

209-bump BGA  
Commercial Temp  
Industrial Temp

## 18Mb Pipelined and Flow Through Synchronous NBT SRAM

200 MHz–133 MHz  
2.5 V or 3.3 V V<sub>DD</sub>  
2.5 V or 3.3 V I/O

### Features

- NBT (No Bus Turn Around) functionality allows zero wait Read-Write-Read bus utilization; fully pin-compatible with both pipelined and flow through NtRAM™, NoBL™ and ZBT™ SRAMs
- 2.5 V or 3.3 V +10%/–10% core power supply
- 2.5 V or 3.3 V I/O supply
- User-configurable Pipeline and Flow Through mode
- ZQ mode pin for user-selectable high/low output drive
- IEEE 1149.1 JTAG-compatible Boundary Scan
- $\overline{\text{LBO}}$  pin for Linear or Interleave Burst mode
- Pin-compatible with 2M, 4M, and 8M devices
- Byte write operation (9-bit Bytes)
- 3 chip enable signals for easy depth expansion
- ZZ Pin for automatic power-down
- JEDEC-standard 209-Bump BGA package

### Functional Description

The GS8162Z72C is an 18Mbit Synchronous Static SRAM. GSI's NBT SRAMs, like ZBT, NtRAM, NoBL or other pipelined read/double late write or flow through read/single late write SRAMs, allow utilization of all available bus bandwidth by eliminating the need to insert deselect cycles when the device is switched from read to write cycles.

Because it is a synchronous device, address, data inputs, and read/write control inputs are captured on the rising edge of the input clock. Burst order control ( $\overline{\text{LBO}}$ ) must be tied to a power rail for proper operation. Asynchronous inputs include the Sleep mode enable (ZZ) and Output Enable. Output Enable can be used to override the synchronous control of the output drivers and turn the RAM's output drivers off at any time. Write cycles are internally self-timed and initiated by the rising edge of the clock input. This feature eliminates complex off-chip write pulse generation required by asynchronous SRAMs and simplifies input signal timing.

The GS8162Z72C may be configured by the user to operate in Pipeline or Flow Through mode. Operating as a pipelined synchronous device, in addition to the rising-edge-triggered registers that capture input signals, the device incorporates a rising edge triggered output register. For read cycles, pipelined SRAM output data is temporarily stored by the edge-triggered output register during the access cycle and then released to the output drivers at the next rising edge of clock.

The GS8162Z72C is implemented with GSI's high performance CMOS technology and is available in a JEDEC-standard 209-bump BGA package.

### Parameter Synopsis

		-200	-166	-150	-133	Unit
Pipeline 3-1-1-1	t <sub>kQ</sub>	3.0	3.4	3.8	4.0	ns
	t <sub>Cycle</sub>	5.0	6.0	6.7	7.5	ns
3.3 V	Curr (x72)	350	300	270	245	mA
2.5 V	Curr (x72)	335	290	260	235	mA
Flow Through 2-1-1-1	t <sub>kQ</sub>	6.5	7.0	7.5	8.5	ns
	t <sub>Cycle</sub>	6.5	7.0	7.5	8.5	ns
3.3 V	Curr (x72)	225	115	210	185	mA
2.5 V	Curr (x72)	225	115	210	185	mA

**GS8162Z72 Pad Out—209-Bump BGA—Top View (Package C)**

	1	2	3	4	5	6	7	8	9	10	11
A	DQG	DQG	A	E2	A	ADV	A	$\bar{E}3$	A	DQB	DQB
B	DQG	DQG	$\bar{B}C$	$\bar{B}G$	NC	$\bar{W}$	A	$\bar{B}B$	$\bar{B}F$	DQB	DQB
C	DQG	DQG	$\bar{B}H$	$\bar{B}D$	NC	$\bar{E}1$	NC	$\bar{B}E$	$\bar{B}A$	DQB	DQB
D	DQG	DQG	V <sub>SS</sub>	NC	NC	$\bar{G}$	NC	NC	V <sub>SS</sub>	DQB	DQB
E	DQPG	DQPC	V <sub>DDQ</sub>	V <sub>DDQ</sub>	V <sub>DD</sub>	V <sub>DD</sub>	V <sub>DD</sub>	V <sub>DDQ</sub>	V <sub>DDQ</sub>	DQPF	DQPB
F	DQC	DQC	V <sub>SS</sub>	V <sub>SS</sub>	V <sub>SS</sub>	ZQ	V <sub>SS</sub>	V <sub>SS</sub>	V <sub>SS</sub>	DQF	DQF
G	DQC	DQC	V <sub>DDQ</sub>	V <sub>DDQ</sub>	V <sub>DD</sub>	MCH	V <sub>DD</sub>	V <sub>DDQ</sub>	V <sub>DDQ</sub>	DQF	DQF
H	DQC	DQC	V <sub>SS</sub>	V <sub>SS</sub>	V <sub>SS</sub>	MCL	V <sub>SS</sub>	V <sub>SS</sub>	V <sub>SS</sub>	DQF	DQF
J	DQC	DQC	V <sub>DDQ</sub>	V <sub>DDQ</sub>	V <sub>DD</sub>	MCH	V <sub>DD</sub>	V <sub>DDQ</sub>	V <sub>DDQ</sub>	DQF	DQF
K	NC	NC	CK	NC	V <sub>SS</sub>	MCL	V <sub>SS</sub>	NC	NC	NC	NC
L	DQH	DQH	V <sub>DDQ</sub>	V <sub>DDQ</sub>	V <sub>DD</sub>	$\bar{F}T$	V <sub>DD</sub>	V <sub>DDQ</sub>	V <sub>DDQ</sub>	DQA	DQA
M	DQH	DQH	V <sub>SS</sub>	V <sub>SS</sub>	V <sub>SS</sub>	MCL	V <sub>SS</sub>	V <sub>SS</sub>	V <sub>SS</sub>	DQA	DQA
N	DQH	DQH	V <sub>DDQ</sub>	V <sub>DDQ</sub>	V <sub>DD</sub>	MCH	V <sub>DD</sub>	V <sub>DDQ</sub>	V <sub>DDQ</sub>	DQA	DQA
P	DQH	DQH	V <sub>SS</sub>	V <sub>SS</sub>	V <sub>SS</sub>	ZZ	V <sub>SS</sub>	V <sub>SS</sub>	V <sub>SS</sub>	DQA	DQA
R	DQPD	DQPH	V <sub>DDQ</sub>	V <sub>DDQ</sub>	V <sub>DD</sub>	V <sub>DD</sub>	V <sub>DD</sub>	V <sub>DDQ</sub>	V <sub>DDQ</sub>	DQPA	DQPE
T	DQD	DQD	V <sub>SS</sub>	NC	NC	$\bar{L}B\bar{O}$	$\bar{P}E$	NC	V <sub>SS</sub>	DQE	DQE
U	DQD	DQD	NC	A	NC	A	NC	A	NC	DQE	DQE
V	DQD	DQD	A	A	A	A1	A	A	A	DQE	DQE
W	DQD	DQD	TMS	TDI	A	A0	A	TDO	TCK	DQE	DQE

Rev 10

 11 x 19 Bump BGA—14 x 22 mm<sup>2</sup> Body—1 mm Bump Pitch

**GS8162Z72 BGA Pin Description**

<b>Symbol</b>	<b>Type</b>	<b>Description</b>
A <sub>0</sub> , A <sub>1</sub>	I	Address field LSBs and Address Counter Preset Inputs
A <sub>n</sub>	I	Address Inputs
DQ <sub>A</sub> DQ <sub>B</sub> DQ <sub>C</sub> DQ <sub>D</sub> DQ <sub>E</sub> DQ <sub>F</sub> DQ <sub>G</sub> DQ <sub>H</sub>	I/O	Data Input and Output pins
$\overline{B_A}$ , $\overline{B_B}$ , $\overline{B_C}$ , $\overline{B_D}$ , $\overline{B_E}$ , $\overline{B_F}$ , $\overline{B_G}$ , $\overline{B_H}$	I	Byte Write Enable for DQ <sub>A</sub> , DQ <sub>B</sub> , DQ <sub>C</sub> , DQ <sub>D</sub> , DQ <sub>E</sub> , DQ <sub>F</sub> , DQ <sub>G</sub> , DQ <sub>H</sub> I/Os; active low
NC	—	No Connect
CK	I	Clock Input Signal; active high
$\overline{W}$	I	Write Enable. Writes all enabled bytes; active low
$\overline{E_1}$ , $\overline{E_3}$	I	Chip Enable; active low
E <sub>2</sub>	I	Chip Enable; active high
$\overline{G}$	I	Output Enable; active low
ZZ	I	Sleep Mode control; active high
$\overline{FT}$	I	Flow Through or Pipeline mode; active low
$\overline{LBO}$	I	Linear Burst Order mode; active low
MCH	I	Must Connect High
MCL	I	Must Connect Low
$\overline{PE}$	I	Parity Bit Enable; active low (High = x64 Mode, Low = x72 Mode)
ADV	I	Burst Address Counter Advance Enable; active high
ZQ	I	FLXDrive Output Impedance Control (Low = Low Impedance [High Drive], High = High Impedance [Low Drive])
TMS	I	Scan Test Mode Select
TDI	I	Scan Test Data In
TDO	O	Scan Test Data Out
TCK	I	Scan Test Clock
V <sub>DD</sub>	I	Core power supply
V <sub>SS</sub>	I	I/O and Core Ground
V <sub>DDQ</sub>	I	Output driver power supply

## Functional Details

### Clocking

Deassertion of the Clock Enable ( $\overline{\text{CKE}}$ ) input blocks the Clock input from reaching the RAM's internal circuits. It may be used to suspend RAM operations. Failure to observe Clock Enable set-up or hold requirements will result in erratic operation.

### Pipeline Mode Read and Write Operations

All inputs (with the exception of Output Enable, Linear Burst Order and Sleep) are synchronized to rising clock edges. Single cycle read and write operations must be initiated with the Advance/Load pin (ADV) held low, in order to load the new address. Device activation is accomplished by asserting all three of the Chip Enable inputs ( $\overline{\text{E}}_1$ ,  $\text{E}_2$ , and  $\overline{\text{E}}_3$ ). Deassertion of any one of the Enable inputs will deactivate the device.

