87 small signal input side		2.2 to 5.5		0.1V _{DD}		
Pin capacitance	CP	All pins	<ul style="list-style-type: none"> • For pins other than that under test: V_{IN}=V_{SS} • f=1MHz • T_a=25°C 	2.2 to 5.5		10		pF
Input sensitivity	V _{sen}	P87 small signal input side		2.2 to 5.5	0.12V _{DD}			V _{p-p}

LC87F7LC8A

Serial I/O Characteristics at Ta = -20°C to +70°C, V_{SS1} = V_{SS2} = V_{SS3} = 0V

1. SIO0 Serial I/O Characteristics (Note 4-1-1)

Parameter		Symbol	Pin/Remarks	Conditions	V _{DD} [V]	Specification					
						min	typ	max	unit		
Serial clock	Input clock	Frequency	tSCK(1)	SCK0(P12)	See Fig. 6.	2.2 to 5.5	2			tCYC	
		Low level pulse width	tSCKL(1)				1				
		High level pulse width	tSCKH(1)				1				
			tSCKHA(1)						4		
	Output clock	Frequency	tSCK(2)	SCK0(P12)	<ul style="list-style-type: none"> • CMOS output selected • See Fig. 6. 	2.2 to 5.5	4/3			tSCK	
		Low level pulse width	tSCKL(2)				1/2				
High level pulse width		tSCKH(2)	1/2								
		tSCKHA(2)	<ul style="list-style-type: none"> • Continuous data transmission/reception mode • CMOS output selected • See Fig. 6. 				tSCKH(2) +2tCYC		tSCKH(2) +(10/3) tCYC	tCYC	
Serial input	Data setup time	tsDI(1)	SB0(P11), SI0(P11)	<ul style="list-style-type: none"> • Must be specified with respect to rising edge of SIOCLK. • See Fig. 6. 	2.2 to 5.5	0.03					
	Data hold time	thDI(1)					2.2 to 5.5	0.03			
Serial output	Input clock	Output delay time	tdD0(1)	SO0(P10), SB0(P11)	<ul style="list-style-type: none"> • Continuous data transmission/reception mode • (Note 4-1-3) 	2.2 to 5.5			(1/3)tCYC +0.05	μs	
			tdD0(2)				<ul style="list-style-type: none"> • Synchronous 8-bit mode • (Note 4-1-3) 	2.2 to 5.5			
	tdD0(3)		(Note 4-1-3)				2.2 to 5.5				

Note 4-1-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-1-2: To use serial-clock-input in continuous trans/rec mode, a time from SIORUN being set when serial clock is "H" to the first negative edge of the serial clock must be longer than tSCKHA.

Note 4-1-3: Must be specified with respect to falling edge of SIOCLK. Must be specified as the time to the beginning of output state change in open drain output mode. See Fig. 6.

LC87F7LC8A

2. SIO1 Serial I/O Characteristics (Note 4-2-1)

Parameter		Symbol	Pin/Remarks	Conditions	V _{DD} [V]	Specification				
						min	typ	max	unit	
Serial clock	Input clock	Frequency	tSCK(3)	SCK1(P15)	See Fig. 6.	2.2 to 5.5	2			tCYC
		Low level pulse width	tSCKL(3)				1			
		High level pulse width	tSCKH(3)				1			
	Output clock	Frequency	tSCK(4)	SCK1(P15)	<ul style="list-style-type: none"> • CMOS output selected • See Fig. 6. 	2.2 to 5.5	2			tSCK
		Low level pulse width	tSCKL(4)				1/2			
		High level pulse width	tSCKH(4)				1/2			
Serial input	Data setup time	tsDI(2)	SB1(P14), SI1(P14)	<ul style="list-style-type: none"> • Must be specified with respect to rising edge of SIOCLK. • See Fig. 6. 	2.2 to 5.5	0.03				
	Data hold time	thDI(2)				2.2 to 5.5	0.03			
Serial output	Output delay time	tdD0(4)	SO1(P13), SB1(P14)	<ul style="list-style-type: none"> • Must be specified with respect to falling edge of SIOCLK. • Must be specified as the time to the beginning of output state change in open drain output mode. • See Fig. 6. 	2.2 to 5.5			(1/3)tCYC +0.05	μs	

Note 4-2-1: These specifications are theoretical values. Add margin depending on its use.

