

### FEATURES

#### High speed

190 MHz, -3 dB bandwidth ( $G = +1$ )

100 V/ $\mu$ s slew rate

#### Low distortion

120 dBc @ 1 MHz SFDR

80 dBc @ 5 MHz SFDR

#### Selectable input crossover threshold

#### Low noise

4.3 nV/ $\sqrt{\text{Hz}}$

1.6 pA/ $\sqrt{\text{Hz}}$

#### Low offset voltage: 900 $\mu$ V max

#### Low power: 6.5 mA/amplifier supply current

#### Power-down mode

#### No phase reversal: $V_{IN} > |V_S| + 200$ mV

#### Wide supply range: 2.7 V to 12 V

#### Small packaging: SOIC-8, SOT-23-6, MSOP-10

### APPLICATIONS

#### Filters

#### ADC drivers

#### Level shifting

#### Buffering

#### Professional video

#### Low voltage instrumentation

### GENERAL DESCRIPTION

The AD8027/AD8028<sup>1</sup> is a high speed amplifier with rail-to-rail input and output that operates on low supply voltages and is optimized for high performance and wide dynamic signal range. The AD8027/AD8028 has low noise (4.3 nV/ $\sqrt{\text{Hz}}$ , 1.6 pA/ $\sqrt{\text{Hz}}$ ) and low distortion (120 dBc @ 1 MHz). In applications that use a fraction of or the entire input dynamic range and require low distortion, the AD8027/AD8028 is an ideal choice.

Many rail-to-rail input amplifiers have an input stage that switches from one differential pair to another as the input signal crosses a threshold voltage, which causes distortion. The AD8027/AD8028 has a unique feature that allows the user to select the input crossover threshold voltage through the SELECT pin. This feature controls the voltage at which the complementary transistor input pairs switch. The AD8027/AD8028 also has intrinsically low crossover distortion.

#### Rev. B

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### CONNECTION DIAGRAMS

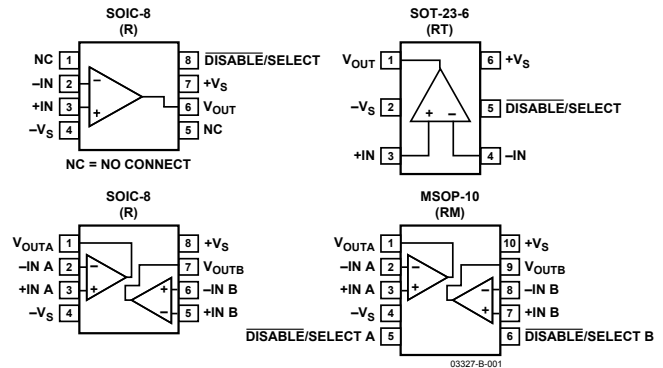


Figure 1. Connection Diagrams (Top View)

With its wide supply voltage range (2.7 V to 12 V) and wide bandwidth (190 MHz), the AD8027/AD8028 amplifier is designed to work in a variety of applications where speed and performance are needed on low supply voltages. The high performance of the AD8027/AD8028 is achieved with a quiescent current of only 6.5 mA/amplifier typical. The AD8027/AD8028 has a shut down mode that is controlled via the SELECT pin.

The AD8027/AD8028 is available in SOIC-8, MSOP-10, and SOT-23-6 packages. They are rated to work over the industrial temperature range of  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ .

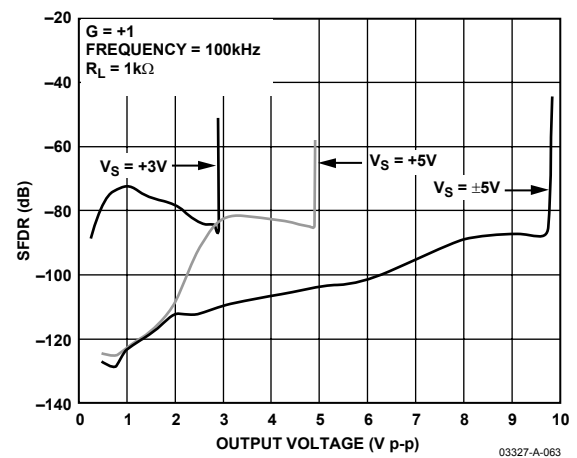


Figure 2. SFDR vs. Output Amplitude

<sup>1</sup>Protected by U.S. patent numbers 6,486,737B1; 6,518,842B1

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## REVISION HISTORY

### Revision B:

10/03—Data Sheet changed from Rev. A to Rev. B

Changes to Figure 1..... 1

### Revision A:

8/03—Data Sheet changed from Rev. 0 to Rev. A

Addition of AD8028..... Universal  
Changes to GENERAL DESCRIPTION..... 1  
Changes to Figures 1, 3, 4, 8, 13, 15, 17..... 1, 6, 7, 8, 9  
Changes to Figures 58, 60..... 18, 20  
Changes to SPECIFICATIONS..... 3  
Updated OUTLINE DIMENSIONS .....

### Revision 0: Initial Version

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## SPECIFICATIONS

**Table 1.  $V_S = \pm 5\text{ V}$  (@  $T_A = 25^\circ\text{C}$ ,  $R_L = 1\text{ k}\Omega$  to midsupply,  $G = +1$ , unless otherwise noted.)**

Parameter	Conditions	Min	Typ	Max	Unit
<b>DYNAMIC PERFORMANCE</b>					
-3 dB Bandwidth	$G = +1$ , $V_O = 0.2\text{ V p-p}$	138	190		MHz
	$G = +1$ , $V_O = 2\text{ V p-p}$	20	32		MHz
Bandwidth for 0.1 dB Flatness	$G = +2$ , $V_O = 0.2\text{ V p-p}$		16		MHz
Slew Rate	$G = +1$ , $V_O = 2\text{ V Step}$ / $G = -1$ , $V_O = 2\text{ V Step}$		90/100		V/ $\mu\text{s}$
Settling Time to 0.1%	$G = +2$ , $V_O = 2\text{ V Step}$		35		ns
<b>NOISE/DISTORTION PERFORMANCE</b>					
Spurious Free Dynamic Range (SFDR)	$f_c = 1\text{ MHz}$ , $V_O = 2\text{ V p-p}$ , $R_F = 24.9\ \Omega$ $f_c = 5\text{ MHz}$ , $V_O = 2\text{ V p-p}$ , $R_F = 24.9\ \Omega$		120		dBc
			80		dBc
Input Voltage Noise	$f = 100\text{ kHz}$		4.3		nV/ $\sqrt{\text{Hz}}$
Input Current Noise	$f = 100\text{ kHz}$		1.6		pA/ $\sqrt{\text{Hz}}$
Differential Gain Error	NTSC, $G = +2$ , $R_L = 150\ \Omega$		0.1		%
Differential Phase Error	NTSC, $G = +2$ , $R_L = 150\ \Omega$		0.2		Degree
Crosstalk, Output to Output	$G = +1$ , $R_L = 100\ \Omega$ , $V_{OUT} = 2\text{ V p-p}$ , $V_S = \pm 5\text{ V @ } 1\text{ MHz}$		-93		dB
<b>DC PERFORMANCE</b>					
Input Offset Voltage	SELECT = Tri-State or Open, PNP Active		200	800	$\mu\text{V}$
	SELECT = High NPN Active		240	900	$\mu\text{V}$
Input Offset Voltage Drift	$T_{MIN}$ to $T_{MAX}$		1.50		$\mu\text{V}/^\circ\text{C}$
Input Bias Current <sup>1</sup>	$V_{CM} = 0\text{ V}$ , NPN Active		4	6	$\mu\text{A}$
	$T_{MIN}$ to $T_{MAX}$		4		$\mu\text{A}$
Input Bias Current <sup>1</sup>	$V_{CM} = 0\text{ V}$ , PNP Active		-8	-11	$\mu\text{A}$
	$T_{MIN}$ to $T_{MAX}$		-8		$\mu\text{A}$
Input Offset Current			$\pm 0.1$	$\pm 0.9$	$\mu\text{A}$
Open-Loop Gain	$V_O = \pm 2.5\text{ V}$	100	110		dB
<b>INPUT CHARACTERISTICS</b>					
Input Impedance			6		M $\Omega$
Input Capacitance			2		pF
Input Common-Mode Voltage Range			-5.2 to +5.2		V
Common-Mode Rejection Ratio	$V_{CM} = \pm 2.5\text{ V}$	90	110		dB
<b>SELECT PIN</b>					
Crossover Low—Selection Input Voltage	Tri-State < $\pm 20\ \mu\text{A}$		-3.3 to +5		V
Crossover High—Selection Input Voltage			-3.9 to -3.3		V
Disable Input Voltage			-5 to -3.9		V
Disable Switching Speed	50% of Input to <10% of Final $V_O$		980		ns
Enable Switching Speed			45		ns
<b>OUTPUT CHARACTERISTICS</b>					
Output Overdrive Recovery Time (Rising/Falling Edge)	$V_I = +6\text{ V to } -6\text{ V}$ , $G = -1$		40/45		ns
Output Voltage Swing		$-V_S + 0.10$	$+V_S - 0.06$ , $-V_S + 0.06$	$+V_S - 0.10$	V
Short Circuit Output	Sinking and Sourcing		120		mA
Off Isolation	$V_{IN} = 0.2\text{ V p-p}$ , $f = 1\text{ MHz}$ , SELECT = Low		-49		dB
Capacitive Load Drive	30% Overshoot		20		pF
<b>POWER SUPPLY</b>					
Operating Range		2.7		12	V
Quiescent Current/Amplifier			6.5	8.5	mA
Quiescent Current (Disabled)	SELECT = Low		370	500	$\mu\text{A}$
Power Supply Rejection Ratio	$V_S \pm 1\text{ V}$	90	110		dB

<sup>1</sup> No sign or a plus indicates current into pin, minus indicates current out of pin.

# AD8027/AD8028

## SPECIFICATIONS

**Table 2.  $V_S = +5\text{ V}$  (@  $T_A = 25^\circ\text{C}$ ,  $R_L = 1\text{ k}\Omega$  to midsupply, unless otherwise noted.)**