### Byte Write Truth Table

Function	$\overline{\text{GW}}$	$\overline{\text{BW}}$	$\overline{\text{BA}}$	$\overline{\text{BB}}$	$\overline{\text{BC}}$	$\overline{\text{BD}}$	$\overline{\text{BE}}$	$\overline{\text{BF}}$	$\overline{\text{BG}}$	$\overline{\text{BH}}$	Notes
Read	H	H	X	X	X	X	X	X	X	X	1
Read	H	L	H	H	H	H	H	H	H	H	1
Write byte A	H	L	L	H	H	H	L	H	H	H	2, 3
Write byte B	H	L	H	L	H	H	H	L	H	H	2, 3
Write byte C	H	L	H	H	L	H	H	H	L	H	2, 3, 4
Write byte D	H	L	H	H	H	L	H	H	H	L	2, 3, 4
Write byte E	H	L	H	H	H	H	L	H	H	H	2, 3, 4
Write byte F	H	L	H	H	H	H	H	L	H	H	2, 3, 4
Write byte G	H	L	H	H	H	H	H	H	L	H	2, 3, 4
Write byte H	H	L	H	H	H	H	H	H	H	L	2, 3, 4
Write all bytes	H	L	L	L	L	L	L	L	L	L	2, 3, 4
Write all bytes	L	X	X	X	X	X	X	X	X	X	

#### Notes:

1. All byte outputs are active in read cycles regardless of the state of Byte Write Enable inputs.
2. Byte Write Enable inputs  $\overline{\text{BA}}$ ,  $\overline{\text{BB}}$ ,  $\overline{\text{BC}}$ ,  $\overline{\text{BD}}$ ,  $\overline{\text{BE}}$ ,  $\overline{\text{BF}}$ ,  $\overline{\text{BG}}$ , and/or  $\overline{\text{BH}}$  may be used in any combination with  $\overline{\text{BW}}$  to write single or multiple bytes.
3. All byte I/Os remain High-Z during all write operations regardless of the state of Byte Write Enable inputs.
4. Bytes "E", "F", "G" and "H" are only available on the x72 version.

Read operation is initiated when the following conditions are satisfied at the rising edge of clock:  $\overline{\text{CKE}}$  is asserted low, all three chip enables ( $\overline{\text{E}}_1$ ,  $\text{E}_2$ , and  $\overline{\text{E}}_3$ ) are active, the write enable input signals  $\overline{\text{W}}$  is deasserted high, and ADV is asserted low. The address presented to the address inputs is latched into the address register and presented to the memory core and control logic. The control logic determines that a read access is in progress and allows the requested data to propagate to the input of the output register. At the next rising edge of clock the read data is allowed to propagate through the output register and onto the output pins.

Write operation occurs when the RAM is selected, CKE is active, and the Write input is sampled low at the rising edge of clock. The Byte Write Enable inputs ( $\overline{\text{BA}}$ ,  $\overline{\text{BB}}$ ,  $\overline{\text{BC}}$ , and  $\overline{\text{BD}}$ ) determine which bytes will be written. All or none may be activated. A write cycle with no Byte Write inputs active is a no-op cycle. The pipelined NBT SRAM provides double late write functionality, matching the write command versus data pipeline length (2 cycles) to the read command versus data pipeline length (2 cycles). At the first rising edge of clock, Enable, Write, Byte Write(s), and Address are registered. The Data In associated with that address is required at the third rising edge of clock.

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**Flow Through Mode Read and Write Operations**

Operation of the RAM in Flow Through mode is very similar to operations in Pipeline mode. Activation of a Read Cycle and the use of the Burst Address Counter is identical. In Flow Through mode the device may begin driving out new data immediately after new address are clocked into the RAM, rather than holding new data until the following (second) clock edge. Therefore, in Flow Through mode the read pipeline is one cycle shorter than in Pipeline mode.

Write operations are initiated in the same way, but differ in that the write pipeline is one cycle shorter as well, preserving the ability to turn the bus from reads to writes without inserting any dead cycles. While the pipelined NBT RAMs implement a double late write protocol in Flow Through mode a single late write protocol mode is observed. Therefore, in Flow Through mode, address and control are registered on the first rising edge of clock and data in is required at the data input pins at the second rising edge of clock.

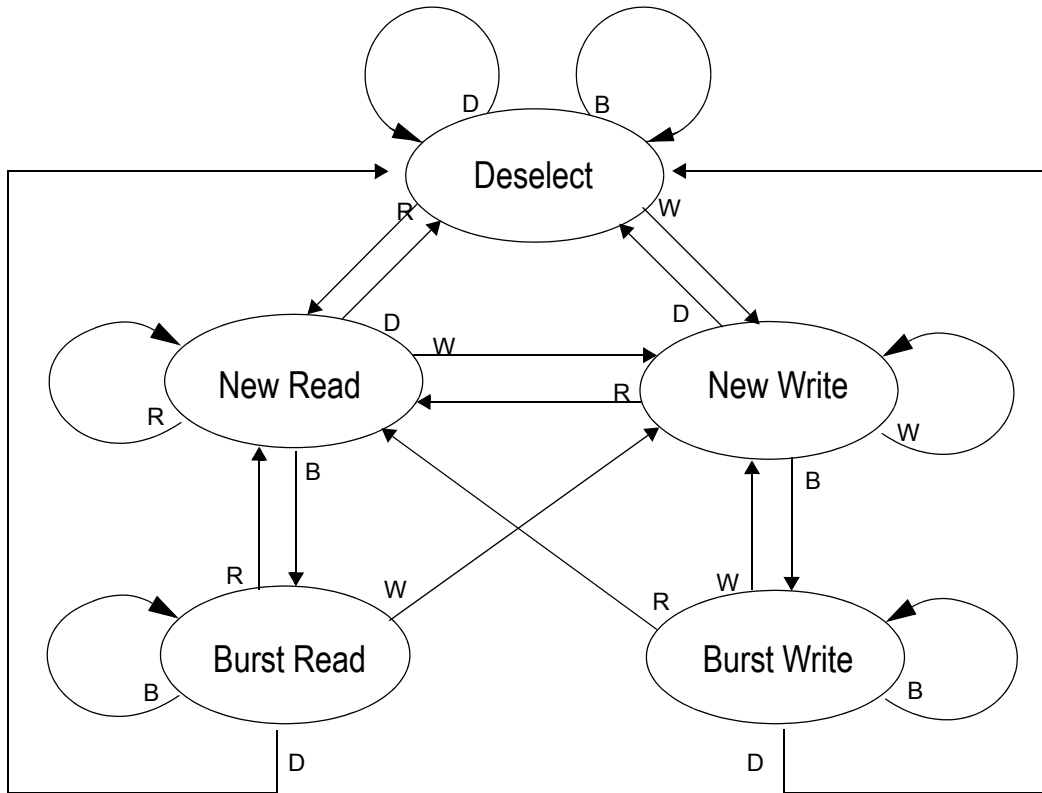
**Synchronous Truth Table**

Operation	Type	Address	CK	$\overline{\text{CKE}}$	ADV	$\overline{\text{W}}$	$\overline{\text{Bx}}$	$\overline{\text{E1}}$	E2	$\overline{\text{E3}}$	$\overline{\text{G}}$	ZZ	DQ	Notes
Read Cycle, Begin Burst	R	External	L-H	L	L	H	X	L	H	L	L	L	Q	
Read Cycle, Continue Burst	B	Next	L-H	L	H	X	X	X	X	X	L	L	Q	1,10
NOP/Read, Begin Burst	R	External	L-H	L	L	H	X	L	H	L	H	L	High-Z	2
Dummy Read, Continue Burst	B	Next	L-H	L	H	X	X	X	X	X	H	L	High-Z	1,2,10
Write Cycle, Begin Burst	W	External	L-H	L	L	L	L	L	H	L	X	L	D	3
Write Cycle, Continue Burst	B	Next	L-H	L	H	X	L	X	X	X	X	L	D	1,3,10
Write Abort, Continue Burst	B	Next	L-H	L	H	X	H	X	X	X	X	L	High-Z	1,2,3,10
Deselect Cycle, Power Down	D	None	L-H	L	L	X	X	H	X	X	X	L	High-Z	
Deselect Cycle, Power Down	D	None	L-H	L	L	X	X	X	X	H	X	L	High-Z	
Deselect Cycle, Power Down	D	None	L-H	L	L	X	X	X	L	X	X	L	High-Z	
Deselect Cycle	D	None	L-H	L	L	L	H	L	H	L	X	L	High-Z	1
Deselect Cycle, Continue	D	None	L-H	L	H	X	X	X	X	X	X	L	High-Z	1
Sleep Mode		None	X	X	X	X	X	X	X	X	X	H	High-Z	
Clock Edge Ignore, Stall		Current	L-H	H	X	X	X	X	X	X	X	L	-	4

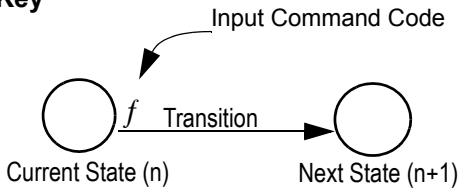
**Notes:**

- Continue Burst cycles, whether read or write, use the same control inputs. A Deselect continue cycle can only be entered into if a Deselect cycle is executed first.
- Dummy Read and Write abort can be considered NOPs because the SRAM performs no operation. A Write abort occurs when the  $\overline{\text{W}}$  pin is sampled low but no Byte Write pins are active so no write operation is performed.
- $\overline{\text{G}}$  can be wired low to minimize the number of control signals provided to the SRAM. Output drivers will automatically turn off during write cycles.
- If CKE High occurs during a pipelined read cycle, the DQ bus will remain active (Low Z). If  $\overline{\text{CKE}}$  High occurs during a write cycle, the bus will remain in High Z.
- X = Don't Care; H = Logic High; L = Logic Low;  $\overline{\text{Bx}}$  = High = All Byte Write signals are high;  $\overline{\text{Bx}}$  = Low = One or more Byte/Write signals are Low
- All inputs, except  $\overline{\text{G}}$  and ZZ must meet setup and hold times of rising clock edge.
- Wait states can be inserted by setting  $\overline{\text{CKE}}$  high.
- This device contains circuitry that ensures all outputs are in High Z during power-up.
- A 2-bit burst counter is incorporated.
- The address counter is incremented for all Burst continue cycles.