LC87F7LC8A

Pulse Input Conditions at Ta = -20°C to +70°C, VSS1 = VSS2= VSS3= 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				VDD[V]	min	typ	max	unit
High/low level pulse width	tPIH(1) tPIL(1)	INT0(P70), INT1(P71), INT2(P72), INT4(P30 to P33), INT5(P34 to P35), INT6(P30), INT7(P34)	<ul style="list-style-type: none"> Interrupt source flag can be set. Event inputs for timer 0 or 1 are enabled. 	2.2 to 5.5	1			tCYC
	tPIH(2) tPIL(2)	INT3(P73) when noise filter time constant is 1/1	<ul style="list-style-type: none"> Interrupt source flag can be set. Event inputs for timer 0 are enabled. 	2.2 to 5.5	2			
	tPIH(3) tPIL(3)	INT3(P73) when noise filter time constant is 1/32	<ul style="list-style-type: none"> Interrupt source flag can be set. Event inputs for timer 0 are enabled. 	2.2 to 5.5	64			
	tPIH(4) tPIL(4)	INT3(P73) when noise filter time constant is 1/128	<ul style="list-style-type: none"> Interrupt source flag can be set. Event inputs for timer 0 are enabled. 	2.2 to 5.5	256			
	tPIH(5) tPIL(5)	MICIN(P87)	Condition that signal is accepted to small signal detection counter.	2.2 to 5.5	1			
	tPIH(6) tPIL(6)	RMIN(P73)	Condition that signal is accepted to remote control receiver circuit.	2.2 to 5.5	4			RMCK (Note 5-1)
	tPIL(7)	$\overline{\text{RES}}$	Resetting is enabled.	2.2 to 5.5	200			μs

Note 5-1: RMCK is an unit for the base clock (40tCYC/50tCYC/Sub-Clock) of remote control receiver circuit.

AD Converter Characteristics at Ta = -20°C to +70°C, VSS1 = VSS2= VSS3= 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				VDD[V]	min	typ	max	unit
Resolution	N	AN0(P80) to		3.0 to 5.5		8		bit
Absolute accuracy	ET	AN7(P87), AN8(P70),	(Note 6-1)	3.0 to 5.5			±1.5	LSB
Conversion time	tCAD	AN9(P71), AN10(XT1), AN11(XT2), AN12(V1), AN13(V2), AN14(V3)	AD conversion time=32×tCYC (When ADCR2=0) (Note 6-2)	4.5 to 5.5	15.20 (tCYC= 0.475μs)		100.80 (tCYC= 3.15μs)	μs
				3.0 to 5.5	22.78 (tCYC= 0.712μs)		100.80 (tCYC= 3.15μs)	
			AD conversion time=64×tCYC (When ADCR2=1) (Note 6-2)	4.5 to 5.5	18.24 (tCYC= 0.285μs)		100.80 (tCYC= 1.57μs)	
				3.0 to 5.5	45.56 (tCYC= 0.712μs)		100.80 (tCYC= 1.57μs)	
Analog input voltage range	VAIN			3.0 to 5.5	VSS		VDD	V
Analog port input current	IAINH		VAIN=VDD	3.0 to 5.5			1	μA
	IAINL		VAIN=VSS	3.0 to 5.5	-1			

Note 6-1: The quantization error (±1/2 LSB) is excluded from the absolute accuracy value.

Note 6-2: The conversion time refers to the interval from the time the instruction for starting the converter is issued till the complete digital value corresponding to the analog input value is loaded in the required register.

LC87F7LC8A

Consumption Current Characteristics at Ta = -20°C to +70°C, VSS1 = VSS2 = VSS3 = 0V