Parameter	Conditions	Min	Typ	Max	Unit
<b>DYNAMIC PERFORMANCE</b>					
-3 dB Bandwidth	$G = +1, V_O = 0.2\text{ V p-p}$	131	185		MHz
	$G = +1, V_O = 2\text{ V p-p}$	18	28		MHz
Bandwidth for 0.1 dB Flatness	$G = +2, V_O = 0.2\text{ V p-p}$		12		MHz
Slew Rate	$G = +1, V_O = 2\text{ V Step}/G = -1, V_O = 2\text{ V Step}$		85/100		V/ $\mu\text{s}$
Settling Time to 0.1%	$G = +2, V_O = 2\text{ V Step}$		40		ns
<b>NOISE/DISTORTION PERFORMANCE</b>					
Spurious Free Dynamic Range (SFDR)	$f_C = 1\text{ MHz}, V_O = 2\text{ V p-p}, R_F = 24.9\ \Omega$ $f_C = 5\text{ MHz}, V_O = 2\text{ V p-p}, R_F = 24.9\ \Omega$		90		dBc
			64		dBc
Input Voltage Noise	$f = 100\text{ kHz}$		4.3		$\text{nV}/\sqrt{\text{Hz}}$
Input Current Noise	$f = 100\text{ kHz}$		1.6		$\text{pA}/\sqrt{\text{Hz}}$
Differential Gain Error	NTSC, $G = +2, R_L = 150\ \Omega$		0.1		%
Differential Phase Error	NTSC, $G = +2, R_L = 150\ \Omega$		0.2		Degree
Crosstalk, Output to Output	$G = 1, R_L = 100\ \Omega, V_{OUT} = 2\text{ V p-p}, V_S = \pm 5\text{ V @ } 1\text{ MHz}$		-92		dB
<b>DC PERFORMANCE</b>					
Input Offset Voltage	SELECT = Tri-State or Open, PNP Active		200	800	$\mu\text{V}$
	SELECT = High NPN Active		240	900	$\mu\text{V}$
Input Offset Voltage Drift	$T_{MIN}$ to $T_{MAX}$		2		$\mu\text{V}/^\circ\text{C}$
Input Bias Current <sup>1</sup>	$V_{CM} = 2.5\text{ V}, \text{NPN Active}$		4	6	$\mu\text{A}$
	$T_{MIN}$ to $T_{MAX}$		4		$\mu\text{A}$
Input Bias Current <sup>1</sup>	$V_{CM} = 2.5\text{ V}, \text{PNP Active}$		-8	-11	$\mu\text{A}$
	$T_{MIN}$ to $T_{MAX}$		-8		$\mu\text{A}$
Input Offset Current			$\pm 0.1$	$\pm 0.9$	$\mu\text{A}$
Open-Loop Gain	$V_O = 1\text{ V to } 4\text{ V}$	96	105		dB
<b>INPUT CHARACTERISTICS</b>					
Input Impedance			6		M $\Omega$
Input Capacitance			2		pF
Input Common-Mode Voltage Range			-0.2 to +5.2		V
Common-Mode Rejection Ratio	$V_{CM} = 0\text{ V to } 2.5\text{ V}$	90	105		dB
<b>SELECT PIN</b>					
Crossover Low—Selection Input Voltage	Tri-State < $\pm 20\ \mu\text{A}$		1.7 to 5		V
Crossover High—Selection Input Voltage			1.1 to 1.7		V
Disable Input Voltage			0 to 1.1		V
DISABLE Switching Speed	50% of Input to <10% of Final $V_O$		1100		ns
Enable Switching Speed			50		ns
<b>OUTPUT CHARACTERISTICS</b>					
Overdrive Recovery Time (Rising/Falling Edge)	$V_I = -1\text{ V to } +6\text{ V}, G = -1$		50/50		ns
Output Voltage Swing	$R_L = 1\text{ k}\Omega$	$-V_S + 0.08$	$+V_S - 0.04,$ $-V_S + 0.04$	$+V_S - 0.08$	V
Off Isolation	$V_{IN} = 0.2\text{ V p-p}, f = 1\text{ MHz}, \text{SELECT} = \text{Low}$		-49		dB
Short Circuit Current	Sinking and Sourcing		105		mA
Capacitive Load Drive	30% Overshoot		20		pF
<b>POWER SUPPLY</b>					
Operating Range		2.7		12	V
Quiescent Current/Amplifier			6	8.5	mA
Quiescent Current (Disabled)	SELECT = Low		320	450	$\mu\text{A}$
Power Supply Rejection Ratio	$V_S \pm 1\text{ V}$	90	105		dB

<sup>1</sup> No sign or a plus indicates current into pin, minus indicates current out of pin.

## SPECIFICATIONS

Table 3.  $V_S = +3\text{ V}$  (@  $T_A = 25^\circ\text{C}$ ,  $R_L = 1\text{ k}\Omega$  to midsupply, unless otherwise noted.)

Parameter	Conditions	Min	Typ	Max	Unit
<b>DYNAMIC PERFORMANCE</b>					
-3 dB Bandwidth	$G = +1$ , $V_O = 0.2\text{ V p-p}$	125	180		MHz
	$G = +1$ , $V_O = 2\text{ V p-p}$	19	29		MHz
Bandwidth for 0.1 dB Flatness	$G = +2$ , $V_O = 0.2\text{ V p-p}$		10		MHz
Slew Rate	$G = +1$ , $V_O = 2\text{ V Step/G} = -1$ , $V_O = 2\text{ V Step}$		73/100		V/ $\mu\text{s}$
Settling Time to 0.1%	$G = +2$ , $V_O = 2\text{ V Step}$		48		ns
<b>NOISE/DISTORTION PERFORMANCE</b>					
Spurious Free Dynamic Range (SFDR)	$f_c = 1\text{ MHz}$ , $V_O = 2\text{ V p-p}$ , $R_F = 24.9\ \Omega$		85		dBc
	$f_c = 5\text{ MHz}$ , $V_O = 2\text{ V p-p}$ , $R_F = 24.9\ \Omega$		64		dBc
Input Voltage Noise	$f = 100\text{ kHz}$		4.3		nV/ $\sqrt{\text{Hz}}$
Input Current Noise	$f = 100\text{ kHz}$		1.6		pA/ $\sqrt{\text{Hz}}$
Differential Gain Error	NTSC, $G = +2$ , $R_L = 150\ \Omega$		0.15		%
Differential Phase Error	NTSC, $G = +2$ , $R_L = 150\ \Omega$		0.20		Degree
Crosstalk, Output to Output	$G = 1$ , $R_L = 100\ \Omega$ , $V_{OUT} = 2\text{ V p-p}$ , $V_S = 3\text{ V @ }1\text{ MHz}$		-89		dB
<b>DC PERFORMANCE</b>					
Input Offset Voltage	SELECT = Tri-State or Open, PNP Active		200	800	$\mu\text{V}$
	SELECT = High NPN Active		240	900	$\mu\text{V}$
Input Offset Voltage Drift	$T_{MIN}$ to $T_{MAX}$		2		$\mu\text{V}/^\circ\text{C}$
Input Bias Current <sup>1</sup>	$V_{CM} = 1.5\text{ V}$ , NPN Active		4	6	$\mu\text{A}$
	$T_{MIN}$ to $T_{MAX}$		4		$\mu\text{A}$
Input Bias Current <sup>1</sup>	$V_{CM} = 1.5\text{ V}$ , PNP Active		-8	-11	$\mu\text{A}$
	$T_{MIN}$ to $T_{MAX}$		-8		$\mu\text{A}$
Input Offset Current			$\pm 0.1$	$\pm 0.9$	$\mu\text{A}$
Open-Loop Gain	$V_O = 1\text{ V to }2\text{ V}$	90	100		dB
<b>INPUT CHARACTERISTICS</b>					
Input Impedance			6		M $\Omega$
Input Capacitance			2		pF
Input Common-Mode Voltage Range	$R_L = 1\text{ k}\Omega$		-0.2 to +3.2		V
Common-Mode Rejection Ratio	$V_{CM} = 0\text{ V to }1.5\text{ V}$	88	100		dB
<b>SELECT PIN</b>					
Crossover Low—Selection Input Voltage	Tri-State < $\pm 20\ \mu\text{A}$		1.7 to 3		V
Crossover High—Selection Input Voltage			1.1 to 1.7		V
Disable Input Voltage			0 to 1.1		V
DISABLE Switching Speed	50% of Input to <10% of Final $V_O$		1150		ns
Enable Switching Speed			50		ns
<b>OUTPUT CHARACTERISTICS</b>					
Output Overdrive Recovery Time (Rising/Falling Edge)	$V_I = -1\text{ V to }+4\text{ V}$ , $G = -1$		55/55		ns
Output Voltage Swing	$R_L = 1\text{ k}\Omega$	$-V_S + 0.07$	$+V_S - 0.03$ , $-V_S + 0.03$	$+V_S - 0.07$	V
Short Circuit Current	Sinking and Sourcing		72		mA
Off Isolation	$V_{IN} = 0.2\text{ V p-p}$ , $f = 1\text{ MHz}$ , SELECT = Low		-49		dB
Capacitive Load Drive	30% Overshoot		20		pF
<b>POWER SUPPLY</b>					
Operating Range		2.7		12	V
Quiescent Current/Amplifier			6.0	8.0	mA
Quiescent Current (Disabled)	SELECT = Low		300	420	$\mu\text{A}$
Power Supply Rejection Ratio	$V_S \pm 1\text{ V}$	88	100		dB

<sup>1</sup> No sign or a plus indicates current into pin, minus indicates current out of pin.

## ABSOLUTE MAXIMUM RATINGS

**Table 4.**

Parameter	Rating
Supply Voltage	12.6 V
Power Dissipation	See Figure 3
Common-Mode Input Voltage	$\pm V_S \pm 0.5$ V
Differential Input Voltage	$\pm 1.8$ V
Storage Temperature	-65°C to +125°C
Operating Temperature Range	-40°C to +125°C
Lead Temperature Range (Soldering 10 sec)	300°C
Junction Temperature	150°C

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### Maximum Power Dissipation

The maximum safe power dissipation in the AD8027/AD8028 package is limited by the associated rise in junction temperature ( $T_J$ ) on the die. The plastic encapsulating the die will locally reach the junction temperature. At approximately 150°C, which is the glass transition temperature, the plastic will change its properties. Even temporarily exceeding this temperature limit may change the stresses that the package exerts on the die, permanently shifting the parametric performance of the AD8027/AD8028. Exceeding a junction temperature of 175°C for an extended period of time can result in changes in the silicon devices, potentially causing failure.

The still-air thermal properties of the package and PCB ( $\theta_{JA}$ ), ambient temperature ( $T_A$ ), and the total power dissipated in the package ( $P_D$ ) determine the junction temperature of the die. The junction temperature can be calculated as

$$T_J = T_A + (P_D \times \theta_{JA})$$

The power dissipated in the package ( $P_D$ ) is the sum of the quiescent power dissipation and the power dissipated in the package due to the load drive for all outputs. The quiescent power is the voltage between the supply pins ( $V_S$ ) times the quiescent current ( $I_S$ ). Assuming the load ( $R_L$ ) is referenced to midsupply, then the total drive power is  $V_S/2 \times I_{OUT}$ , some of which is dissipated in the package and some in the load ( $V_{OUT} \times I_{OUT}$ ). The difference between the total drive power and the load power is the drive power dissipated in the package.

$$P_D = \text{Quiescent Power} + (\text{Total Drive Power} - \text{Load Power})$$

$$P_D = (V_S \times I_S) + \left( \frac{V_S}{2} \times \frac{V_{OUT}}{R_L} \right) - \frac{V_{OUT}^2}{R_L}$$

RMS output voltages should be considered. If  $R_L$  is referenced to  $V_S$ -, as in single-supply operation, then the total drive power is  $V_S \times I_{OUT}$ .

If the rms signal levels are indeterminate, then consider the worst case, when  $V_{OUT} = V_S/4$  for  $R_L$  to midsupply

$$P_D = (V_S \times I_S) + \frac{(V_S/4)^2}{R_L}$$

In single-supply operation with  $R_L$  referenced to  $V_S$ -, worst case is  $V_{OUT} = V_S/2$ .

Airflow will increase heat dissipation, effectively reducing  $\theta_{JA}$ . Also, more metal directly in contact with the package leads from metal traces, through holes, ground, and power planes will reduce the  $\theta_{JA}$ . Care must be taken to minimize parasitic capacitances at the input leads of high speed op amps as discussed in the board layout section.

Figure 3 shows the maximum safe power dissipation in the package versus the ambient temperature for the SOIC-8 (125°C/W), SOT-23-6 (170°C/W), and MSOP-10 (130°C/W) packages on a JEDEC standard 4-layer board.

### OUTPUT SHORT CIRCUIT

Shorting the output to ground or drawing excessive current from the AD8027/AD8028 will likely cause catastrophic failure.

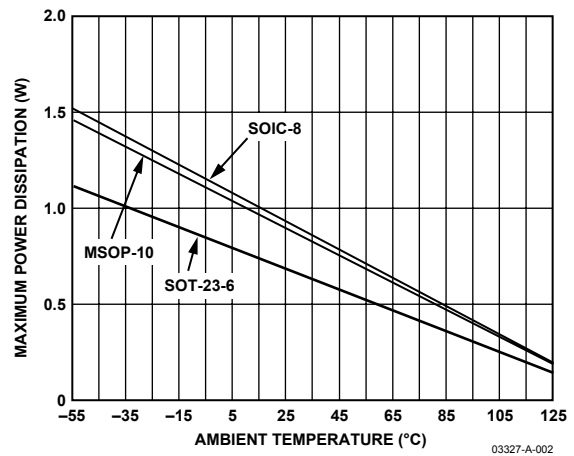


Figure 3. Maximum Power Dissipation

# TYPICAL PERFORMANCE CHARACTERISTICS

Default Conditions  $V_S = +5\text{ V}$  ( $T_A = +25^\circ\text{C}$ ,  $R_L = 1\text{ k}\Omega$ , unless otherwise noted.)