Pipelined and Flow Through Read Write Control State Diagram

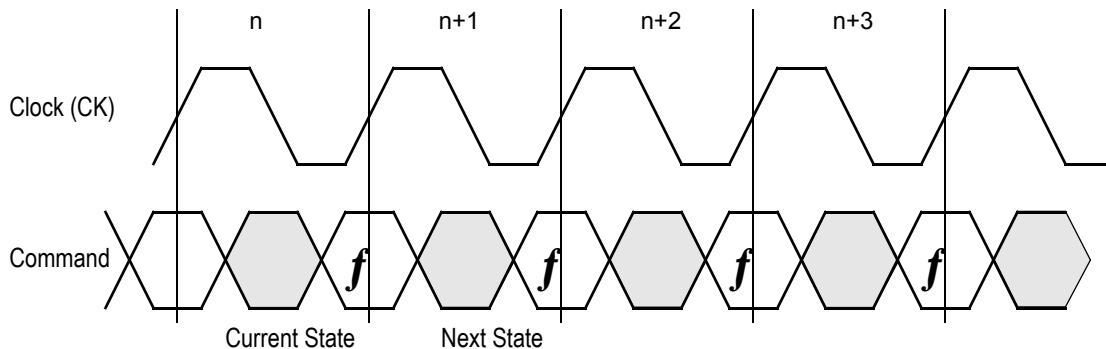


**Key**



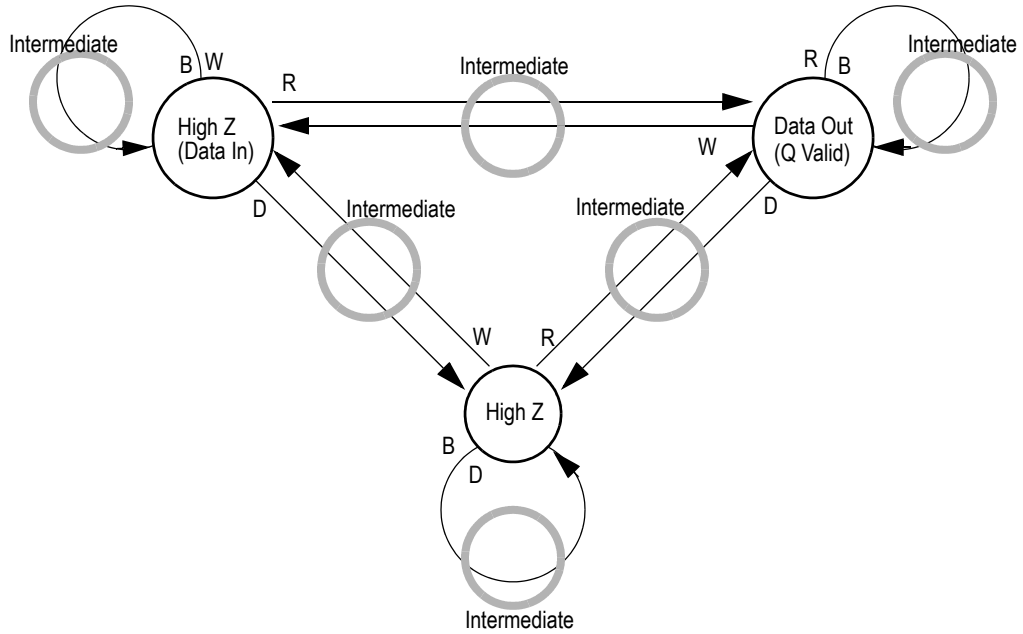
**Notes**

1. The Hold command ( $\overline{\text{CKE}}$  Low) is not shown because it prevents any state change.
2. W, R, B, and D represent input command codes as indicated in the Synchronous Truth Table.

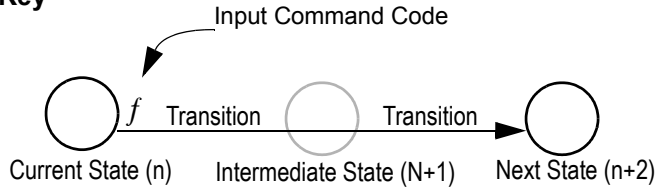


**Current State and Next State Definition for Pipelined and Flow through Read/Write Control State Diagram**

Pipeline Mode Data I/O State Diagram

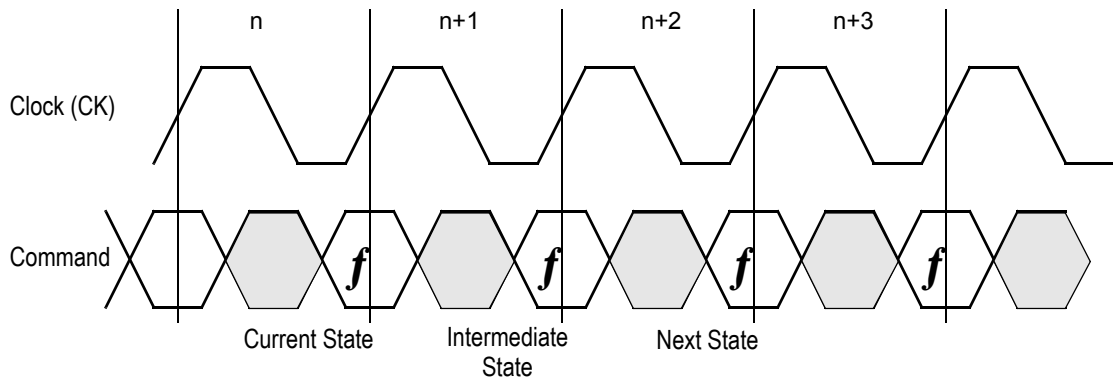


Key



Notes

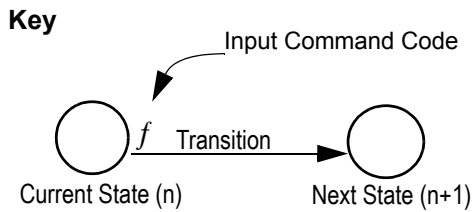
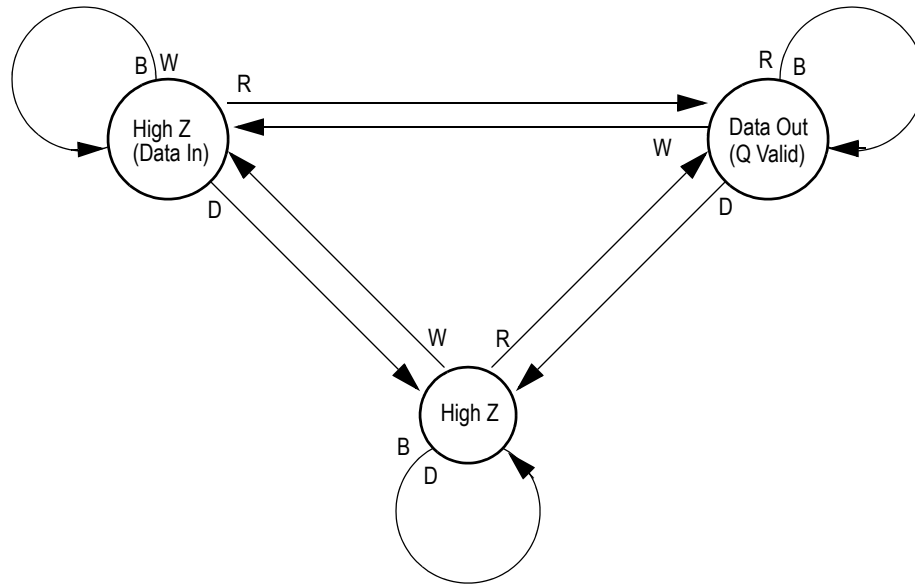
1. The Hold command ( $\overline{CKE}$  Low) is not shown because it prevents any state change.
2. W, R, B, and D represent input command codes as indicated in the Truth Tables.



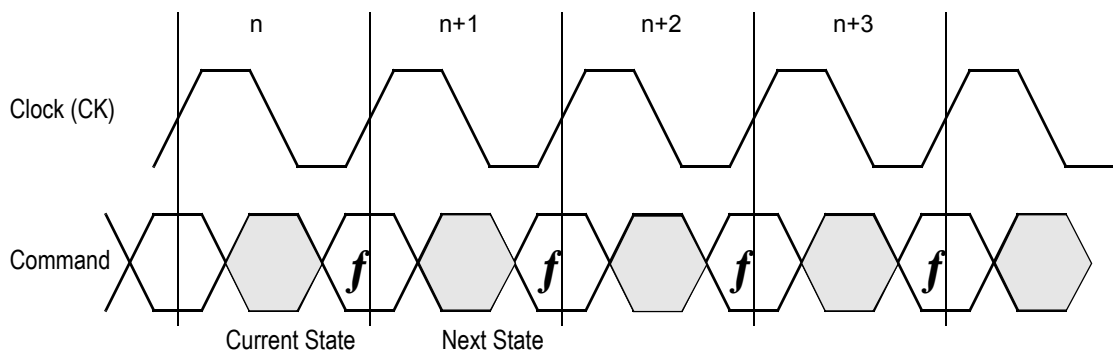
Current State and Next State Definition for Pipeline Mode Data I/O State Diagram



Flow Through Mode Data I/O State Diagram



- Notes**
1. The Hold command ( $\overline{CKE}$  Low) is not shown because it prevents any state change.
  2. W, R, B, and D represent input command codes as indicated in the Truth Tables.



Current State and Next State Definition for: Pipeline and Flow Through Read Write Control State Diagram

### Burst Cycles

Although NBT RAMs are designed to sustain 100% bus bandwidth by eliminating turnaround cycle when there is transition from read to write, multiple back-to-back reads or writes may also be performed. NBT SRAMs provide an on-chip burst address generator that can be utilized, if desired, to further simplify burst read or write implementations. The ADV control pin, when driven high, commands the SRAM to advance the internal address counter and use the counter generated address to read or write the SRAM. The starting address for the first cycle in a burst cycle series is loaded into the SRAM by driving the ADV pin low, into Load mode.

### Burst Order

The burst address counter wraps around to its initial state after four addresses (the loaded address and three more) have been accessed. The burst sequence is determined by the state of the Linear Burst Order pin ( $\overline{\text{LBO}}$ ). When this pin is Low, a linear burst sequence is selected. When the RAM is installed with the LBO pin tied high, Interleaved burst sequence is selected. See the tables below for details.

### FLXDrive™

The ZQ pin allows selection between NBT RAM nominal drive strength (ZQ low) for multi-drop bus applications and low drive strength (ZQ floating or high) point-to-point applications. See the Output Driver Characteristics chart for details.

### Mode Pin Functions

Mode Name	Pin Name	State	Function
Burst Order Control	$\overline{\text{LBO}}$	L	Linear Burst
		H	Interleaved Burst
Output Register Control	$\overline{\text{FT}}$	L	Flow Through
		H or NC	Pipeline
Power Down Control	ZZ	L or NC	Active
		H	Standby, $I_{DD} = I_{SB}$
FLXDrive Output Impedance Control	ZQ	L	High Drive (Low Impedance)
		H or NC	Low Drive (High Impedance)
9th Bit Enable	$\overline{\text{PE}}$	L	Activate DQPx I/Os (x72 mode)
		H or NC	Deactivate DQPx I/Os (x72 mode)

#### Note:

There are pull-up devices on the ZQ and  $\overline{\text{FT}}$  pins and a pull-down device on the ZZ pin, so those input pins can be unconnected and the chip will operate in the default states as specified in the above tables.

**Burst Counter Sequences**
**Linear Burst Sequence**

	A[1:0]	A[1:0]	A[1:0]	A[1:0]
1st address	00	01	10	11
2nd address	01	10	11	00
3rd address	10	11	00	01
4th address	11	00	01	10

**Note:**

The burst counter wraps to initial state on the 5th clock.

**Interleaved Burst Sequence**

	A[1:0]	A[1:0]	A[1:0]	A[1:0]
1st address	00	01	10	11
2nd address	01	00	11	10
3rd address	10	11	00	01
4th address	11	10	01	00

**Note:**

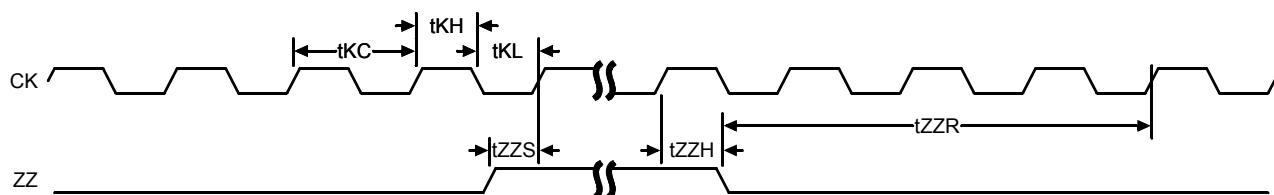
The burst counter wraps to initial state on the 5th clock.

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**Sleep Mode**

During normal operation, ZZ must be pulled low, either by the user or by its internal pull down resistor. When ZZ is pulled high, the SRAM will enter a Power Sleep mode after 2 cycles. At this time, internal state of the SRAM is preserved. When ZZ returns to low, the SRAM operates normally after ZZ recovery time.