Parameter	Symbol	Pin/ Remarks	Conditions	Specification				
				VDD[V]	min	typ	max	unit
Normal mode consumption current (Note 7-1)	IDDOP(1)	VDD1 = VDD2 = VDD3	<ul style="list-style-type: none"> FmCF=12MHz ceramic oscillation mode FmX'tal=32.768kHz crystal oscillation mode System clock set to 12MHz side Internal RC oscillation stopped. Frequency variable RC oscillation stopped. 1/1 frequency division ratio 	4.5 to 5.5		8.7	22	mA
	IDDOP(2)			3.0 to 3.6		5	12.5	
	IDDOP(3)		<ul style="list-style-type: none"> FmCF=8MHz ceramic oscillation mode FmX'tal=32.768kHz crystal oscillation mode System clock set to 8MHz side Internal RC oscillation stopped. Frequency variable RC oscillation stopped. 1/1 frequency division ratio 	4.5 to 5.5		6.6	16.5	
	IDDOP(4)			3.0 to 3.6		3.8	9.6	
	IDDOP(5)		<ul style="list-style-type: none"> FmCF=4MHz ceramic oscillation mode FmX'tal=32.768kHz crystal oscillation mode System clock set to 4MHz side Internal RC oscillation stopped. Frequency variable RC oscillation stopped. 1/1 frequency division ratio 	2.5 to 3.0		2.5	7.4	
	IDDOP(6)			4.5 to 5.5		2.5	6.3	
	IDDOP(7)		<ul style="list-style-type: none"> FmCF=0Hz (oscillation stopped) FmX'tal=32.768kHz crystal oscillation mode System clock set to internal RC oscillation Frequency variable RC oscillation stopped. 1/2 frequency division ratio 	3.0 to 3.6		1.4	3.5	
	IDDOP(8)			2.2 to 3.0		0.9	2.7	
	IDDOP(9)		<ul style="list-style-type: none"> FmCF=0Hz (oscillation stopped) FmX'tal=32.768 kHz crystal oscillation mode Internal RC oscillation stopped. System clock set to 10MHz with frequency variable RC oscillation 1/1 frequency division ratio 	4.5 to 5.5		0.75	3.1	
	IDDOP(10)			3.0 to 3.6		0.4	1.7	
	IDDOP(11)		<ul style="list-style-type: none"> FmCF=0Hz (oscillation stopped) FmX'tal=32.768 kHz crystal oscillation mode Internal RC oscillation stopped. System clock set to 4MHz with frequency variable RC oscillation 1/1 frequency division ratio 	2.2 to 3.0		0.28	1.35	
	IDDOP(12)			4.5 to 5.5		8	20	
	IDDOP(13)		<ul style="list-style-type: none"> FmCF=0Hz (oscillation stopped) FmX'tal=32.768kHz crystal oscillation mode Internal RC oscillation stopped. System clock set to 4MHz with frequency variable RC oscillation 1/1 frequency division ratio 	3.0 to 3.6		4.7	12	
	IDDOP(14)			4.5 to 5.5		4.5	11.5	
	IDDOP(15)		<ul style="list-style-type: none"> FmCF=0Hz (oscillation stopped) FmX'tal=32.768kHz crystal oscillation mode Internal RC oscillation stopped. System clock set to 32.768kHz side Internal RC oscillation stopped. Frequency variable RC oscillation stopped. 1/2 frequency division ratio 	3.0 to 3.6		2.6	6.6	
	IDDOP(16)			2.2 to 3.0		1.7	5	
	IDDOP(17)		<ul style="list-style-type: none"> FmCF=0Hz (oscillation stopped) FmX'tal=32.768kHz crystal oscillation mode System clock set to 32.768kHz side Internal RC oscillation stopped. Frequency variable RC oscillation stopped. 1/2 frequency division ratio 	4.5 to 5.5		35	115	
	IDDOP(18)			3.0 to 3.6		18	65	
	IDDOP(19)			2.2 to 3.0		12	46	

Note 7-1: The consumption current value includes none of the currents that flow into the output Tr and internal pull-up resistors.

Continued on next page.

LC87F7LC8A

Continued from preceding page.