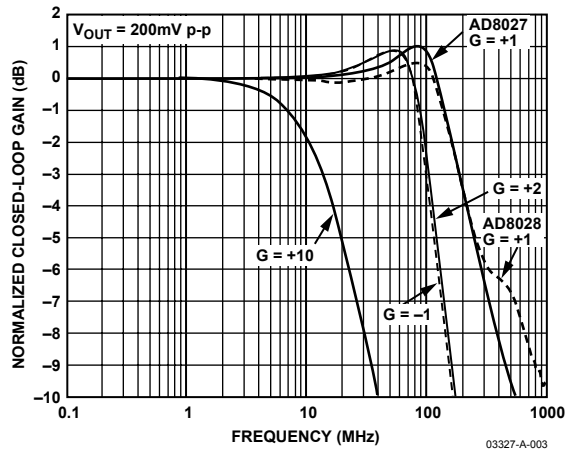


Figure 4. Small Signal Frequency Response for Various Gains

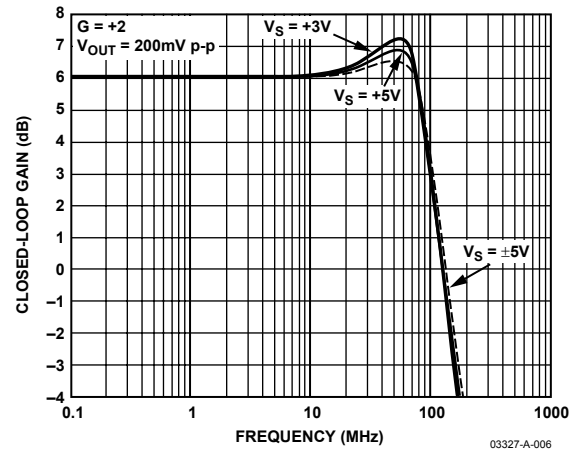


Figure 7. Small Signal Frequency Response for Various Supplies

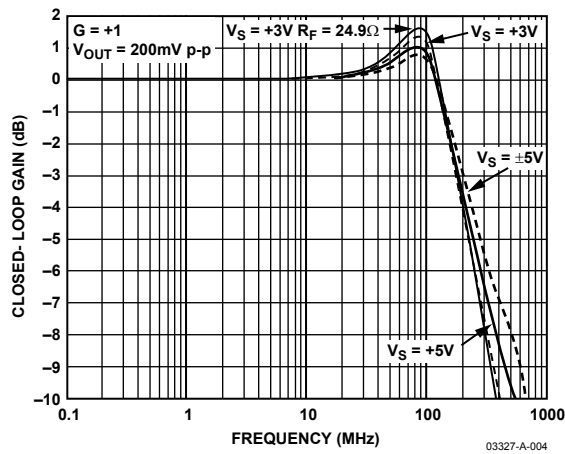


Figure 5. AD8027 Small Signal Frequency Response for Various Supplies

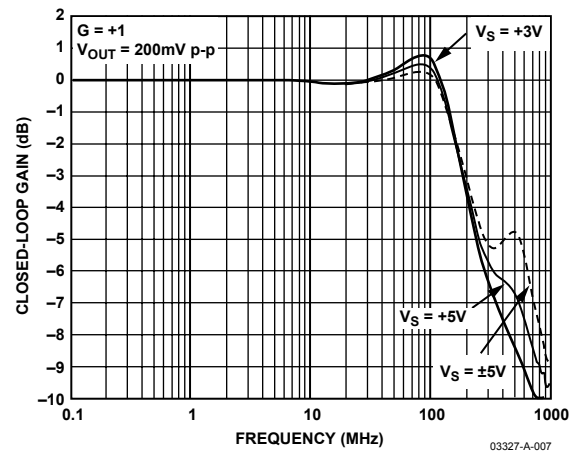


Figure 8. AD8028 Small Signal Frequency Response for Various Supplies

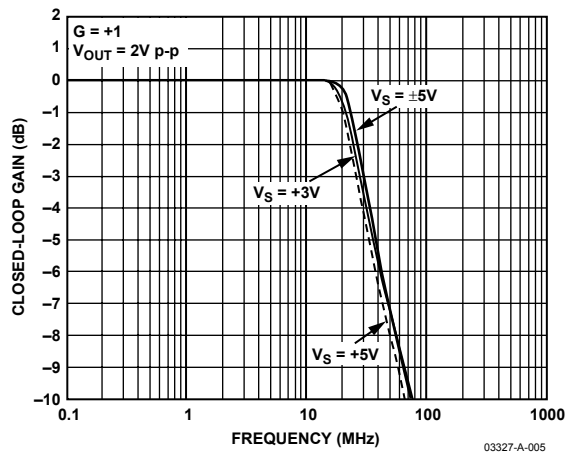


Figure 6. Large Signal Frequency Response for Various Supplies

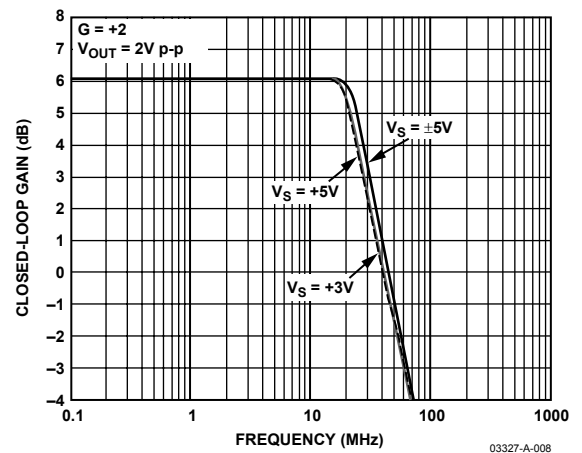


Figure 9. Large Signal Frequency Response for Various Supplies

# AD8027/AD8028

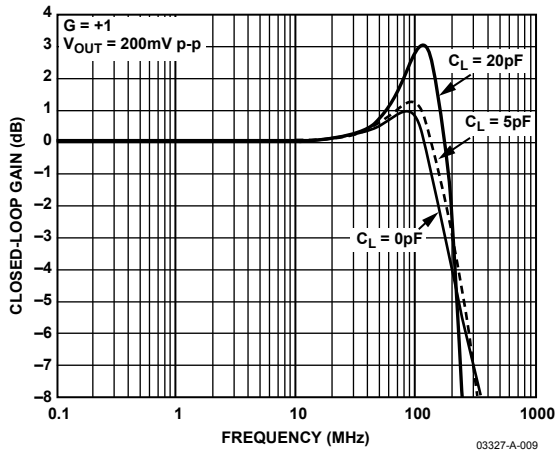


Figure 10. AD8027 Small Signal Frequency Response for Various  $C_{LOAD}$

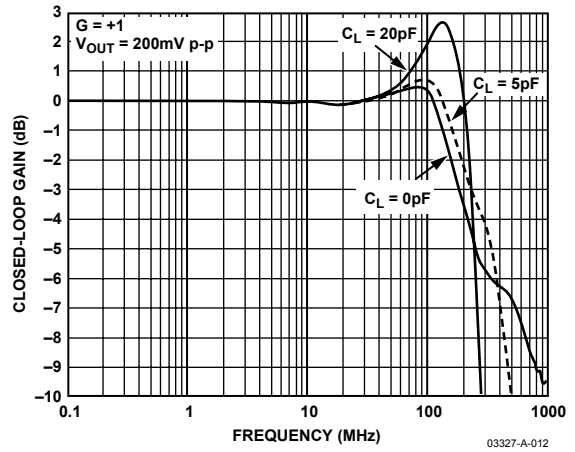


Figure 13. AD8028 Small Signal Frequency Response for Various  $C_{LOAD}$

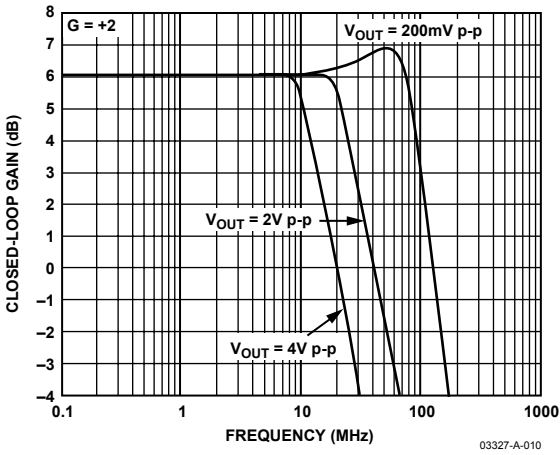


Figure 11. Frequency Response for Various Output Amplitudes

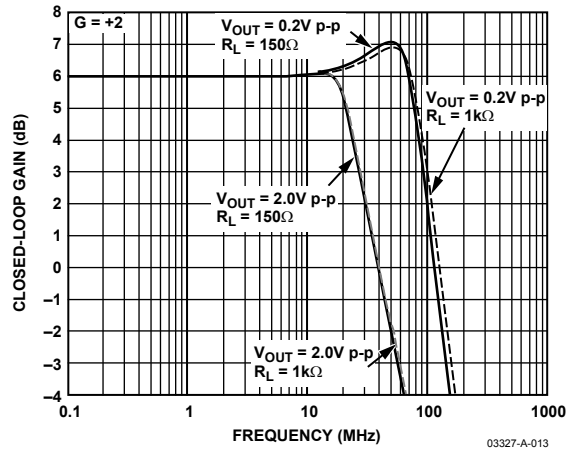


Figure 14. Small Signal Frequency Response for Various  $R_{LOAD}$  Values

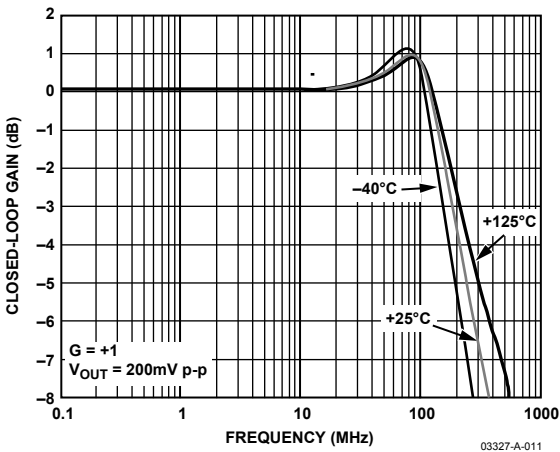


Figure 12. AD8027 Small Signal Frequency Response vs. Temperature