Sleep mode is a low current, power-down mode in which the device is deselected and current is reduced to  $I_{SB2}$ . The duration of Sleep mode is dictated by the length of time the ZZ is in a High state. After entering Sleep mode, all inputs except ZZ become disabled and all outputs go to High-Z. The ZZ pin is an asynchronous, active high input that causes the device to enter Sleep mode. When the ZZ pin is driven high,  $I_{SB2}$  is guaranteed after the time  $t_{ZZI}$  is met. Because ZZ is an asynchronous input, pending operations or operations in progress may not be properly completed if ZZ is asserted. Therefore, Sleep mode must not be initiated until valid pending operations are completed. Similarly, when exiting Sleep mode during  $t_{ZZR}$ , only a Deselect or Read commands may be applied while the SRAM is recovering from Sleep mode.

**Sleep Mode Timing Diagram**

**Designing for Compatibility**

The GSI NBT SRAMs offer users a configurable selection between Flow Through mode and Pipeline mode via the  $\overline{FT}$  signal found on Bump 5R. Not all vendors offer this option, however most mark Bump 5R as  $V_{DD}$  or  $V_{DDQ}$  on pipelined parts and  $V_{SS}$  on flow through parts. GSI NBT SRAMs are fully compatible with these sockets.

**Absolute Maximum Ratings**

 (All voltages reference to  $V_{SS}$ )

Symbol	Description	Value	Unit
$V_{DD}$	Voltage on $V_{DD}$ Pins	-0.5 to 4.6	V
$V_{DDQ}$	Voltage in $V_{DDQ}$ Pins	-0.5 to 4.6	V
$V_{I/O}$	Voltage on I/O Pins	-0.5 to $V_{DDQ} + 0.5$ ( $\leq 4.6$ V max.)	V
$V_{IN}$	Voltage on Other Input Pins	-0.5 to $V_{DD} + 0.5$ ( $\leq 4.6$ V max.)	V
$I_{IN}$	Input Current on Any Pin	+/-20	mA
$I_{OUT}$	Output Current on Any I/O Pin	+/-20	mA
$P_D$	Package Power Dissipation	1.5	W
$T_{STG}$	Storage Temperature	-55 to 125	$^{\circ}C$
$T_{BIAS}$	Temperature Under Bias	-55 to 125	$^{\circ}C$

**Note:**

Permanent damage to the device may occur if the Absolute Maximum Ratings are exceeded. Operation should be restricted to Recommended Operating Conditions. Exposure to conditions exceeding the Absolute Maximum Ratings, for an extended period of time, may affect reliability of this component.

**Power Supply Voltage Ranges**

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
3.3 V Supply Voltage	$V_{DD3}$	3.0	3.3	3.6	V	
2.5 V Supply Voltage	$V_{DD2}$	2.3	2.5	2.7	V	
3.3 V $V_{DDQ}$ I/O Supply Voltage	$V_{DDQ3}$	3.0	3.3	3.6	V	
2.5 V $V_{DDQ}$ I/O Supply Voltage	$V_{DDQ2}$	2.3	2.5	2.7	V	

**Notes:**

1. The part numbers of Industrial Temperature Range versions end the character "I". Unless otherwise noted, all performance specifications quoted are evaluated for worst case in the temperature range marked on the device.
2. Input Under/overshoot voltage must be  $-2\text{ V} > V_i < V_{DDn} + 2\text{ V}$  not to exceed 4.6 V maximum, with a pulse width not to exceed 20% tKC.

**V<sub>DDQ3</sub> Range Logic Levels**

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
V <sub>DD</sub> Input High Voltage	V <sub>IH</sub>	2.0	—	V <sub>DD</sub> + 0.3	V	1
V <sub>DD</sub> Input Low Voltage	V <sub>IL</sub>	-0.3	—	0.8	V	1
V <sub>DDQ</sub> I/O Input High Voltage	V <sub>IHQ</sub>	2.0	—	V <sub>DDQ</sub> + 0.3	V	1,3
V <sub>DDQ</sub> I/O Input Low Voltage	V <sub>ILQ</sub>	-0.3	—	0.8	V	1,3

**Notes:**

1. The part numbers of Industrial Temperature Range versions end the character "I". Unless otherwise noted, all performance specifications quoted are evaluated for worst case in the temperature range marked on the device.
2. Input Under/overshoot voltage must be  $-2\text{ V} > V_i < V_{DDn} + 2\text{ V}$  not to exceed 4.6 V maximum, with a pulse width not to exceed 20% t<sub>KC</sub>.
3. V<sub>IHQ</sub> (max) is voltage on V<sub>DDQ</sub> pins plus 0.3 V.

**V<sub>DDQ2</sub> Range Logic Levels**

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
V <sub>DD</sub> Input High Voltage	V <sub>IH</sub>	0.6*V <sub>DD</sub>	—	V <sub>DD</sub> + 0.3	V	1
V <sub>DD</sub> Input Low Voltage	V <sub>IL</sub>	-0.3	—	0.3*V <sub>DD</sub>	V	1
V <sub>DDQ</sub> I/O Input High Voltage	V <sub>IHQ</sub>	0.6*V <sub>DD</sub>	—	V <sub>DDQ</sub> + 0.3	V	1,3
V <sub>DDQ</sub> I/O Input Low Voltage	V <sub>ILQ</sub>	-0.3	—	0.3*V <sub>DD</sub>	V	1,3

**Notes:**

1. The part numbers of Industrial Temperature Range versions end the character "I". Unless otherwise noted, all performance specifications quoted are evaluated for worst case in the temperature range marked on the device.
2. Input Under/overshoot voltage must be  $-2\text{ V} > V_i < V_{DDn} + 2\text{ V}$  not to exceed 4.6 V maximum, with a pulse width not to exceed 20% t<sub>KC</sub>.
3. V<sub>IHQ</sub> (max) is voltage on V<sub>DDQ</sub> pins plus 0.3 V.

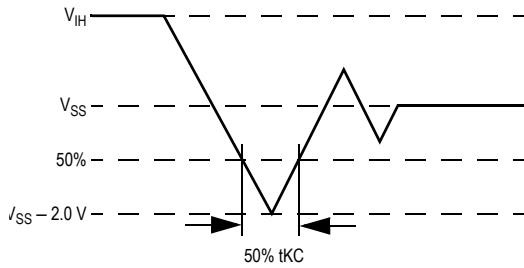
**Recommended Operating Temperatures**

Parameter	Symbol	Min.	Typ.	Max.	Unit	Notes
Ambient Temperature (Commercial Range Versions)	T <sub>A</sub>	0	25	70	°C	2
Ambient Temperature (Industrial Range Versions)	T <sub>A</sub>	-40	25	85	°C	2

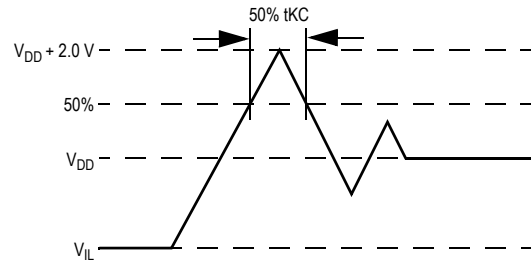
**Notes:**

1. The part numbers of Industrial Temperature Range versions end the character "I". Unless otherwise noted, all performance specifications quoted are evaluated for worst case in the temperature range marked on the device.
2. Input Under/overshoot voltage must be  $-2\text{ V} > V_i < V_{DDn} + 2\text{ V}$  not to exceed 4.6 V maximum, with a pulse width not to exceed 20% t<sub>KC</sub>.

### Undershoot Measurement and Timing



### Overshoot Measurement and Timing



### Capacitance

( $T_A = 25^\circ\text{C}$ ,  $f = 1\text{ MHz}$ ,  $V_{DD} = 2.5\text{ V}$ )

Parameter	Symbol	Test conditions	Typ.	Max.	Unit
Input Capacitance	$C_{IN}$	$V_{IN} = 0\text{ V}$	4	5	pF
Input/Output Capacitance	$C_{I/O}$	$V_{OUT} = 0\text{ V}$	6	7	pF

**Note:**

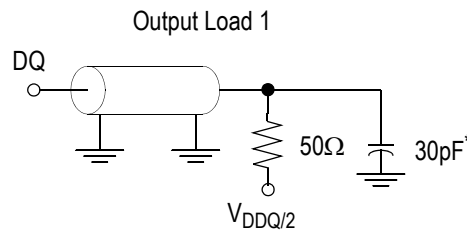
These parameters are sample tested.

### AC Test Conditions

Parameter	Conditions
Input high level	$V_{DD} - 0.2\text{ V}$
Input low level	$0.2\text{ V}$
Input slew rate	$1\text{ V/ns}$
Input reference level	$V_{DD}/2$
Output reference level	$V_{DDQ}/2$
Output load	<b>Fig. 1</b>

**Notes:**

1. Include scope and jig capacitance.
2. Test conditions as specified with output loading as shown in **Fig. 1** unless otherwise noted.
3. Device is deselected as defined by the Truth Table.



\* Distributed Test Jig Capacitance

**DC Electrical Characteristics**

Parameter	Symbol	Test Conditions	Min	Max
Input Leakage Current (except mode pins)	$I_{IL}$	$V_{IN} = 0 \text{ to } V_{DD}$	-1 $\mu\text{A}$	1 $\mu\text{A}$
ZZ Input Current	$I_{IN1}$	$V_{DD} \geq V_{IN} \geq V_{IH}$ $0 \text{ V} \leq V_{IN} \leq V_{IH}$	-1 $\mu\text{A}$ -1 $\mu\text{A}$	1 $\mu\text{A}$ 100 $\mu\text{A}$
$\overline{\text{FT}}$ , ZQ Input Current	$I_{IN2}$	$V_{DD} \geq V_{IN} \geq V_{IL}$ $0 \text{ V} \leq V_{IN} \leq V_{IL}$	-100 $\mu\text{A}$ -1 $\mu\text{A}$	1 $\mu\text{A}$ 1 $\mu\text{A}$
Output Leakage Current	$I_{OL}$	Output Disable, $V_{OUT} = 0 \text{ to } V_{DD}$	-1 $\mu\text{A}$	1 $\mu\text{A}$
Output High Voltage	$V_{OH2}$	$I_{OH} = -8 \text{ mA}$ , $V_{DDQ} = 2.375 \text{ V}$	1.7 V	—
Output High Voltage	$V_{OH3}$	$I_{OH} = -8 \text{ mA}$ , $V_{DDQ} = 3.135 \text{ V}$	2.4 V	—
Output Low Voltage	$V_{OL}$	$I_{OL} = 8 \text{ mA}$	—	0.4 V

**Operating Currents**

Parameter	Test Conditions	Mode	Symbol	-200		-166		-150		-133		Unit	
				0 to 70°C	-40 to 85°C	0 to 70°C	-40 to 85°C	0 to 70°C	-40 to 85°C	0 to 70°C	-40 to 85°C		
Operating Current <b>3.3 V</b>	Device Selected; All other inputs $\geq V_{IH}$ or $\leq V_{IL}$ Output open	(x72)	Pipeline	$I_{DD}$	290	300	250	260	225	235	205	215	mA
				$I_{DDQ}$	60	60	50	50	45	45	40	40	
			Flow Through	$I_{DD}$	195	205	185	195	180	190	165	175	mA
				$I_{DDQ}$	30	30	30	30	30	30	20	20	
Operating Current <b>2.5 V</b>	Device Selected; All other inputs $\geq V_{IH}$ or $\leq V_{IL}$ Output open	(x72)	Pipeline	$I_{DD}$	290	300	250	260	225	235	205	215	mA
				$I_{DDQ}$	45	45	40	40	35	35	30	30	
			Flow Through	$I_{DD}$	195	205	185	195	180	190	165	175	mA
				$I_{DDQ}$	30	30	30	30	30	30	20	20	
Standby Current	$ZZ \geq V_{DD} - 0.2 V$	—	Pipeline	$I_{SB}$	20	30	20	30	20	30	20	30	mA
			Flow Through	$I_{SB}$	20	30	20	30	20	30	20	30	mA
Deselect Current	Device Deselected; All other inputs $\geq V_{IH}$ or $\leq V_{IL}$	—	Pipeline	$I_{DD}$	75	80	64	70	60	65	50	55	mA
			Flow Through	$I_{DD}$	50	55	50	55	50	55	45	50	mA

**Notes:**

- $I_{DD}$  and  $I_{DDQ}$  apply to any combination of  $V_{DD3}$ ,  $V_{DD2}$ ,  $V_{DDQ3}$ , and  $V_{DDQ2}$  operation.
- All parameters listed are worst case scenario.