Parameter	Symbol	Pin/ Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
HALT mode consumption current (Note 7-1)	IDDHALT(1)	V _{DD1} =V _{DD2} =V _{DD3}	HALT mode • FmCF=12MHz ceramic oscillation mode • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 12MHz side • Internal RC oscillation stopped. • Frequency variable RC oscillation stopped. • 1/1 frequency division ratio	4.5 to 5.5		3.6	8.2	mA
	IDDHALT(2)			3.0 to 3.6		2	4.6	
	IDDHALT(3)		HALT mode • FmCF=8MHz ceramic oscillation mode • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 8 MHz side • Internal RC oscillation stopped. • Frequency variable RC oscillation stopped. • 1/1 frequency division ratio	4.5 to 5.5		2.6	5.9	
	IDDHALT(4)			3.0 to 3.6		1.4	3.3	
	IDDHALT(5)		HALT mode • FmCF=4MHz ceramic oscillation mode • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 4MHz side • Internal RC oscillation stopped. • Frequency variable RC oscillation stopped. • 1/2 frequency division ratio	4.5 to 5.5		1.15	2.65	
	IDDHALT(6)			3.0 to 3.6		0.6	1.5	
	IDDHALT(7)		HALT mode • FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillation mode • System clock set to internal RC oscillation • Frequency variable RC oscillation stopped. • 1/2 frequency division ratio	4.5 to 5.5		0.37	1.3	
	IDDHALT(8)			3.0 to 3.6		0.2	0.75	
	IDDHALT(9)		HALT mode • FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillation mode • Internal RC oscillation stopped. • System clock set to 10MHz with frequency variable RC oscillation • 1/1 frequency division ratio	4.5 to 5.5		3.6	8.2	
	IDDHALT(10)			3.0 to 3.6		2	4.6	
	IDDHALT(11)		HALT mode • FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillation mode • Internal RC oscillation stopped. • System clock set to 4MHz with frequency variable RC oscillation • 1/1 frequency division ratio	4.5 to 5.5		1.7	4	
	IDDHALT(12)			3.0 to 3.6		1	2.5	
	IDDHALT(13)		HALT mode • FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 32.768kHz side • Internal RC oscillation stopped. • Frequency variable RC oscillation stopped. • 1/2 frequency division ratio	4.5 to 5.5		18.5	68	
	IDDHALT(14)			3.0 to 3.6		10	38	
	IDDHALT(15)		HALT mode • FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 32.768kHz side • Internal RC oscillation stopped. • Frequency variable RC oscillation stopped. • 1/2 frequency division ratio	4.5 to 5.5		0.05	20	
	IDDHALT(16)			3.0 to 3.6		0.03	12	
	IDDHALT(17)		HALT mode • CF1=V _{DD} or open (External clock mode)	2.2 to 3.0		0.02	8	
	IDDHALT(18)			2.2 to 3.0		0.02	8	
	Timer HOLD mode consumption current		IDDHOLD(4)	V _{DD1}	Timer HOLD mode • CF1=V _{DD} or open (External clock mode) • FmX'tal=32.768kHz crystal oscillation mode	4.5 to 5.5		
IDDHOLD(5)		3.0 to 3.6				8.5	32	
IDDHOLD(6)		2.2 to 3.0				5	20	

Note 7-1: The consumption current value includes none of the currents that flow into the output Tr and internal pull-up resistors.

LC87F7LC8A

F-ROM Programming Characteristics at Ta = +10°C to +55°C, VSS1 = VSS2= VSS3= 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				VDD[V]	min	typ	max	unit
Onboard programming current	IDDFW(1)	VDD1	<ul style="list-style-type: none"> 128-byte programming Erasing current included 	3.0 to 5.5		25	40	mA
Programming time	tFW(1)		<ul style="list-style-type: none"> 128-byte programming Erasing current included Time for setting up 128-byte data is excluded. 	3.0 to 5.5		22.5	45	ms

UART (Full Duplex) Operating Conditions at Ta = +20°C to +70°C, VSS1 = VSS2= VSS3= 0V

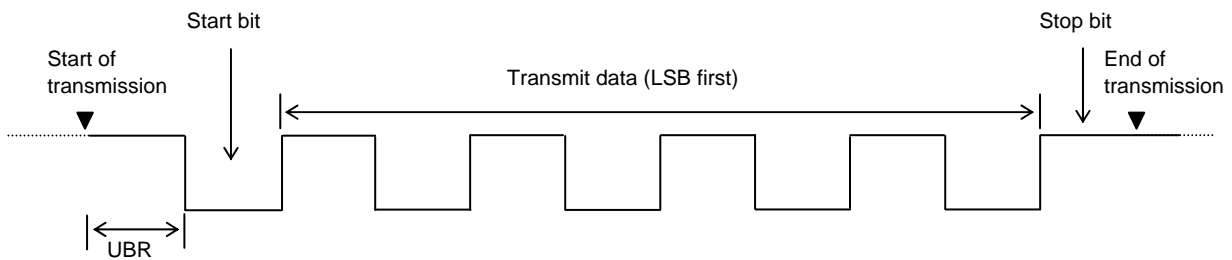
Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				VDD[V]	min	typ	max	unit
Transfer rate	UBR	UTX(S32), URX(S33)		2.2 to 5.5	16/3		8192/3	tCYC