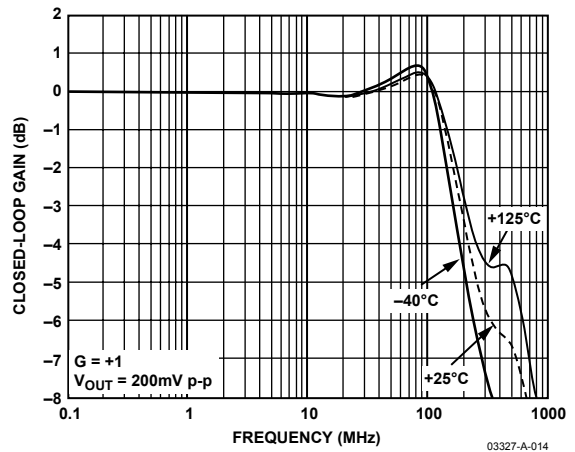


Figure 15. AD8028 Small Signal Frequency Response vs. Temperature



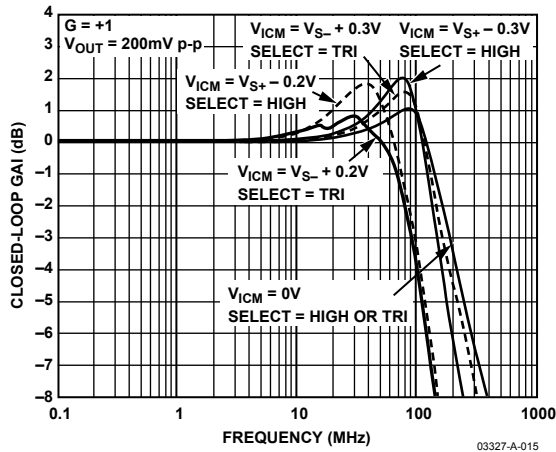


Figure 16. Small Signal Frequency Response vs. Input Common-Mode Voltages

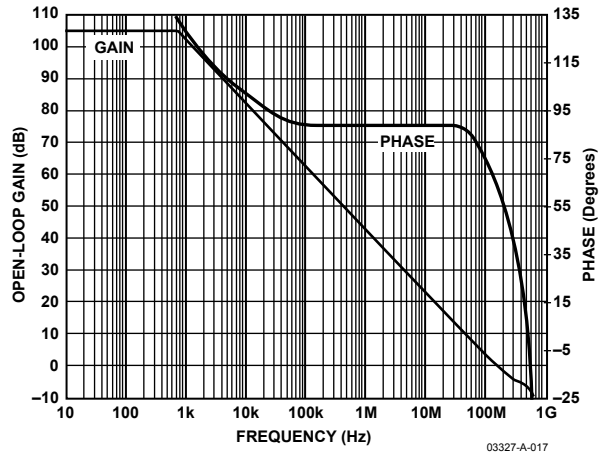


Figure 18. Open-Loop Gain and Phase vs. Frequency

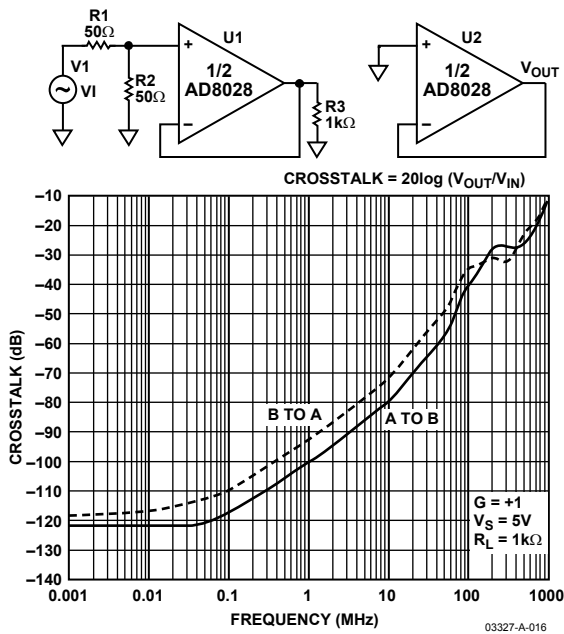


Figure 17. AD8028 Crosstalk Output to Output

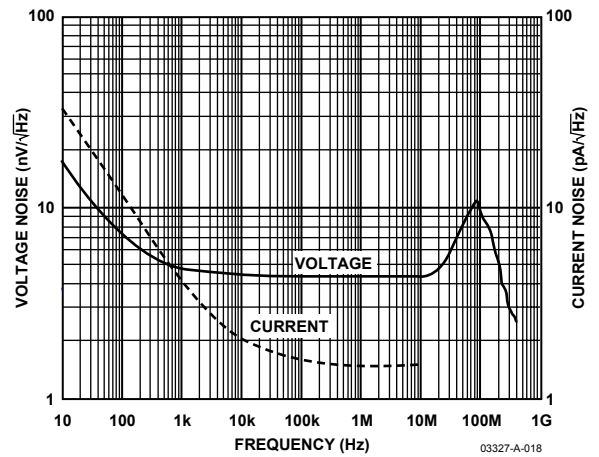


Figure 19. Voltage and Current Noise vs. Frequency

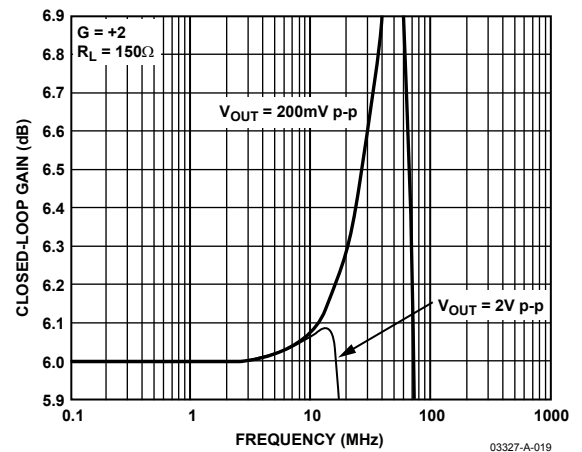


Figure 20. 0.1 dB Flatness Frequency Response

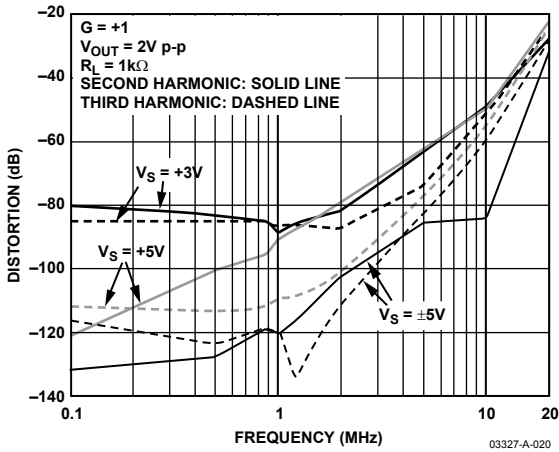


Figure 21. Harmonic Distortion vs. Frequency and Supply Voltage

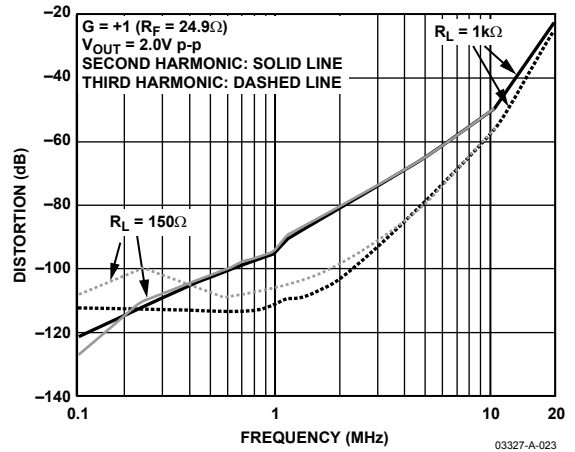


Figure 24. Harmonic Distortion vs. Frequency and Load

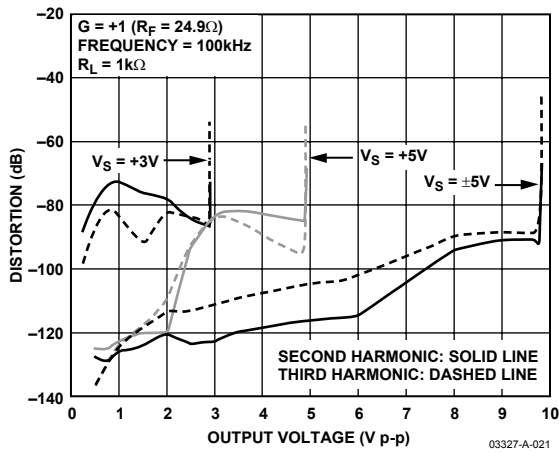


Figure 22. Harmonic Distortion vs. Output Amplitude

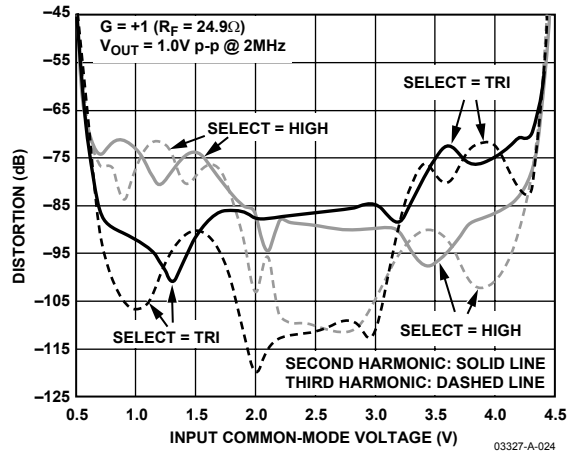


Figure 25. Harmonic Distortion vs. Input Common-Mode Voltage,  $V_S = +5V$

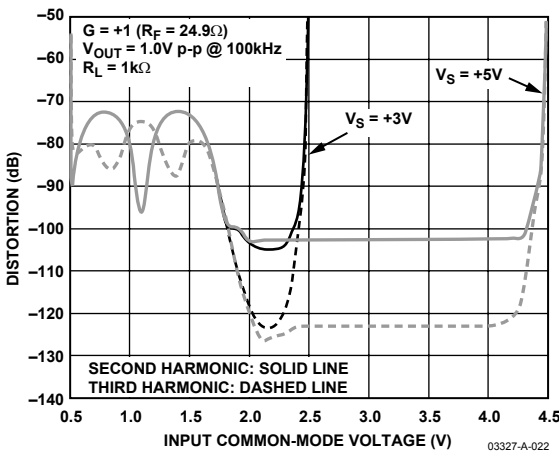


Figure 23. Harmonic Distortion vs. Input Common-Mode Voltage, *SELECT = High*

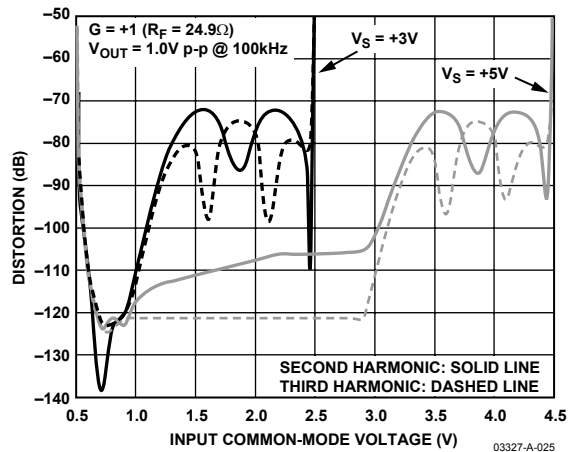


Figure 26. Harmonic Distortion vs. Input Common-Mode Voltage, *SELECT = Tri-State or Open*