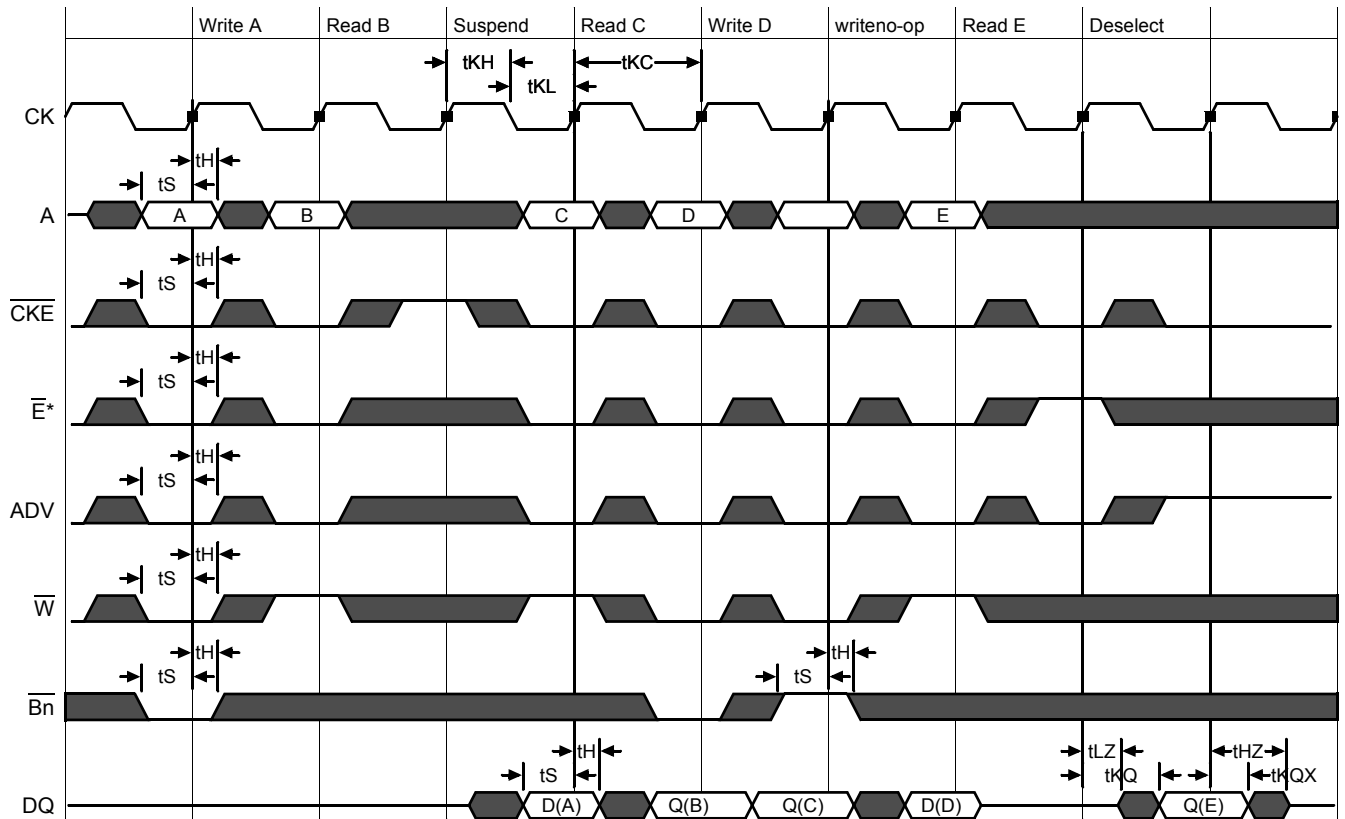
**AC Electrical Characteristics**

	Parameter	Symbol	-200		-166		-150		-133		Unit
			Min	Max	Min	Max	Min	Max	Min	Max	
<b>Pipeline</b>	Clock Cycle Time	t <sub>KC</sub>	5.0	—	6.0	—	6.7	—	7.5	—	ns
	Clock to Output Valid	t <sub>KQ</sub>	—	3.0	—	3.4	—	3.8	—	4.0	ns
	Clock to Output Invalid	t <sub>KQX</sub>	1.5	—	1.5	—	1.5	—	1.5	—	ns
	Clock to Output in Low-Z	t <sub>LZ</sub> <sup>1</sup>	1.5	—	1.5	—	1.5	—	1.5	—	ns
	Setup time	t <sub>S</sub>	1.4	—	1.5	—	1.5	—	1.5	—	ns
	Hold time	t <sub>H</sub>	0.4	—	0.5	—	0.5	—	0.5	—	ns
<b>Flow Through</b>	Clock Cycle Time	t <sub>KC</sub>	6.5	—	7.0	—	7.5	—	8.5	—	ns
	Clock to Output Valid	t <sub>KQ</sub>	—	6.5	—	7.0	—	7.5	—	8.5	ns
	Clock to Output Invalid	t <sub>KQX</sub>	3.0	—	3.0	—	3.0	—	3.0	—	ns
	Clock to Output in Low-Z	t <sub>LZ</sub> <sup>1</sup>	3.0	—	3.0	—	3.0	—	3.0	—	ns
	Setup time	t <sub>S</sub>	1.5	—	1.5	—	1.5	—	1.5	—	ns
	Hold time	t <sub>H</sub>	0.5	—	0.5	—	0.5	—	0.5	—	ns
	Clock HIGH Time	t <sub>KH</sub>	1.3	—	1.3	—	1.5	—	1.7	—	ns
	Clock LOW Time	t <sub>KL</sub>	1.5	—	1.5	—	1.7	—	2	—	ns
	Clock to Output in High-Z	t <sub>HZ</sub> <sup>1</sup>	1.5	3.0	1.5	3.0	1.5	3.0	1.5	3.0	ns
	$\bar{G}$ to Output Valid	t <sub>OE</sub>	—	3.2	—	3.5	—	3.8	—	4.0	ns
	$\bar{G}$ to output in Low-Z	t <sub>OLZ</sub> <sup>1</sup>	0	—	0	—	0	—	0	—	ns
	$\bar{G}$ to output in High-Z	t <sub>OHZ</sub> <sup>1</sup>	—	3.0	—	3.0	—	3.0	—	3.0	ns
	ZZ setup time	t <sub>ZZS</sub> <sup>2</sup>	5	—	5	—	5	—	5	—	ns
	ZZ hold time	t <sub>ZZH</sub> <sup>2</sup>	1	—	1	—	1	—	1	—	ns
	ZZ recovery	t <sub>ZZR</sub>	20	—	20	—	20	—	20	—	ns

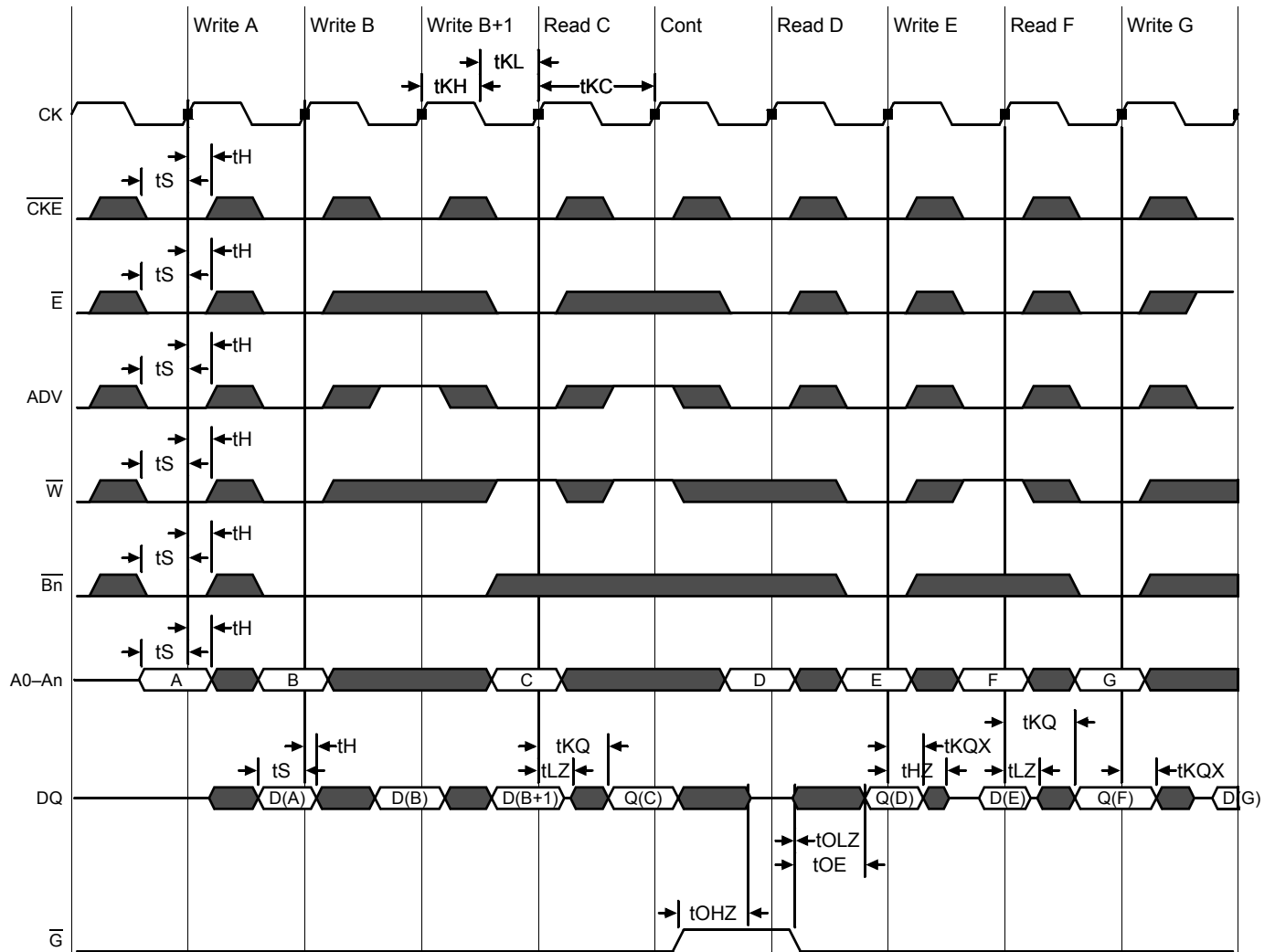
**Notes:**

1. These parameters are sampled and are not 100% tested.
2. ZZ is an asynchronous signal. However, in order to be recognized on any given clock cycle, ZZ must meet the specified setup and hold times as specified above.