Data length: 7/8/9 bits (LSB first)

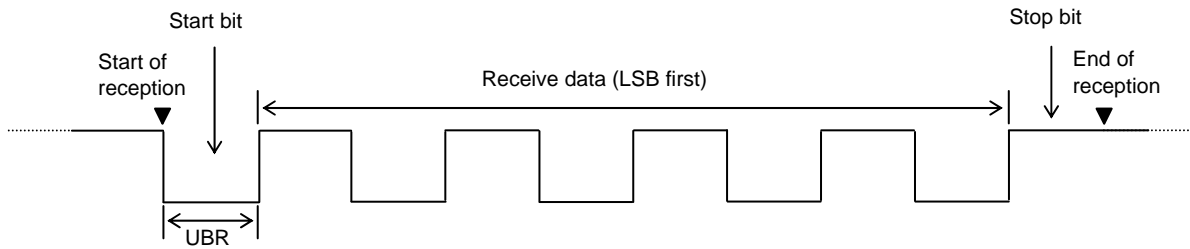
Stop bits: 1 bit (2-bit in continuous data transmission)

Parity bits: None

Example of 8-bit Data Transmission Mode Processing (Transmit Data=55H)



Example of 8-bit Data Reception Mode Processing (Receive Data=55H)



Characteristics of a Sample Main System Clock Oscillation Circuit

Given below are the characteristics of a sample main system clock oscillation circuit that are measured using a SANYO-designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 1 Characteristics of a Sample Main System Clock Oscillator Circuit with a Ceramic Oscillator

Nominal Frequency	Vendor Name	Oscillator Name	Circuit Constant				Operating Voltage Range [V]	Oscillation Stabilization Time		Remarks
			C1 [pF]	C2 [pF]	Rf1 [Ω]	Rd1 [Ω]		typ [ms]	max [ms]	
12MHz	MURATA	CSTCE12M0G52-R0	(10)	(10)	Open	470	3.0 to 5.5	0.05	0.15	Internal C1, C2
8MHz	MURATA	CSTCE8M00G52-R0	(10)	(10)	Open	2.2k	2.7 to 5.5	0.05	0.15	Internal C1, C2
		CSTLS8M00G53-B0	(15)	(15)	Open	680	2.5 to 5.5	0.05	0.15	
4MHz	MURATA	CSTCR4M00G53-R0	(15)	(15)	Open	3.3k	2.2 to 5.5	0.05	0.15	Internal C1, C2
		CSTLS4M00G53-B0	(15)	(15)	Open	3.3k	2.2 to 5.5	0.05	0.15	

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized after VDD goes above the operating voltage lower limit (see Fig. 4).

Characteristics of a Sample Subsystem Clock Oscillator Circuit

Given below are the characteristics of a sample subsystem clock oscillation circuit that are measured using a SANYO-designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 2 Characteristics of a Sample Subsystem Clock Oscillation Circuit with a Crystal Oscillation

Nominal Frequency	Vendor Name	Oscillator Name	Circuit Constant				Operating Voltage Range [V]	Oscillation Stabilization Time		Remarks
			C3 [pF]	C4 [pF]	Rf2 [Ω]	Rd2 [Ω]		typ [s]	max [s]	
32.768kHz	SEIKO EPSON	MC-306	18	18	Open	560k	2.2 to 5.5	1.4	3.0	Applicable CL value=12.5pF

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized after the instruction for starting the subclock oscillation circuit is executed and to the time interval that is required for the oscillation to get stabilized after the HOLD mode is reset (see Fig. 4).

Note: The components that are involved in oscillation should be placed as close to the IC and to one another as possible because they are vulnerable to the influences of the circuit pattern.