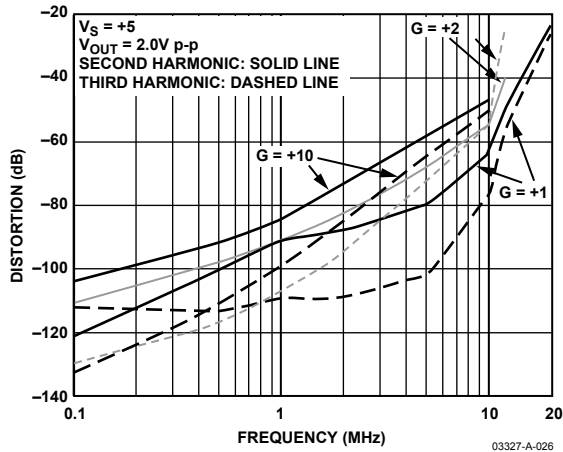


Figure 27. Harmonic Distortion vs. Frequency and Gain

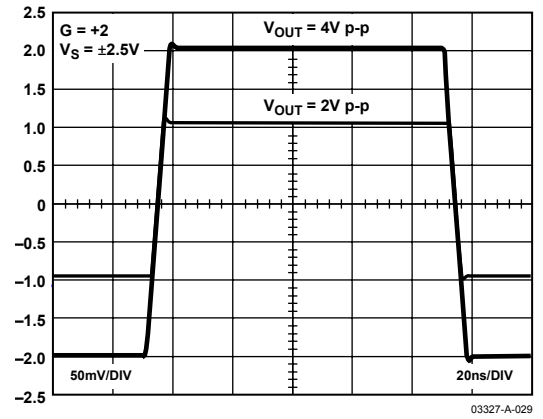


Figure 30. Large Signal Transient Response,  $G = +2$

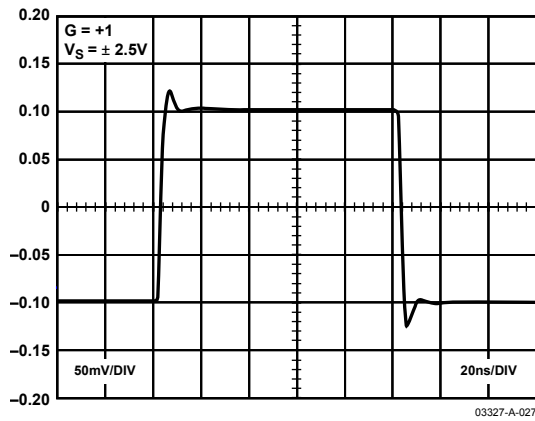


Figure 28. Small Signal Transient Response

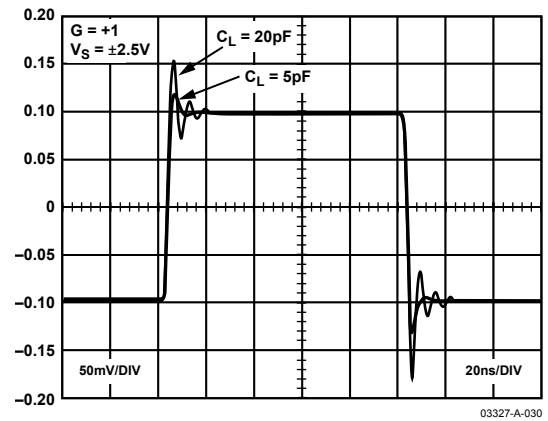


Figure 31. Small Signal Transient Response with Capacitive Load

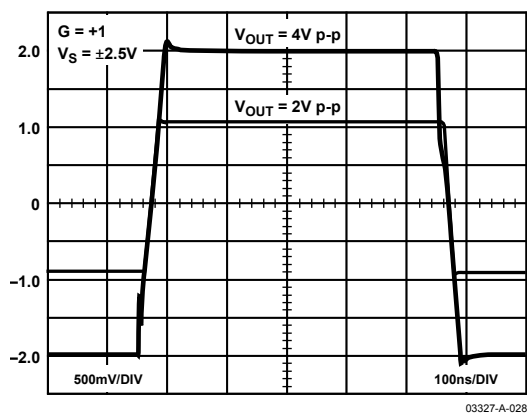


Figure 29. Large Signal Transient Response,  $G = +1$

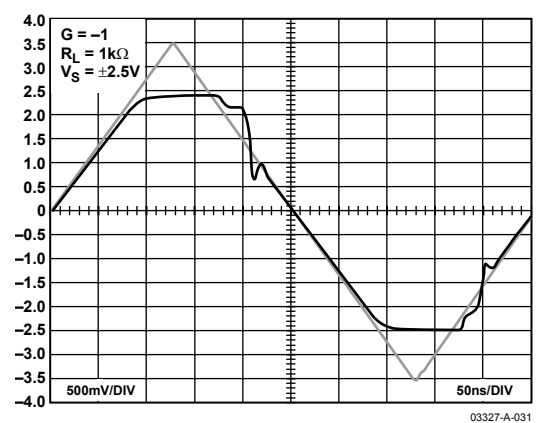


Figure 32. Output Overdrive Recovery

# AD8027/AD8028

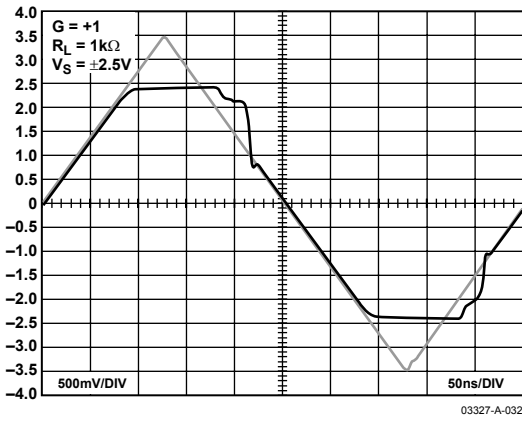


Figure 33. Input Overdrive Recovery

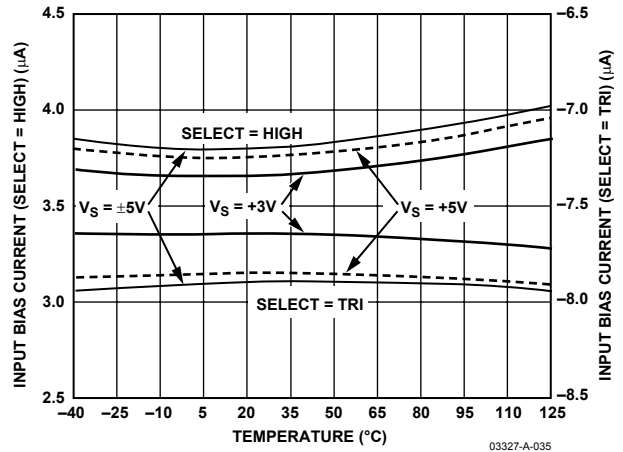


Figure 36. Input Bias Current vs. Temperature

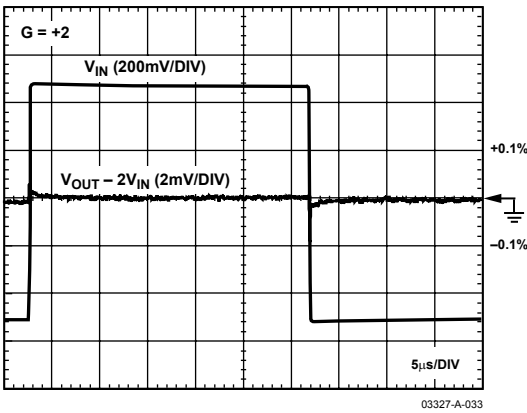


Figure 34. Long-Term Settling Time

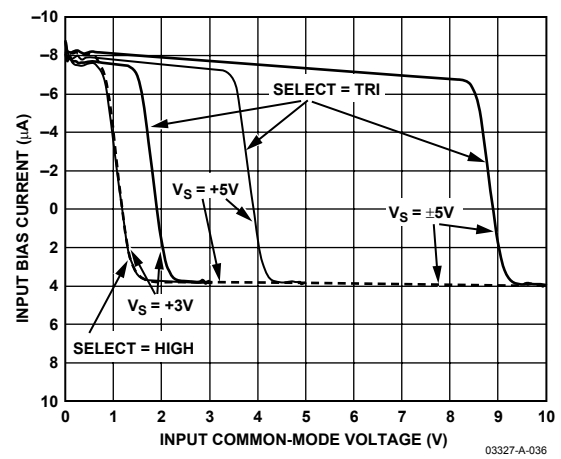


Figure 37. Input Bias Current vs. Input Common-Mode Voltage

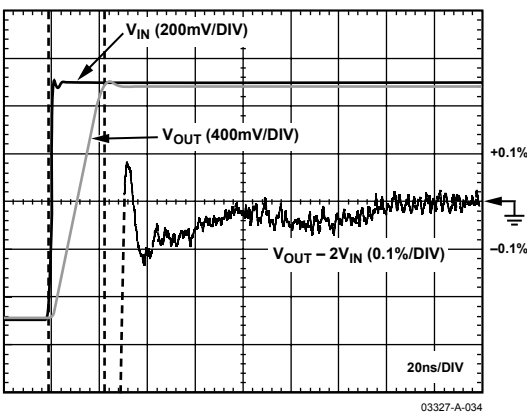


Figure 35. 0.1% Short-Term Settling Time

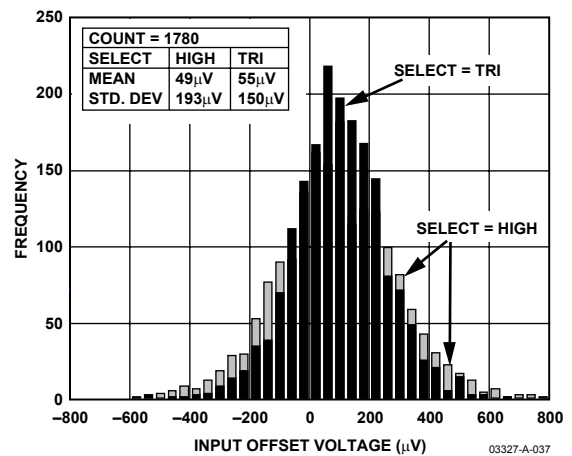


Figure 38. Input Offset Voltage Distribution

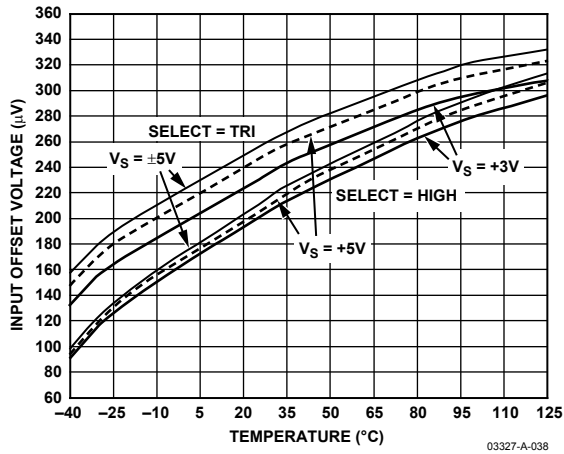


Figure 39. Input Offset Voltage vs. Temperature

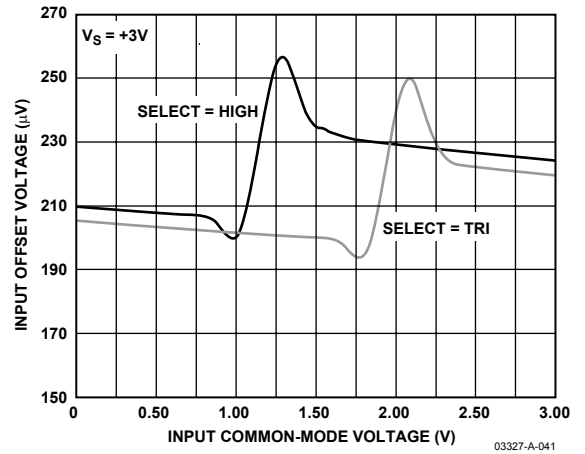


Figure 42. Input Offset Voltage vs. Input Common-Mode Voltage,  $V_S = +3$

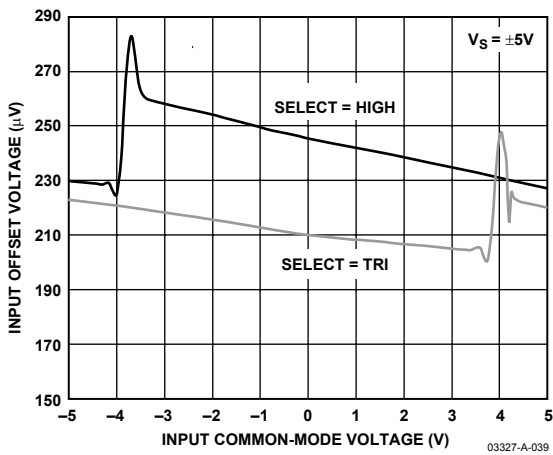


Figure 40. Input Offset Voltage vs. Input Common-Mode Voltage,  $V_S = \pm 5$

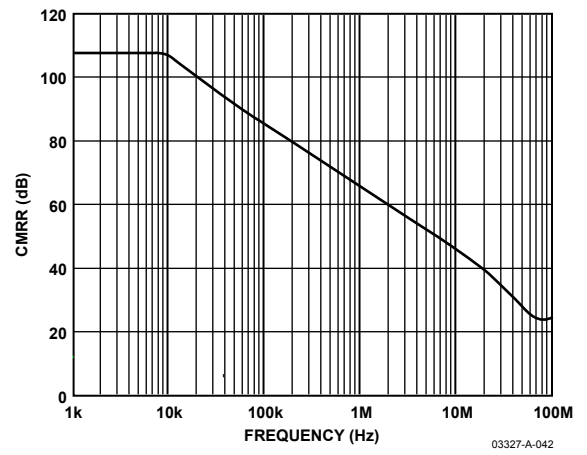


Figure 43. CMRR vs. Frequency

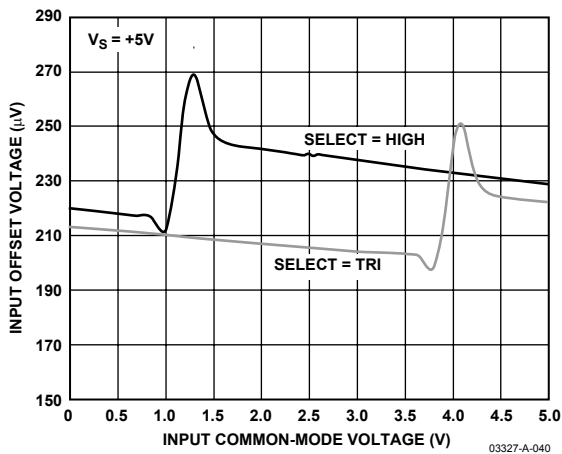


Figure 41. Input Offset Voltage vs. Input Common-Mode Voltage,  $V_S = +5$

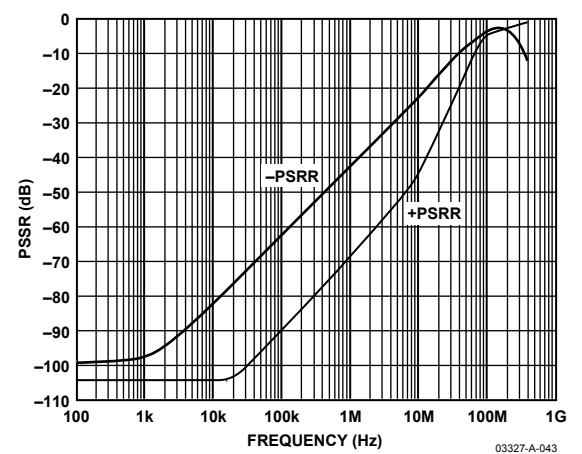


Figure 44. PSRR vs. Frequency