### Pipeline Mode Timing (NBT)



Flow Through Mode Timing (NBT)



\*Note:  $\bar{E}$  = High(False) if  $\bar{E}1 = 1$  or  $E2 = 0$  or  $\bar{E}3 = 1$

## JTAG Port Operation

### Overview

The JTAG Port on this RAM operates in a manner that is compliant with IEEE Standard 1149.1-1990, a serial boundary scan interface standard (commonly referred to as JTAG). The JTAG Port input interface levels scale with  $V_{DD}$ . The JTAG output drivers are powered by  $V_{DDQ}$ .

### Disabling the JTAG Port

It is possible to use this device without utilizing the JTAG port. The port is reset at power-up and will remain inactive unless clocked. TCK, TDI, and TMS are designed with internal pull-up circuits. To assure normal operation of the RAM with the JTAG Port unused, TCK, TDI, and TMS may be left floating or tied to either  $V_{DD}$  or  $V_{SS}$ . TDO should be left unconnected.

## JTAG Port Registers

### JTAG Pin Descriptions

Pin	Pin Name	I/O	Description
TCK	Test Clock	In	Clocks all TAP events. All inputs are captured on the rising edge of TCK and all outputs propagate from the falling edge of TCK.
TMS	Test Mode Select	In	The TMS input is sampled on the rising edge of TCK. This is the command input for the TAP controller state machine. An undriven TMS input will produce the same result as a logic one input level.
TDI	Test Data In	In	The TDI input is sampled on the rising edge of TCK. This is the input side of the serial registers placed between TDI and TDO. The register placed between TDI and TDO is determined by the state of the TAP Controller state machine and the instruction that is currently loaded in the TAP Instruction Register (refer to the TAP Controller State Diagram). An undriven TDI pin will produce the same result as a logic one input level.
TDO	Test Data Out	Out	Output that is active depending on the state of the TAP state machine. Output changes in response to the falling edge of TCK. This is the output side of the serial registers placed between TDI and TDO.

#### Note:

This device does not have a TRST (TAP Reset) pin. TRST is optional in IEEE 1149.1. The Test-Logic-Reset state is entered while TMS is held high for five rising edges of TCK. The TAP Controller is also reset automatically at power-up.

### Overview

The various JTAG registers, referred to as Test Access Port or TAP Registers, are selected (one at a time) via the sequences of 1s and 0s applied to TMS as TCK is strobed. Each of the TAP Registers is a serial shift register that captures serial input data on the rising edge of TCK and pushes serial data out on the next falling edge of TCK. When a register is selected, it is placed between the TDI and TDO pins.

### Instruction Register

The Instruction Register holds the instructions that are executed by the TAP controller when it is moved into the Run, Test/Idle, or the various data register states. Instructions are 3 bits long. The Instruction Register can be loaded when it is placed between the TDI and TDO pins. The Instruction Register is automatically preloaded with the IDCODE instruction at power-up or whenever the controller is placed in Test-Logic-Reset state.

### Bypass Register

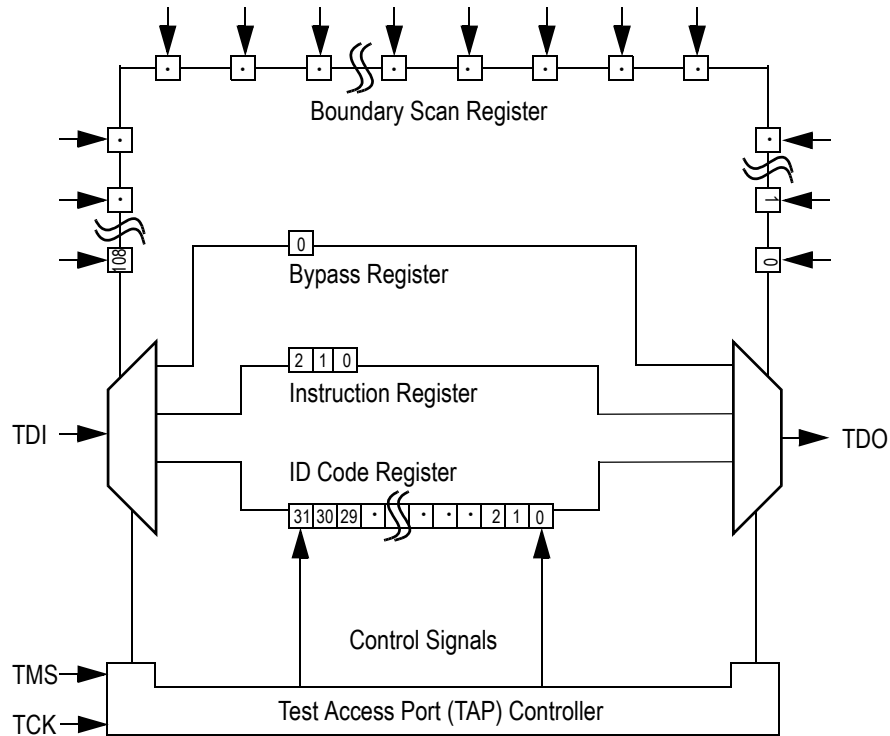
The Bypass Register is a single bit register that can be placed between TDI and TDO. It allows serial test data to be passed through the RAM's JTAG Port to another device in the scan chain with as little delay as possible.

### Boundary Scan Register

The Boundary Scan Register is a collection of flip flops that can be preset by the logic level found on the RAM's input or I/O pins. The flip flops are then daisy chained together so the levels found can be shifted serially out of the JTAG Port's TDO pin. The Boundary Scan Register also includes a number of place holder flip flops (always set to a logic 1). The relationship between the

device pins and the bits in the Boundary Scan Register is described in the Scan Order Table following. The Boundary Scan Register, under the control of the TAP Controller, is loaded with the contents of the RAMs I/O ring when the controller is in Capture-DR state and then is placed between the TDI and TDO pins when the controller is moved to Shift-DR state. SAMPLE-Z, SAMPLE/PRELOAD and EXTEST instructions can be used to activate the Boundary Scan Register.

### JTAG TAP Block Diagram



#### Identification (ID) Register

The ID Register is a 32-bit register that is loaded with a device and vendor specific 32-bit code when the controller is put in Capture-DR state with the IDCODE command loaded in the Instruction Register. The code is loaded from a 32-bit on-chip ROM. It describes various attributes of the RAM as indicated below. The register is then placed between the TDI and TDO pins when the controller is moved into Shift-DR state. Bit 0 in the register is the LSB and the first to reach TDO when shifting begins.

**Tap Controller Instruction Set  
ID Register Contents**

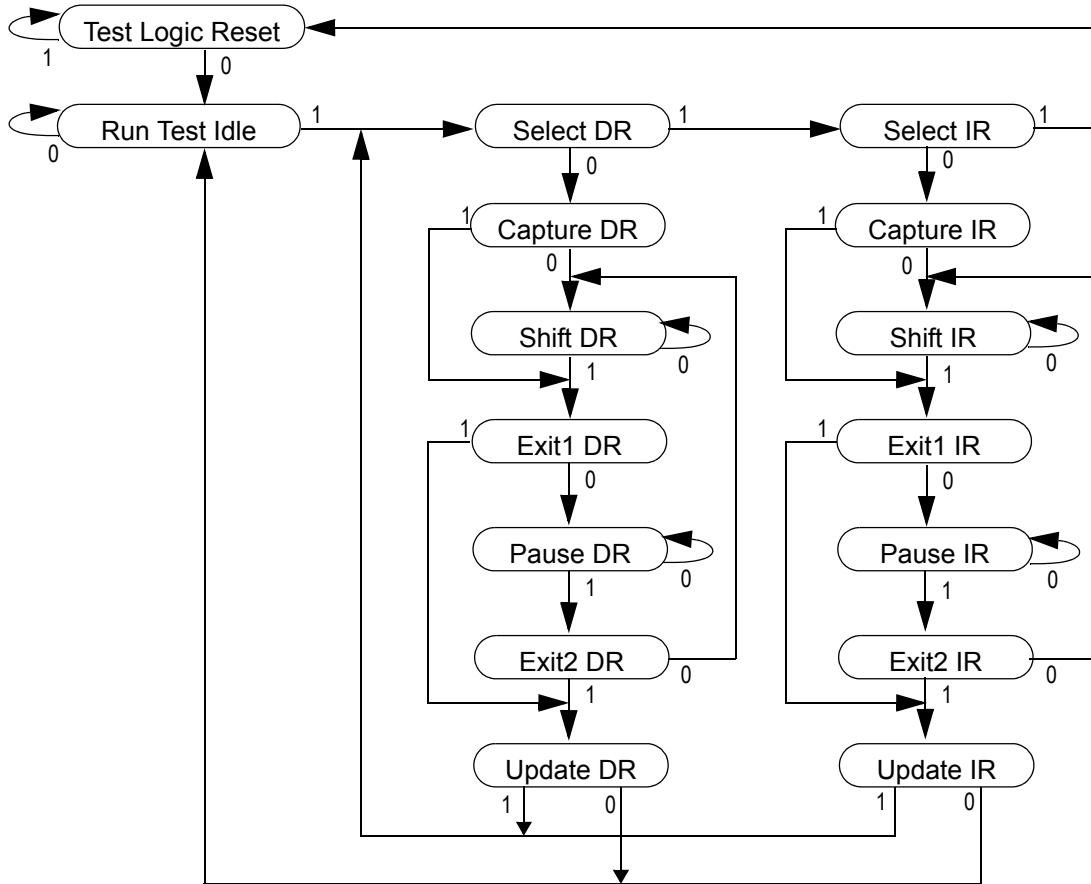
Bit #	Die Revision Code				Not Used												I/O Configuration				GSI Technology JEDEC Vendor ID Code								Presence Register			
	31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4		3	2	1
x72	X	X	X	X	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	1	0	0	0	1	1	0	1	1	0	0	1	1

**Overview**

There are two classes of instructions defined in the Standard 1149.1-1990; the standard (Public) instructions, and device specific (Private) instructions. Some Public instructions are mandatory for 1149.1 compliance. Optional Public instructions must be implemented in prescribed ways. The TAP on this device may be used to monitor all input and I/O pads, and can be used to load address, data or control signals into the RAM or to preload the I/O buffers.