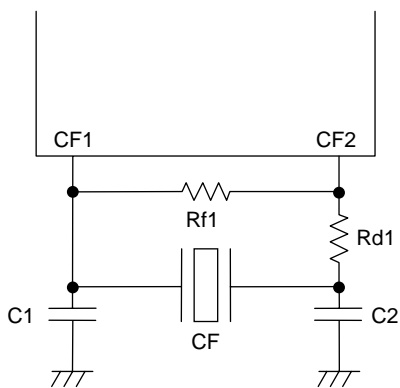


Figure 1 CF Oscillator Circuit

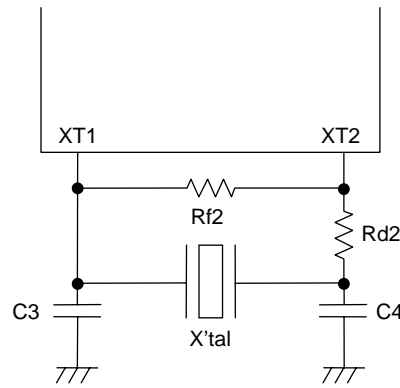


Figure 2 XT Oscillator Circuit

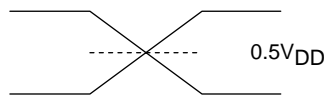
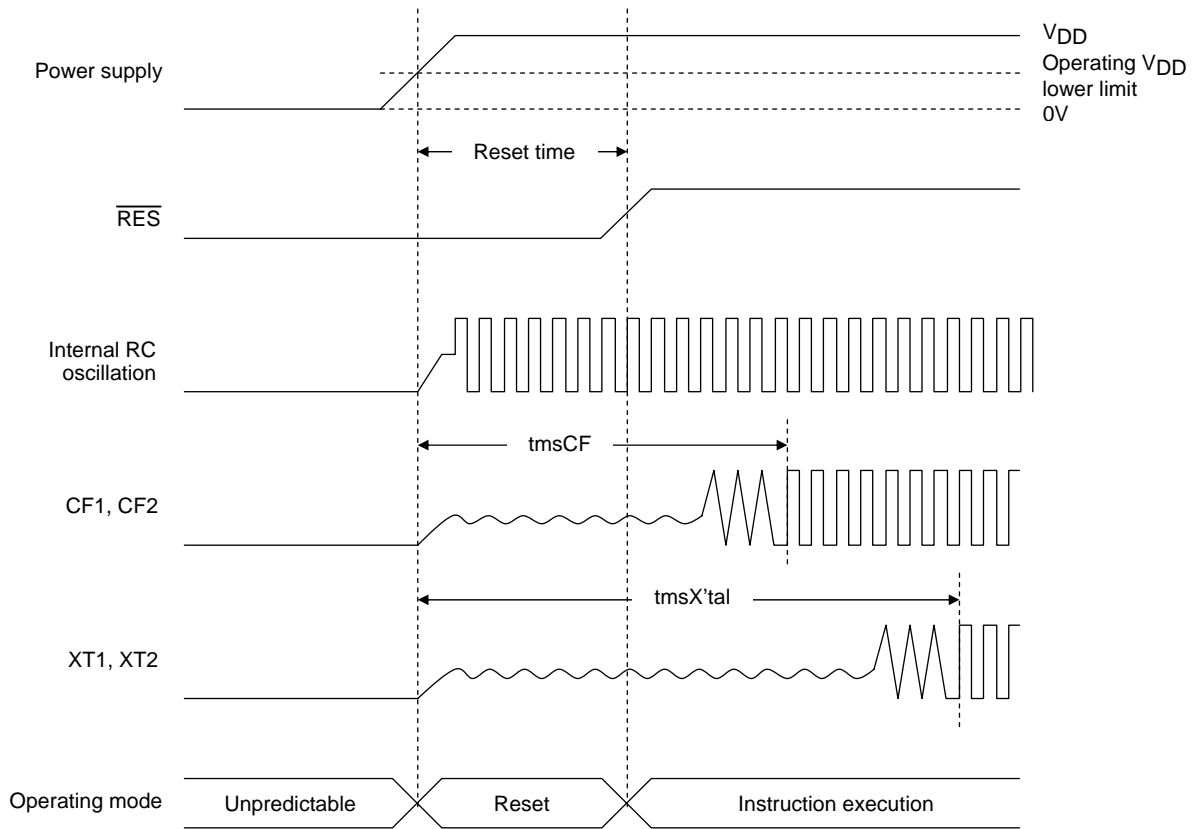
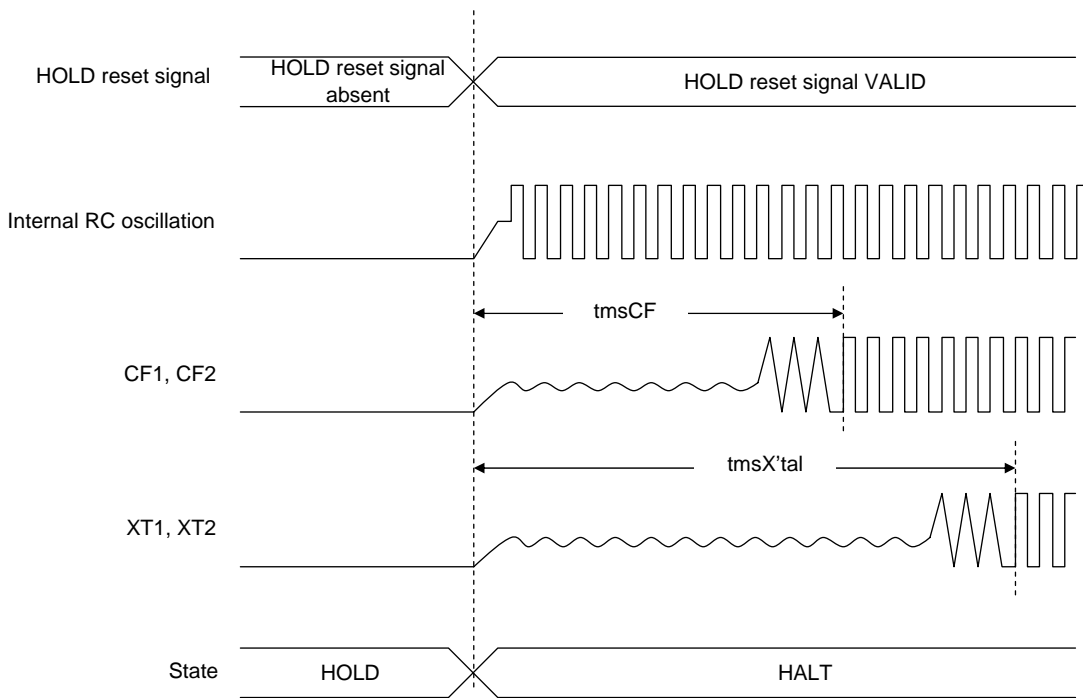