# AD8027/AD8028

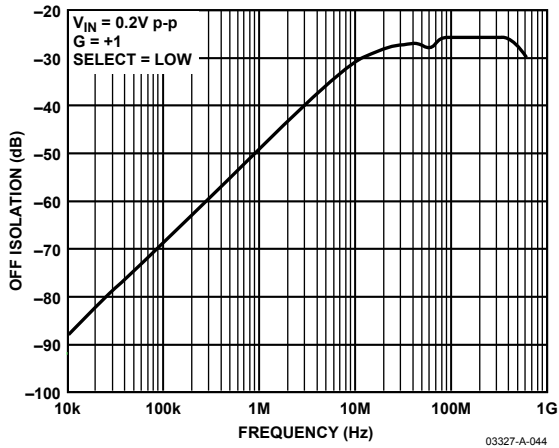


Figure 45. Off Isolation vs. Frequency

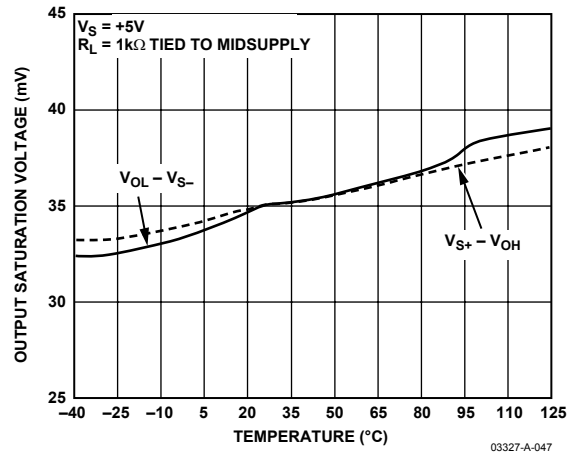


Figure 48. Output Saturation Voltage vs. Temperature

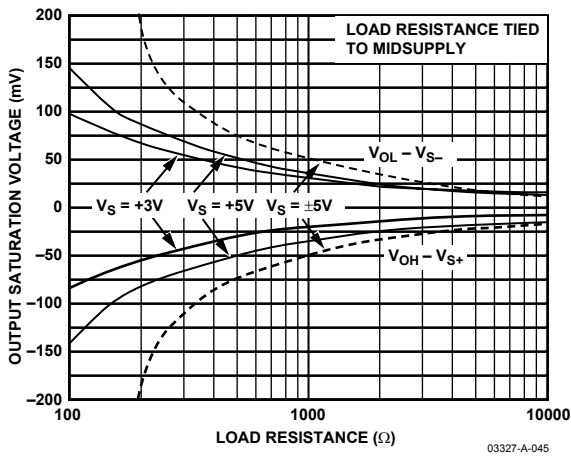


Figure 46. Output Saturation Voltage vs. Output Load

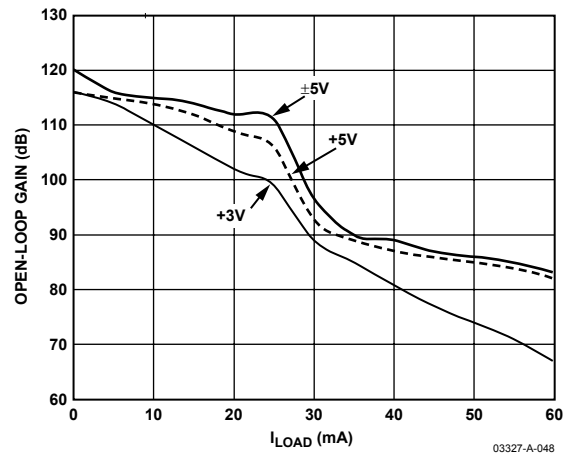


Figure 49. Open-Loop Gain vs. Load Current

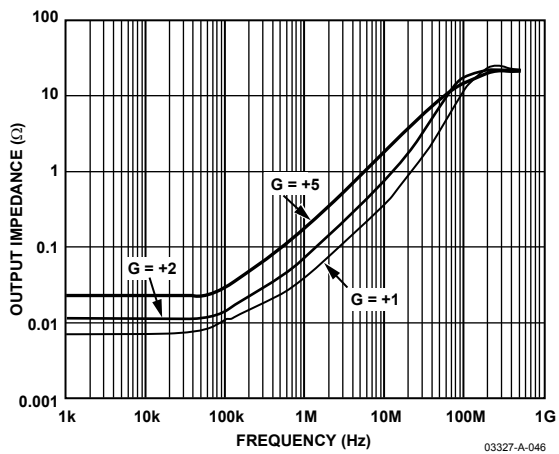


Figure 47. Output Enabled—Impedance vs. Frequency

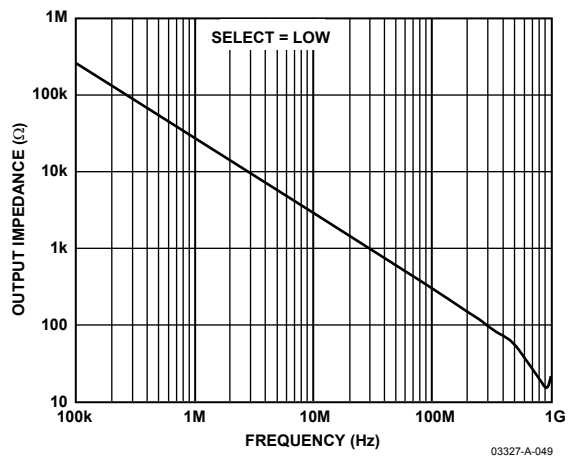


Figure 50. Output Disabled—Impedance vs. Frequency

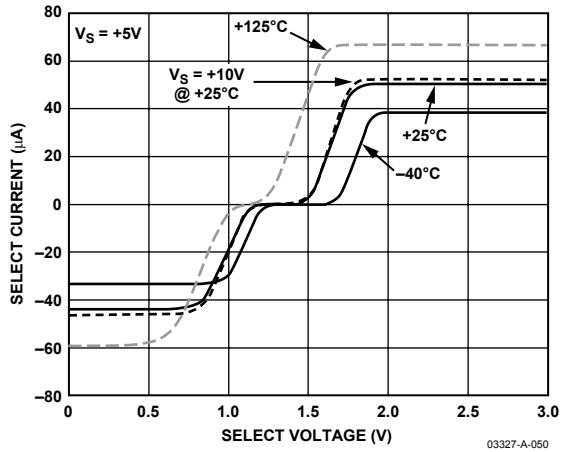


Figure 51. SELECT Pin Current vs. SELECT Pin Voltage and Temperature

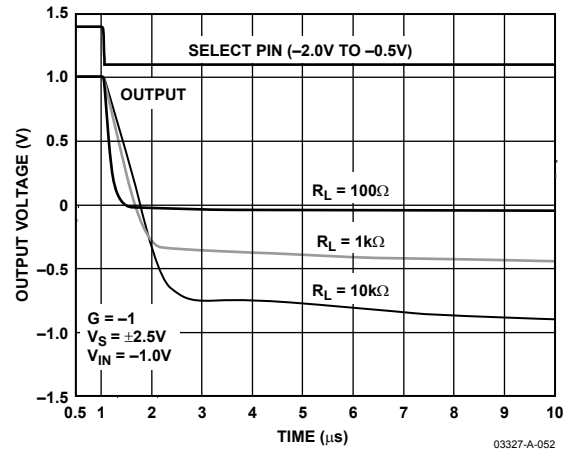


Figure 53. Disable Turn-Off Timing

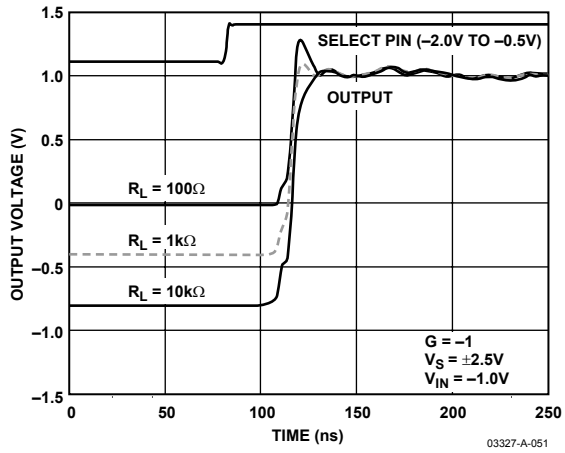


Figure 52. Enable Turn-On Timing

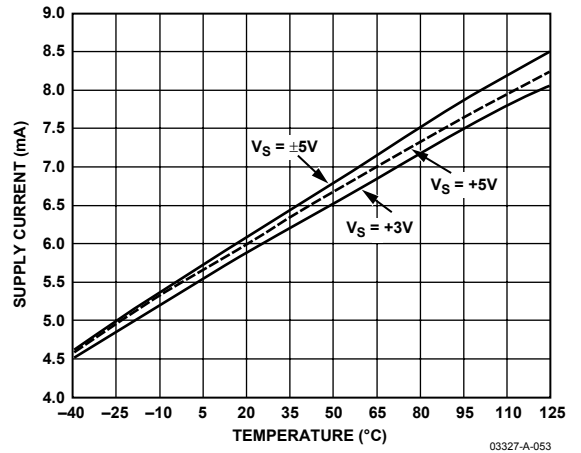


Figure 54. Quiescent Supply Current vs. Supply Voltage and Temperature





In the event that the crossover region cannot be avoided, specific attention has been given to the input stage to ensure constant transconductance and minimal offset in all regions of operation. The regions are: PNP input pair running, NPN input pair running, and both running at the same time (in the 200 mV crossover region). Maintaining constant transconductance in all regions ensures the best wideband distortion performance when going between these regions. With this technique, the AD8027/AD8028 can achieve greater than 80 dB SFDR for a 2 V p-p, 1 MHz, G = +1 signal on ±1.5 V supplies. Another requirement in achieving this level of distortion is the offset of each pair must be laser trimmed to achieve greater than 80 dB SFDR, even for low frequency signals.