When the TAP controller is placed in Capture-IR state the two least significant bits of the instruction register are loaded with 01. When the controller is moved to the Shift-IR state the Instruction Register is placed between TDI and TDO. In this state the desired instruction is serially loaded through the TDI input (while the previous contents are shifted out at TDO). For all instructions, the TAP executes newly loaded instructions only when the controller is moved to Update-IR state. The TAP instruction set for this device is listed in the following table.

## JTAG Tap Controller State Diagram


**Instruction Descriptions**
**BYPASS**

When the BYPASS instruction is loaded in the Instruction Register the Bypass Register is placed between TDI and TDO. This occurs when the TAP controller is moved to the Shift-DR state. This allows the board level scan path to be shortened to facilitate testing of other devices in the scan path.

**SAMPLE/PRELOAD**

SAMPLE/PRELOAD is a Standard 1149.1 mandatory public instruction. When the SAMPLE / PRELOAD instruction is loaded in the Instruction Register, moving the TAP controller into the Capture-DR state loads the data in the RAMs input and I/O buffers into the Boundary Scan Register. Boundary Scan Register locations are not associated with an input or I/O pin, and are loaded with the default state identified in the Boundary Scan Chain table at the end of this section of the datasheet. Because the RAM clock is independent from the TAP Clock (TCK) it is possible for the TAP to attempt to capture the I/O ring contents while the input buffers are in transition (i.e. in a metastable state). Although allowing the TAP to sample metastable inputs will not harm the device, repeatable results cannot be expected. RAM input signals must be stabilized for long enough to meet the TAPs input data capture set-up plus hold time (tTS plus tTH). The RAMs clock inputs need not be paused for any other TAP operation except capturing the I/O ring contents into the Boundary Scan Register. Moving the controller to Shift-DR state then places the boundary scan register between the TDI and TDO pins.

**EXTEST**

EXTEST is an IEEE 1149.1 mandatory public instruction. It is to be executed whenever the instruction register is loaded with all logic 0s. The EXTEST command does not block or override the RAM's input pins; therefore, the RAM's internal state is still determined by its input pins.

Typically, the Boundary Scan Register is loaded with the desired pattern of data with the SAMPLE/PRELOAD command. Then the EXTEST command is used to output the Boundary Scan Register's contents, in parallel, on the RAM's data output drivers on the falling edge of TCK when the controller is in the Update-IR state.

Alternately, the Boundary Scan Register may be loaded in parallel using the EXTEST command. When the EXTEST instruction is selected, the state of all the RAM's input and I/O pins, as well as the default values at Scan Register locations not associated with a pin, are transferred in parallel into the Boundary Scan Register on the rising edge of TCK in the Capture-DR state, the RAM's output pins drive out the value of the Boundary Scan Register location with which each output pin is associated.

#### **IDCODE**

The IDCODE instruction causes the ID ROM to be loaded into the ID register when the controller is in Capture-DR mode and places the ID register between the TDI and TDO pins in Shift-DR mode. The IDCODE instruction is the default instruction loaded in at power up and any time the controller is placed in the Test-Logic-Reset state.

#### **SAMPLE-Z**

If the SAMPLE-Z instruction is loaded in the instruction register, all RAM outputs are forced to an inactive drive state (high-Z) and the Boundary Scan Register is connected between TDI and TDO when the TAP controller is moved to the Shift-DR state.

#### **RFU**

These instructions are Reserved for Future Use. In this device they replicate the BYPASS instruction.

### **JTAG TAP Instruction Set Summary**

<b>Instruction</b>	<b>Code</b>	<b>Description</b>	<b>Notes</b>
EXTEST	000	Places the Boundary Scan Register between TDI and TDO.	1
IDCODE	001	Preloads ID Register and places it between TDI and TDO.	1, 2
SAMPLE-Z	010	Captures I/O ring contents. Places the Boundary Scan Register between TDI and TDO. Forces all RAM output drivers to High-Z.	1
RFU	011	Do not use this instruction; Reserved for Future Use. Replicates BYPASS instruction. Places Bypass Register between TDI and TDO.	1
SAMPLE/ PRELOAD	100	Captures I/O ring contents. Places the Boundary Scan Register between TDI and TDO.	1
GSI	101	GSI private instruction.	1
RFU	110	Do not use this instruction; Reserved for Future Use. Replicates BYPASS instruction. Places Bypass Register between TDI and TDO.	1
BYPASS	111	Places Bypass Register between TDI and TDO.	1

#### **Notes:**

1. Instruction codes expressed in binary, MSB on left, LSB on right.
2. Default instruction automatically loaded at power-up and in test-logic-reset state.



**JTAG Port Recommended Operating Conditions and DC Characteristics**

Parameter	Symbol	Min.	Max.	Unit	Notes
3.3 V Test Port Input High Voltage	$V_{IHJ3}$	2.0	$V_{DD3} + 0.3$	V	1
3.3 V Test Port Input Low Voltage	$V_{ILJ3}$	-0.3	0.8	V	1
2.5 V Test Port Input High Voltage	$V_{IHJ2}$	$0.6 * V_{DD2}$	$V_{DD2} + 0.3$	V	1
2.5 V Test Port Input Low Voltage	$V_{ILJ2}$	-0.3	$0.3 * V_{DD2}$	V	1
TMS, TCK and TDI Input Leakage Current	$I_{INHJ}$	-300	1	uA	2
TMS, TCK and TDI Input Leakage Current	$I_{INLJ}$	-1	100	uA	3
TDO Output Leakage Current	$I_{OLJ}$	-1	1	uA	4
Test Port Output High Voltage	$V_{OHJ}$	1.7	—	V	5, 6
Test Port Output Low Voltage	$V_{OLJ}$	—	0.4	V	5, 7
Test Port Output CMOS High	$V_{OHJC}$	$V_{DDQ} - 100$ mV	—	V	5, 8
Test Port Output CMOS Low	$V_{OLJC}$	—	100 mV	V	5, 9

**Notes:**

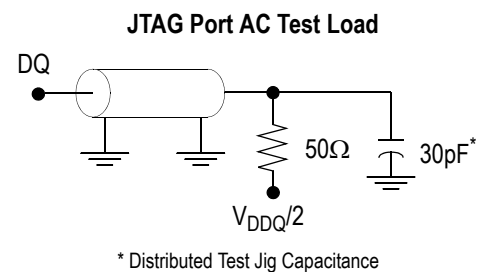
- Input Under/overshoot voltage must be  $-2\text{ V} < V_i < V_{DDn} + 2\text{ V}$  not to exceed 4.6 V maximum, with a pulse width not to exceed 20% tTKC.
- $V_{ILJ} \leq V_{IN} \leq V_{DDn}$
- $0\text{ V} \leq V_{IN} \leq V_{ILJn}$
- Output Disable,  $V_{OUT} = 0$  to  $V_{DDn}$
- The TDO output driver is served by the  $V_{DDQ}$  supply.
- $I_{OHJ} = -4\text{ mA}$
- $I_{OLJ} = +4\text{ mA}$
- $I_{OHJC} = -100\text{ uA}$
- $I_{OLJC} = +100\text{ uA}$

**JTAG Port AC Test Conditions**

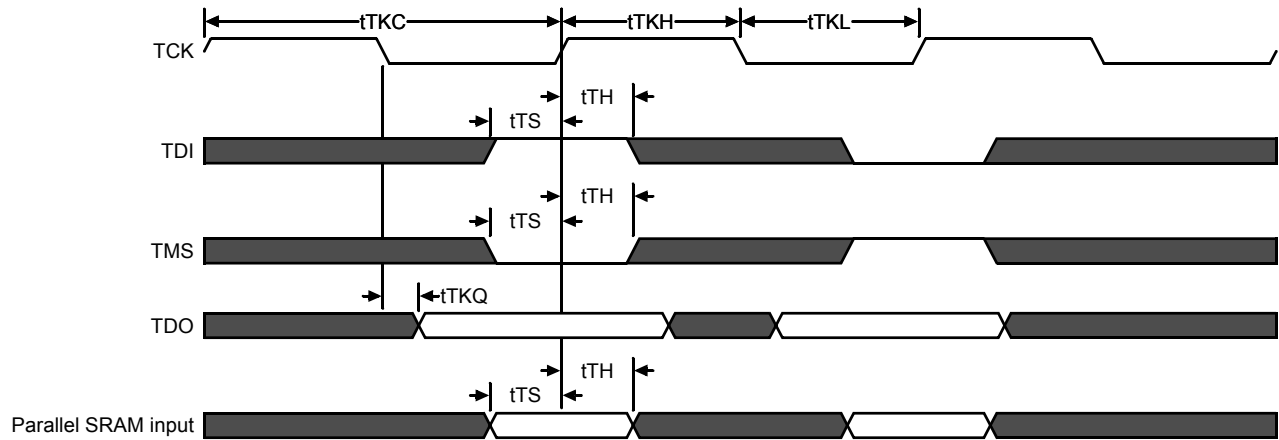
Parameter	Conditions
Input high level	$V_{DD} - 0.2\text{ V}$
Input low level	0.2 V
Input slew rate	1 V/ns
Input reference level	$V_{DDQ}/2$
Output reference level	$V_{DDQ}/2$

**Notes:**

- Include scope and jig capacitance.
- Test conditions as shown unless otherwise noted.



### JTAG Port Timing Diagram



### JTAG Port AC Electrical Characteristics

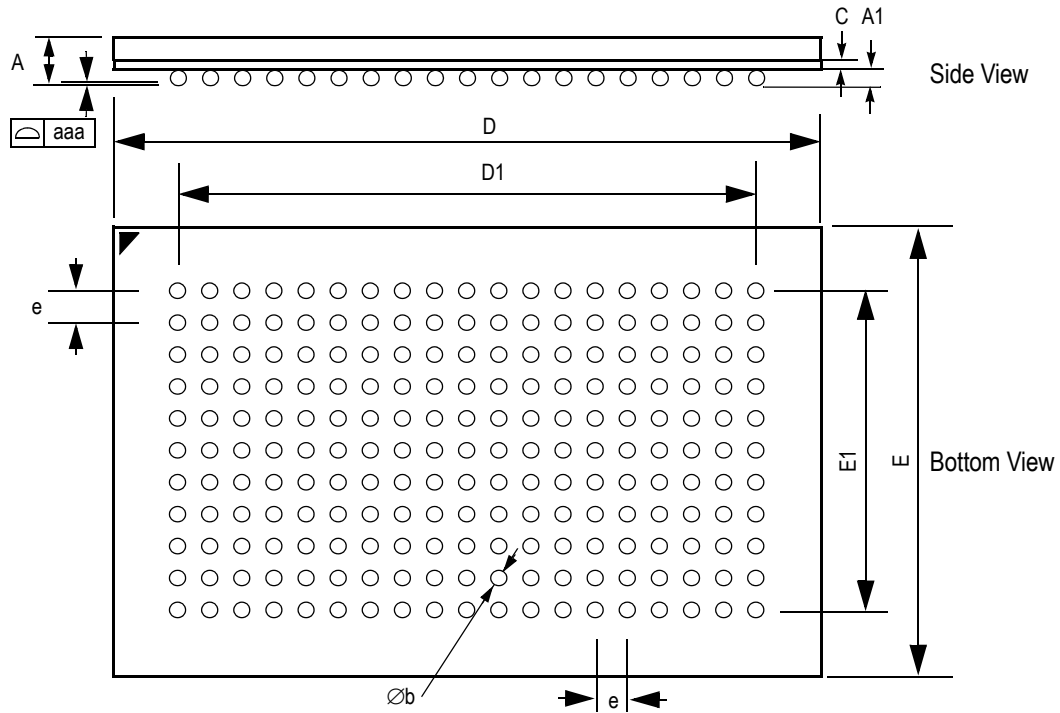
Parameter	Symbol	Min	Max	Unit
TCK Cycle Time	$t_{TKC}$	50	—	ns
TCK Low to TDO Valid	$t_{TKQ}$	—	20	ns
TCK High Pulse Width	$t_{TKH}$	20	—	ns
TCK Low Pulse Width	$t_{TKL}$	20	—	ns
TDI & TMS Set Up Time	$t_{TS}$	10	—	ns
TDI & TMS Hold Time	$t_{TH}$	10	—	ns

#### Boundary Scan (BSDL Files)

For information regarding the Boundary Scan Chain, or to obtain BSDL files for this part, please contact our Applications Engineering Department at: [apps@gsitechnology.com](mailto:apps@gsitechnology.com).