Figure 3 AC Timing Measurement Point

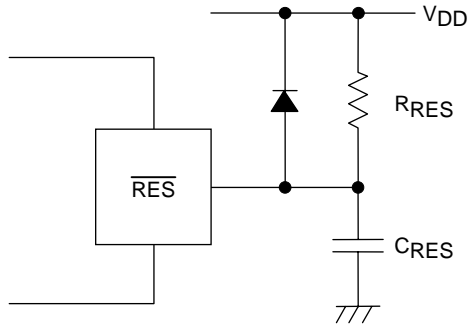


Reset Time and Oscillation Stabilizing Time



HOLD Release Signal and Oscillation Stable Time

Figure 4 Oscillation Stabilizing Times



Note:
Determine the value of C_{RES} and R_{RES} so that the reset signal is present for a period of $200\mu s$ after the supply voltage goes beyond the lower limit of the IC's operating voltage.

Figure 5 Reset Circuit

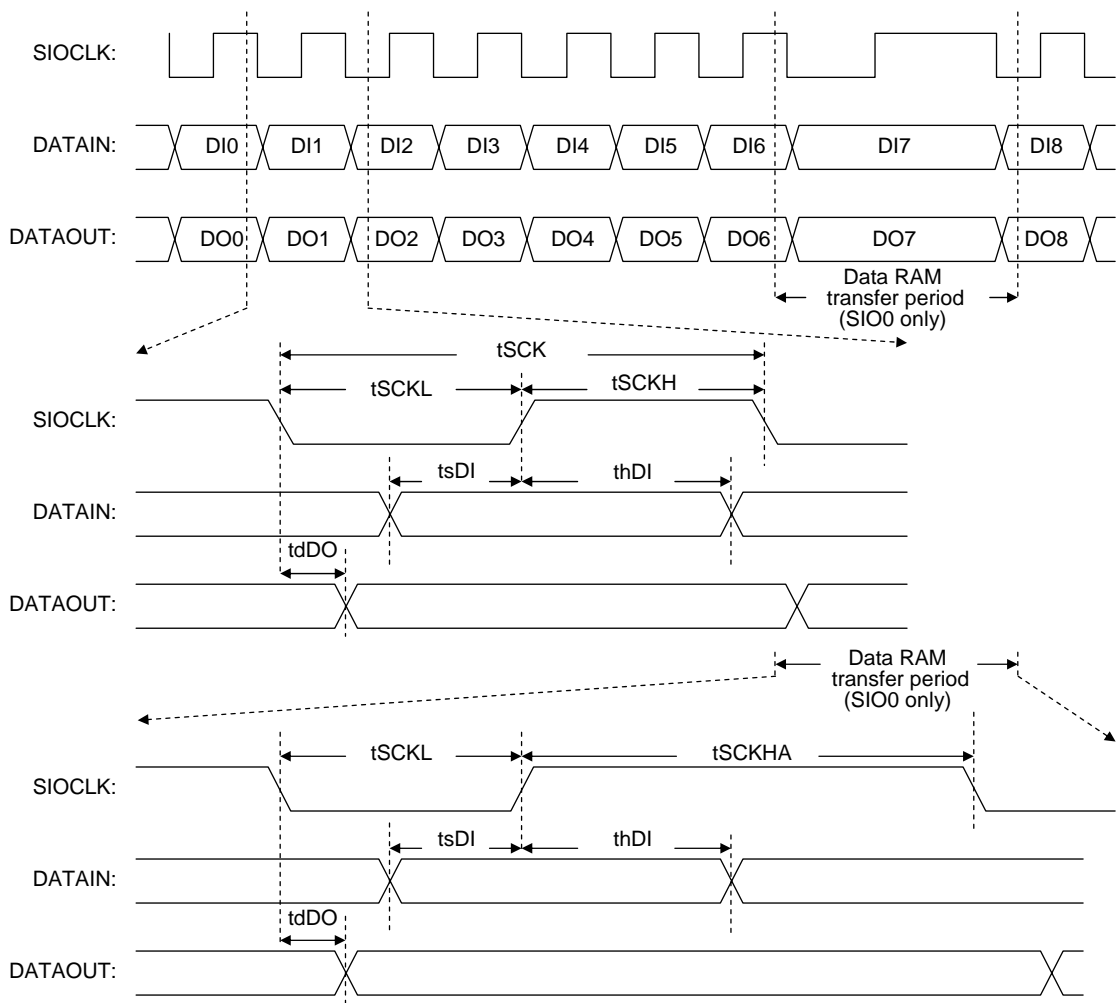


Figure 6 Serial I/O Waveforms

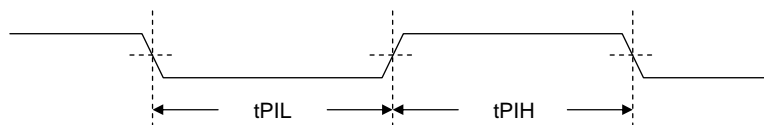


Figure 7 Pulse Input Timing Signal Waveform

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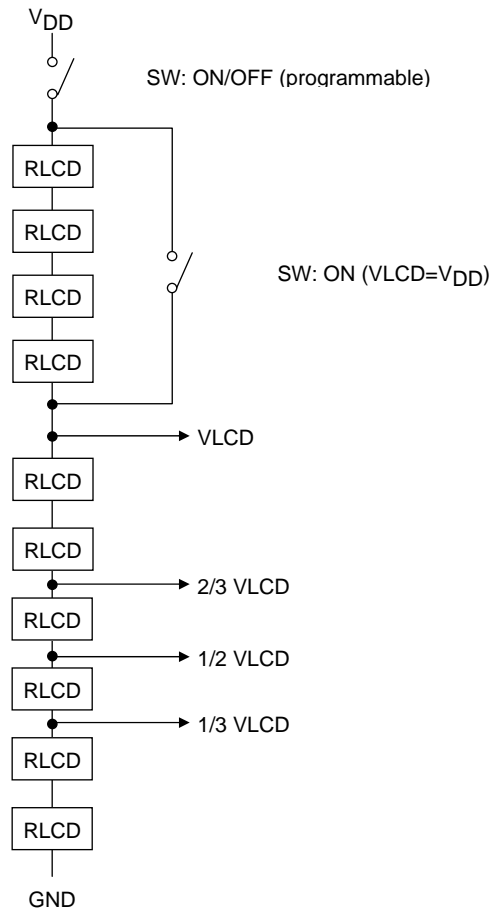


Figure 8 LCD bias resistor

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