## Output Stage

The AD8027/AD8028 uses a common-emitter output structure to achieve rail-to-rail output capability. The output stage is designed to drive 50 mA of linear output current, 40 mA within 200 mV of the rail, and 2.5 mA within 35 mV of the rail. Loading of the output stage, including any possible feedback network, will lower the open-loop gain of the amplifier. Refer to Figure 49 for the loading behavior. Capacitive load can degrade the phase margin of the amplifier. The AD8027/AD8028 can drive up to 20 pF, G = +1 as seen in Figure 10. A small (25 Ω to 50 Ω) series resistor (R<sub>SNUB</sub>) should be included if the capacitive load is to exceed 20 pF for a gain of 1. Increasing the closed-loop gain will increase the amount of capacitive load that can be driven before a series resistor will need to be included.

## DC Errors

The AD8027/AD8028 uses two complementary input stages to achieve rail-to-rail input performance, as mentioned in the Input Stage section. To use the dc performance over the entire common-mode range, the input bias current and input offset voltage of each pair must be considered.

Referring to Figure 56, the output offset voltage of each pair is calculated by

$$V_{OS,PNP,OUT} = V_{OS,PNP} \left( \frac{R_G + R_F}{R_G} \right),$$

$$V_{OS,NPN,OUT} = V_{OS,NPN} \left( \frac{R_G + R_F}{R_G} \right)$$

where the difference of the two will be the discontinuity experienced when going through the crossover region. The size of the discontinuity is defined as

$$V_{DIS} = (V_{OS,PNP} - V_{OS,NPN}) \times \left( \frac{R_G + R_F}{R_G} \right)$$

Using the crossover select feature of the AD8027/AD8028 helps to avoid this region. In the event that the region cannot be avoided, the quantity (V<sub>OS,PNP</sub> - V<sub>OS,NPN</sub>) is trimmed to minimize this effect.

Because the input pairs are complementary, the input bias current will reverse polarity when going through the crossover region shown in Figure 37. The offset between pairs is described by

$$V_{OS,PNP} - V_{OS,NPN} = (I_{B,PNP} - I_{B,NPN}) \times \left[ R_S \left( \frac{R_G + R_F}{R_G} \right) - R_F \right]$$

I<sub>B,PNP</sub> is the input bias current of either input when the PNP input pair is active, and I<sub>B,NPN</sub> is the input bias current of either input pair when the NPN pair is active. If R<sub>S</sub> is sized so that when multiplied by the gain factor it equals R<sub>F</sub>, this effect will be eliminated. It is strongly recommended to balance the impedances in this manner when traveling through the crossover region to minimize the dc error and distortion. As an example, assuming the PNP input pair has an input bias current of 6 μA and the NPN input pair has an input bias current of -2 μA, a 200 μV shift in offset will occur when traveling through the crossover region with R<sub>F</sub> equal to 0 Ω and R<sub>S</sub> equal to 25 Ω.

In addition to the input bias current shift between pairs, each input pair has an input bias current offset that will contribute to the total offset in the following manner

$$\Delta V_{OS} = I_{B+} R_S \left( \frac{R_G + R_F}{R_G} \right) - I_{B-} R_F$$

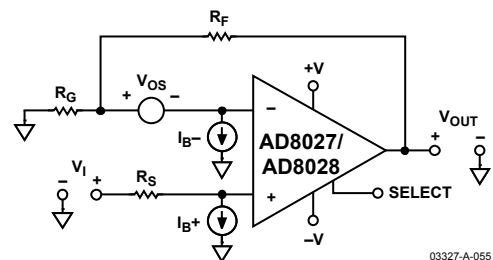


Figure 56. Op Amp DC Error Sources

# AD8027/AD8028

## WIDEBAND OPERATION

Voltage feedback amplifiers can use a wide range of resistor values to set their gain. Proper design of the application's feedback network requires consideration of the following issues:

- Poles formed by the amplifier's input capacitances with the resistances seen at the amplifier's input terminals
- Effects of mismatched source impedances
- Resistor value impact on the application's voltage noise
- Amplifier loading effects

The AD8027/AD8028 has an input capacitance of 2 pF. This input capacitance will form a pole with the amplifier's feedback network, destabilizing the loop. For this reason, it is generally desirable to keep the source resistances below 500 Ω, unless some capacitance is included in the feedback network. Likewise, keeping the source resistances low will also take advantage of the AD8027/AD8028's low input referred voltage noise of 4.3 nV/√Hz.

With a wide bandwidth of over 190 MHz, the AD8027/AD8028 has numerous applications and configurations. The AD8027/AD8028 shown in Figure 57 is configured as a noninverting amplifier. The inverting configuration is shown in Figure 58 and an easy selection table of gain, resistor values, bandwidth, slew rate, and noise performance is presented in Table 5.

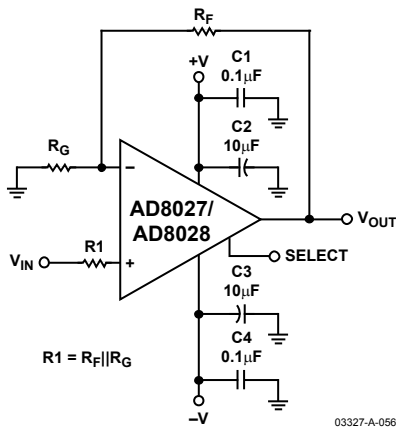


Figure 57. Wideband Noninverting Gain Configuration

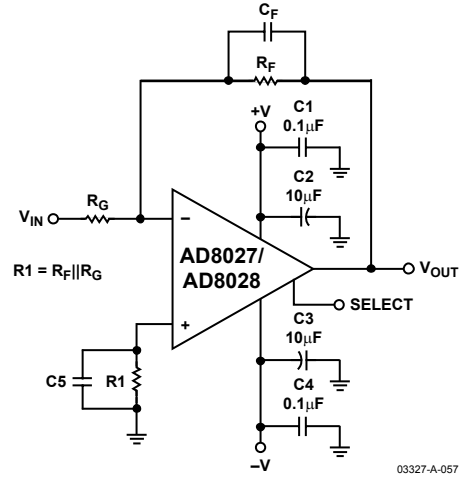


Figure 58. Wideband Inverting Gain Configuration

**Table 5. Component Values, Bandwidth, and Noise Performance ( $V_S = \pm 2.5\text{ V}$ )**

Noise Gain (Noninverting)	R <sub>SOURCE</sub> (Ω)	R <sub>F</sub> (Ω)	R <sub>G</sub> (Ω)	-3 dB SS BW (MHz)	Output Noise with Resistors (nV/√Hz)
1	50	0	N/A	190	4.4
2	50	499	499	95	10
10	50	499	54.9	13	45

## Circuit Considerations

### BALANCED INPUT IMPEDANCES

Balanced input impedances can help improve distortion performance. When the amplifier transitions from PNP pair to NPN pair operation, a change in both the magnitude and direction of the input bias current will occur. When multiplied times imbalanced input impedances, a change in offset will result. The key to minimizing this distortion is to keep the input impedances balanced on both inputs. Figure 59 shows the effect of the imbalance and degradation in distortion performance for a  $50\ \Omega$  source impedance, with and without a  $50\ \Omega$  balanced feedback path.

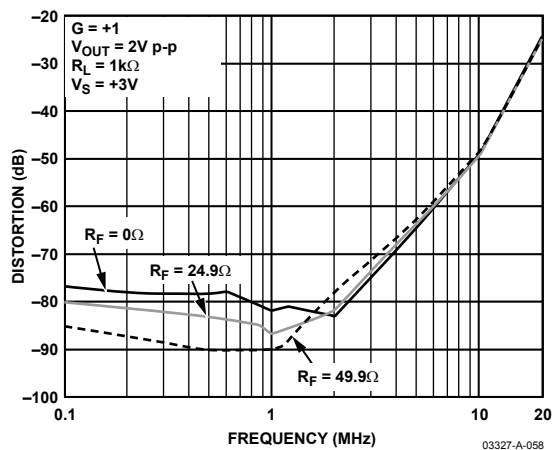


Figure 59. SFDR vs. Frequency and Various  $R_F$

### PCB LAYOUT

As with all high speed op amps, achieving optimum performance from the AD8027/AD8028 requires careful attention to PCB layout. Particular care must be exercised to minimize lead lengths of the bypass capacitors. Excess lead inductance can influence the frequency response and even cause high frequency oscillations. The use of a multilayer board, with an internal ground plane, will reduce ground noise and enable a tighter layout.

To achieve the shortest possible lead length at the inverting input, the feedback resistor,  $R_F$ , should be located beneath the board and span the distance from the output, Pin 6, to the input, Pin 2. The return node of the resistor  $R_G$  should be situated as closely as possible to the return node of the negative supply bypass capacitor connected to Pin 4.

On multilayer boards, all layers underneath the op amp should be cleared of metal to avoid creating parasitic capacitive elements. This is especially true at the summing junction (i.e., the  $-$ input). Extra capacitance at the summing junction can cause increased peaking in the frequency response and lower phase margin.

### GROUNDING

To minimize parasitic inductances and ground loops in high speed, densely populated boards, a ground plane layer is critical. Understanding where the current flows in a circuit is critical in the implementation of high speed circuit design. The length of the current path is directly proportional to the magnitude of the parasitic inductances and thus the high frequency impedance of the path. Fast current changes in an inductive ground return will create unwanted noise and ringing.

The length of the high frequency bypass capacitor pads and traces is critical. A parasitic inductance in the bypass grounding will work against the low impedance created by the bypass capacitor. Because load currents flow from supplies as well as ground, the load should be placed at the same physical location as the bypass capacitor ground. For large values of capacitors, which are intended to be effective at lower frequencies, the current return path length is less critical.

### POWER SUPPLY BYPASSING

Power supply pins are actually inputs and care must be taken to provide a clean, low noise dc voltage source to these inputs. The bypass capacitors have two functions:

1. Provide a low impedance path for unwanted frequencies from the supply inputs to ground, thereby reducing the effect of noise on the supply lines.
2. Provide sufficient localized charge storage, for fast switching conditions and minimizing the voltage drop at the supply pins and the output of the amplifier. This is usually accomplished with larger electrolytic capacitors.

Decoupling methods are designed to minimize the bypassing impedance at all frequencies. This can be accomplished with a combination of capacitors in parallel to ground.

Good quality ceramic chip capacitors should be used and always kept as close to the amplifier package as possible. A parallel combination of a  $0.01\ \mu\text{F}$  ceramic and a  $10\ \mu\text{F}$  electrolytic covers a wide range of rejection for unwanted noise. The  $10\ \mu\text{F}$  capacitor is less critical for high frequency bypassing, and in most cases, one per supply line is sufficient.

# AD8027/AD8028

## APPLICATIONS

### Using the AD8027/AD8028 SELECT Pin

The AD8027/AD8028 features a unique SELECT pin with two functions. The first is a power-down function that places the AD8027/AD8028 into low power consumption mode. In the power-down mode, the amplifier draws 450  $\mu\text{A}$  (typ) of supply current.

The second function, as mentioned in the Theory of Operation section, shifts the crossover point (where the NPN/PNP input differential pairs transition from one to the other) closer to either the positive supply rail or the negative supply rail. This selectable crossover point allows the user to minimize distortion based on the input signal and environment. The default state is 1.2 V from the positive power supply, with the SELECT pin left floating or in tri-state.