**209 BGA Package Drawing (Package C)**

14 mm x 22 mm Body, 1.0 mm Bump Pitch, 11 x 19 Bump Array



Symbol	Min	Typ	Max	Units	Symbol	Min	Typ	Max	Units
A	—	—	1.70	mm	D1	—	18.0 (BSC)	—	mm
A1	0.40	0.50	0.60	mm	E	13.9	14.0	14.1	mm
Øb	0.50	0.60	0.70	mm	E1	—	10.0 (BSC)	—	mm
c	0.31	0.36	0.38	mm	e	—	1.00 (BSC)	—	mm
D	21.9	22.0	22.1	mm	aaa	—	0.15	—	mm

Rev 1.0

**Ordering Information—GSI NBT Synchronous SRAM**

Org	Part Number <sup>1</sup>	Type	Package	Speed <sup>2</sup> (MHz/ns)	T <sub>A</sub> <sup>3</sup>	Status
256K x 72	GS8162Z72C-200	NBT Pipeline/Flow Through	209 BGA	200/6.5	C	
256K x 72	GS8162Z72C-166	NBT Pipeline/Flow Through	209 BGA	166/7	C	
256K x 72	GS8162Z72C-150	NBT Pipeline/Flow Through	209 BGA	150/7.5	C	
256K x 72	GS8162Z72C-133	NBT Pipeline/Flow Through	209 BGA	133/8.5	C	
256K x 72	GS8162Z72C-200I	NBT Pipeline/Flow Through	209 BGA	200/6.5	I	
256K x 72	GS8162Z72C-166I	NBT Pipeline/Flow Through	209 BGA	166/7	I	
256K x 72	GS8162Z72C-150I	NBT Pipeline/Flow Through	209 BGA	150/7.5	I	
256K x 72	GS8162Z72C-133I	NBT Pipeline/Flow Through	209 BGA	133/8.5	I	

**Notes:**

1. Customers requiring delivery in Tape and Reel should add the character "T" to the end of the part number. Example: GS8162Z72-200IT.
2. The speed column indicates the cycle frequency (MHz) of the device in Pipeline mode and the latency (ns) in Flow Through mode. Each device is Pipeline/Flow Through mode-selectable by the user.
3. T<sub>A</sub> = C = Commercial Temperature Range. T<sub>A</sub> = I = Industrial Temperature Range.
4. GSI offers other versions this type of device in many different configurations and with a variety of different features, only some of which are covered in this data sheet. See the GSI Technology web site ([www.gsitechnology.com](http://www.gsitechnology.com)) for a complete listing of current offerings

**18Mb Sync SRAM Datasheet Revision History**

<b>DS/DateRev. Code: Old; New</b>	<b>Types of Changes Format or Content</b>	<b>Page;Revisions;Reason</b>
GS8162Z18/36/72B 1.00 9/ 1999A;GS8162Z18/36/ 72B2.0012/1999B	Content	<ul style="list-style-type: none"> <li>• Converted from 0.25u 3.3V process to 0.18u 2.5V process. Master File Rev B</li> <li>• Added x72 Pinout.</li> </ul>
GS8162Z18/36/72B2.00 12/ 1999BGS8162Z18/36/ 72B2.01 1/2000C	Format	<ul style="list-style-type: none"> <li>• Added new GSI Logo</li> </ul>
GS8162Z18/36/72B2.01 1/ 2000C;GS8162Z18/36/ 72B2.02 1/2000D	Content	<ul style="list-style-type: none"> <li>• Added 209 Pin BGA Package diagram</li> </ul>
GS8162Z18/36/72B2.02 1/ 2000DGS8162Z18/36/ 72B2.03 2/2000E		<ul style="list-style-type: none"> <li>• Front page; Features - changed 2.5V I/O supply to 2.5V or 3.3V I/O supply; Completeness</li> <li>• Absolute Maximum Ratings; Changed VDDQ - Value: From: -.05 to VDD : to : -.05 to 3.6; Completeness.</li> <li>• Recommended Operating Conditions; Changed: I/O Supply Voltage- Max. from VDD to 3.6; Input High Voltage- Max. from VDD +0.3 to 3.6; Same page - took out Note 1; Completeness</li> <li>• Electrical Characteristics - Added second Output High Voltage line to table; completeness.</li> <li>• Note: There was not a Rev 2.02 for the 8160Z or the 8161Z.</li> </ul>
GS8162Z18/36/72B2.03 2/ 2000E; 8162Z18_r2_04	Content	<ul style="list-style-type: none"> <li>• Pin 6N changed to MCH.</li> </ul>
8162Z18_r2_04; 8162Z18_r2_05	Content	<ul style="list-style-type: none"> <li>• Updated BGA pin description tables to meet JEDEC standards</li> </ul>
8162Z18_r2_05; 8162Z18_42_06	Content	<ul style="list-style-type: none"> <li>• Changed the value of ZZ recovery in the AC Electrical Characteristics table on page 22 from 20 ns to 100 ns</li> </ul>
8162Z18_r2_06; 8162Z18_r2_07	Content/Format	<ul style="list-style-type: none"> <li>• Added 225 MHz speed bin</li> <li>• Updated numbers in page 1 table, AC Characteristics table, and Operating Currents table</li> <li>• Updated format to comply with Technical Publications standards</li> </ul>
8162Z18_r2_07; 8162Z18_r2_08	Content	<ul style="list-style-type: none"> <li>• Changed V<sub>SSQ</sub> references to V<sub>SS</sub></li> <li>• Changed K4 and K8 in 209-bump BGA to NC</li> </ul>
8162Z18_r2_08; 8162Z18_r2_09	Content	<ul style="list-style-type: none"> <li>• Updated numbers for Clock to Output Valid (PL) and Clock to Output Valid (FT) for 166 MHz and 133 MHz on AC Electrical Characteristics table</li> </ul>
8162Z18_r2_09; 8162Z18_r2_10	Content	<ul style="list-style-type: none"> <li>• Updated Features list on page 1</li> <li>• Completely reworked table on page 1</li> <li>• Updated Mode Pin Functions table on page 14</li> </ul>

**18Mb Sync SRAM Datasheet Revision History**

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8162Z18_r2_10; 8162Z18_r2_11	Content	<ul style="list-style-type: none"> <li>• Added 3.3 V references to entire document</li> <li>• Updated Operating Conditions table</li> <li>• Updated JTAG section</li> <li>• Updated Operating Currents table and added note</li> <li>• Updated Boundary Scan Chain table</li> <li>• Updated table on page 1; added power numbers</li> </ul>
8162Z18_r2_11; 8162Z18_r2_11	Content	<ul style="list-style-type: none"> <li>• Updated DQ on page 24</li> <li>• Updated DQ on page 26 (Q(A3))</li> <li>• Updated ID Register Contents table</li> <li>• Updated Operating Currents table</li> <li>• Updated power numbers in table on page 1</li> <li>• Updated Recommended Operating Conditions table (added <math>V_{DDQ}</math> references)</li> </ul>
8162Z18_r2_12; 8162Z18_r2_13	Content	<ul style="list-style-type: none"> <li>• Updated table on page 1</li> <li>• Added 119-Bump BGA Pin Description table</li> <li>• Created recommended operating conditions tables on pages 19 and 20</li> <li>• Updated AC Electrical Characteristics table</li> <li>• Updated Ordering Information for 225 MHz part (changed from 7ns to 6.5 ns)</li> <li>• Updated BSR table (2 and 3 changed to X (value undefined))</li> <li>• Added 250 MHz speed bin</li> <li>• Deleted 180 MHz speed bin</li> </ul>
8162Z18_r2_13; 8162Z18_r2_14	Content	<ul style="list-style-type: none"> <li>• Added parity bit references to x18 pad out and pin description table</li> <li>• Updated x36 pinout (DQA pins listed twice)</li> </ul>
8162Z18_r2_14; 8162Z18_r2_15	Content	<ul style="list-style-type: none"> <li>• Updated pin description tables to match pinouts</li> </ul>
8162Z18_r2_15; 8162Z18_r2_16	Content	<ul style="list-style-type: none"> <li>• Updated Flow Through power numbers in table on page 1 and Operating Currents table</li> <li>• Updated Pipeline and Flow Through numbers in AC Characteristics table</li> <li>• Added 165-bump BGA package, pinout, and pinout description</li> <li>• Removed ByteSafe pins and references</li> <li>• Updated AC Test Conditions table and removed Output Load 2 diagram</li> </ul>
8162Z18_r2_16; 8162Z18_r2_17	Content	<ul style="list-style-type: none"> <li>• Removed parity I/O bit designation from 165 BGA pinout</li> <li>• Updated both 209 BGA and 119 BGA pin description tables</li> <li>• Removed pin locations from pin description tables</li> <li>• Removed Preliminary banner</li> <li>• Removed BSR table</li> </ul>

**18Mb Sync SRAM Datasheet Revision History**

DS/DateRev. Code: Old; New	Types of Changes Format or Content	Page;Revisions;Reason
8162Z18_r2_17; 8162Z18_r2_18	Content	<ul style="list-style-type: none"> <li>• Removed 250 MHz and 225 MHz specs from x72</li> <li>• Updated AC Characteristics table (tHZ, tOE, tOHZ equal to tKQ (PL) for 250 MHz and 225 MHz)</li> <li>• Added new timing diagrams</li> <li>• Added specific address locations to 165 BGA</li> </ul>
8162Z18_r2_18; 8162Z18_r2_19	Content	<ul style="list-style-type: none"> <li>• Corrected 209 BGA pin description table (removed BW reference and replaced with ADV reference)</li> </ul>
8162Z18_r2_19; 8162Z18_r2_20	Content	<ul style="list-style-type: none"> <li>• Corrected incorrect DQ designations for x36 "B"</li> </ul>
8162Z18_r2_20; 8162Z18_r2_21	Content	<ul style="list-style-type: none"> <li>• Updated format</li> <li>• Updated timing diagrams</li> <li>• Updated truth table</li> </ul>
8162Z18_r2_21; 8162Z18_r2_22	Content	<ul style="list-style-type: none"> <li>• Separated x18/x36 out of document</li> </ul>