Table 6 shows the required voltages and modes of the SELECT pin.

**Table 6. SELECT Pin Mode Control**

Mode	SELECT Pin Voltage (V)		
	$V_S = \pm 5\text{ V}$	$V_S = +5\text{ V}$	$V_S = +3\text{ V}$
Disable	-5 to -4.2	0 to 0.8	0 to 0.8
Crossover Referenced -1.2 V to Positive Supply	-4.2 to -3.3	0.8 to 1.7	0.8 to 1.7
Crossover Referenced +1.2 V to Negative Supply	-3.3 to +5	1.7 to 5.0	1.7 to 3.0

When the input stage transitions from one input differential pair to the other, there is virtually no noticeable change in the output waveform.

The disable time of the AD8027/AD8028 amplifier is load dependent. Typical data is presented in Table 7. See Figure 52 and Figure 53 for the actual switching measurements.

**Table 7. DISABLE Switching Speeds**

	Supply Voltages ( $R_L = 1\text{ k}\Omega$ )		
	$\pm 5\text{ V}$	+5 V	+3 V
$t_{\text{ON}}$	45 ns	50 ns	50 ns
$t_{\text{OFF}}$	980 ns	1100 ns	1150 ns

### Driving a 16-Bit ADC

With the adjustable crossover distortion selection point and low noise, the AD8028 is an ideal amplifier for driving or buffering input signals into high resolution ADCs, such as the AD7677, a 16-Bit, 1 LSB INL, 1 MSPS differential ADC. Figure 60 shows the typical schematic for driving the ADC. The AD8028 driving the AD7677 offers performance close to non-rail-to-rail amplifiers and avoids the need for an additional supply,

other than the single 5 V supply already used by the ADC. In this application, the SELECT pins are biased to avoid the crossover region of the AD8028 for low distortion operation.

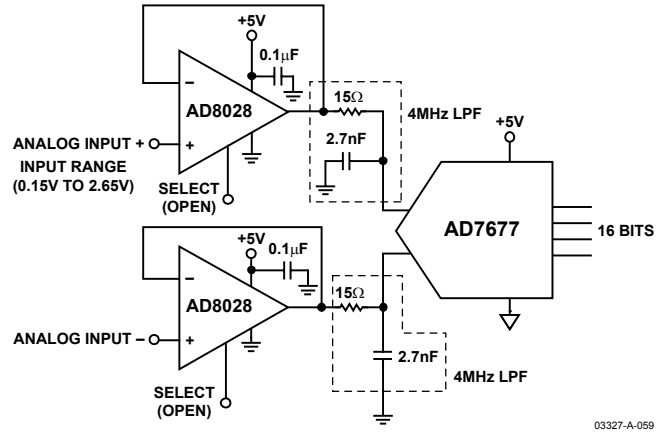


Figure 60. Unity Gain Differential Drive

As seen in Figure 61, the AD8028 and AD7677 combination offers excellent integral nonlinearity (INL). Summary test data for the schematic shown in Figure 60 is presented in Table 8.

**Table 8. ADC Driver Performance,**  
 $f_c = 100\text{ kHz}$ ,  $V_{\text{OUT}} = 4.7\text{ V p-p}$

Parameter	Measurement
Second Harmonic Distortion	-105dB
Third Harmonic Distortion	-102dB
THD	-102 dB
SFDR	105 dBc

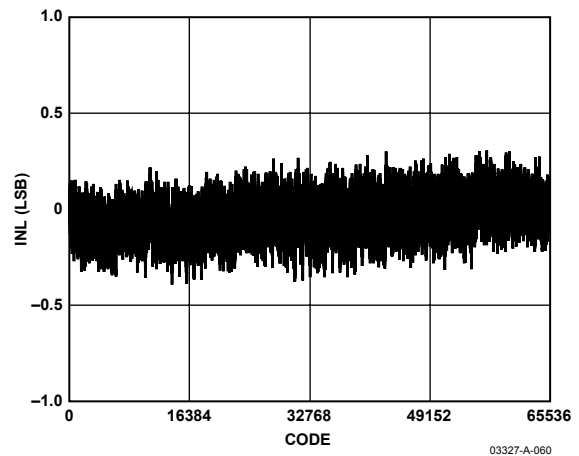


Figure 61. Integral Nonlinearity

## Band-Pass Filter

In communication systems, active filters are used extensively in signal processing. The AD8027/AD8028 is an excellent choice for active filter applications. In realizing this filter, it is important that the amplifier has a large signal bandwidth of at least 10× the center frequency,  $f_0$ . Otherwise, a phase shift can occur in the amplifier, causing instability and oscillations.

In the schematic shown in Figure 62, the AD8027/AD8028 is configured as a 1 MHz band-pass filter. The target specifications are  $f_0 = 1$  MHz and a -3 dB pass band of 500 kHz. Start the design by selecting the following:  $f_0$ ,  $Q$ ,  $C1$ , and  $R4$ . Then using the equations shown below, calculate the remaining variables.

The test data shown in Figure 63 indicates that this design yielded a filter response with a center frequency  $f_0 = 1$  MHz and a bandwidth of 450 kHz.

$$Q = \frac{f_0 \text{ (MHz)}}{\text{Pass Band (MHz)}}$$

$$k = 2\pi f_0 C1$$

$$C2 = 0.5C1$$

$$R1 = 2/k, R2 = 2/(3k), R3 = 4/k$$

$$H = 1/3(6.5 - 1/Q)$$

$$R5 = R4/(H - 1)$$

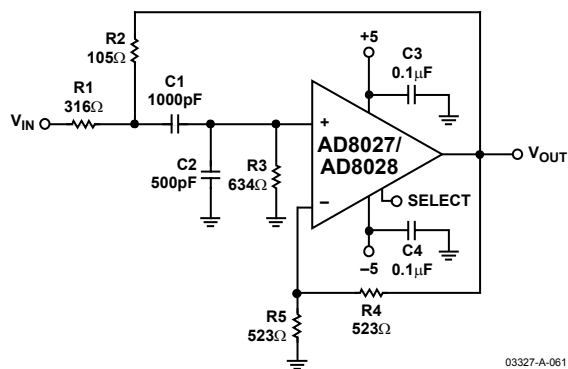


Figure 62. Band-Pass Filter Schematic

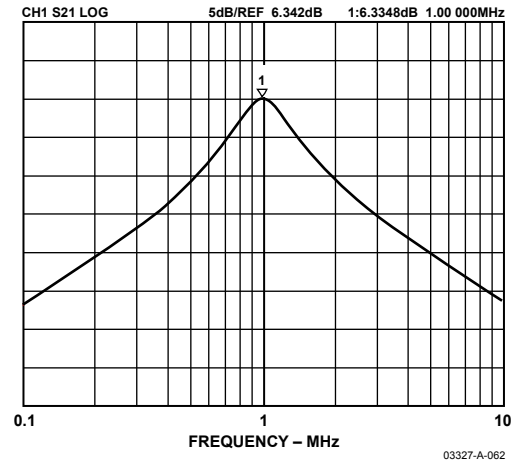
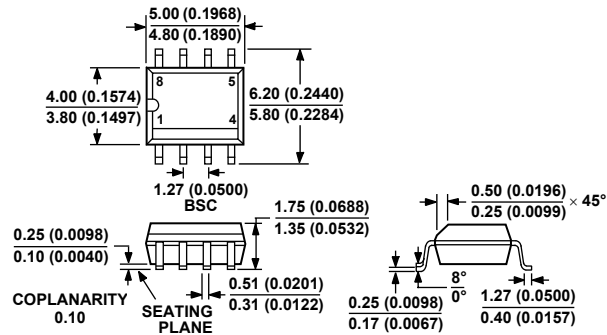


Figure 63. Band-Pass Filter Response

## Design Tools and Technical Support

Analog Devices is committed to simplifying the design process by providing technical support and online design tools. We offer technical support via free evaluation boards, sample ICs, interactive evaluation tools, data sheets, spice models, application notes, phone and email support, all of which are available at [www.analog.com](http://www.analog.com).

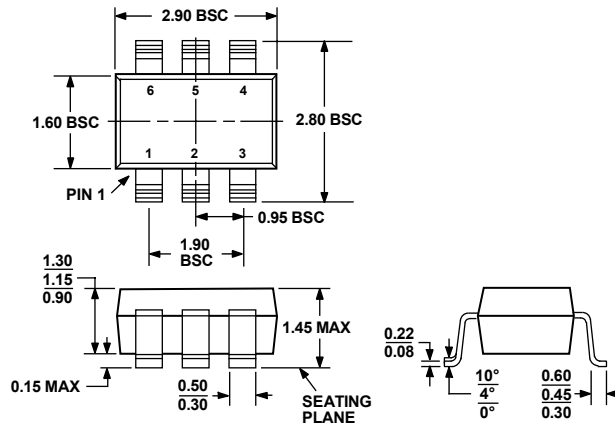
## OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MS-012AA  
CONTROLLING DIMENSIONS ARE IN MILLIMETERS; INCH DIMENSIONS (IN PARENTHESES) ARE ROUNDED-OFF MILLIMETER EQUIVALENTS FOR REFERENCE ONLY AND ARE NOT APPROPRIATE FOR USE IN DESIGN

Figure 64. 8-Lead Standard Small Outline Package, Narrow Body [SOIC] (R-8)

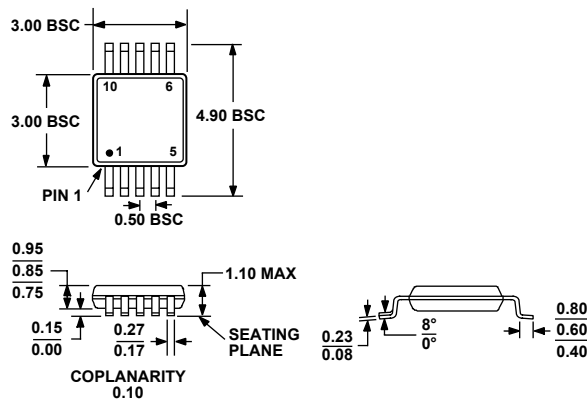
Dimensions shown in millimeters and (inches)



COMPLIANT TO JEDEC STANDARDS MO-178AB

Figure 65. 6-Lead Plastic Surface-Mount Package [SOT-23] (RT-6)

Dimensions shown in millimeters



COMPLIANT TO JEDEC STANDARDS MO-187BA

Figure 66. 10-Lead Mini Small Outline Package [MSOP] (RM-10)

Dimensions shown in millimeters

**ESD CAUTION**

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.

**Ordering Guide**

Model	Minimum Ordering Quantity	Temperature Range	Package Description	Package Outline	Branding
AD8027AR	1	-40°C to +125°C	8-Lead SOIC	R-8	
AD8027AR-REEL	2,500	-40°C to +125°C	8-Lead SOIC	R-8	
AD8027AR-REEL7	1,000	-40°C to +125°C	8-Lead SOIC	R-8	
AD8027ART-R2	250	-40°C to +125°C	6-Lead SOT-23	RT-6	H4B
AD8027ART-REEL	10,000	-40°C to +125°C	6-Lead SOT-23	RT-6	H4B
AD8027ART-REEL7	3,000	-40°C to +125°C	6-Lead SOT-23	RT-6	H4B
AD8028AR	1	-40°C to +125°C	8-Lead SOIC	R-8	
AD8028AR-REEL	2,500	-40°C to +125°C	8-Lead SOIC	R-8	
AD8028AR-REEL7	1,000	-40°C to +125°C	8-Lead SOIC	R-8	
AD8028ARM	1	-40°C to +125°C	10-Lead MSOP	RM-10	H5B
AD8028ARM-REEL	3,000	-40°C to +125°C	10-Lead MSOP	RM-10	H5B
AD8028ARM-REEL7	1,000	-40°C to +125°C	10-Lead MSOP	RM-10	H5B

**NOTES**